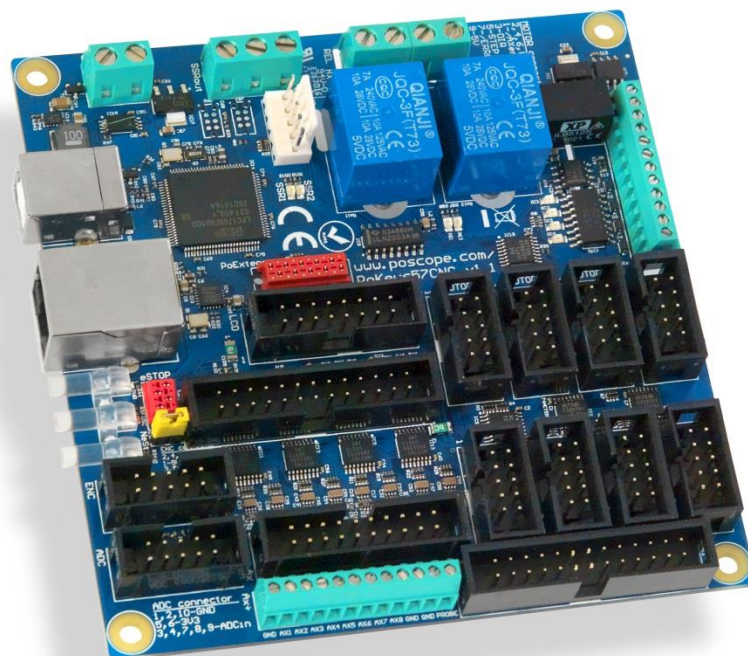




PoKeys57CNC User's manual

Version: 26/9/2016



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1. Introduction

PoKeys products line consists of simple, easy-to-use USB and network devices with the extended list of features making them powerful input/output devices. PoKeys57CNC features both USB and Ethernet connectivity, giving user an option to select the preferred connection for the application. The device is highly adjustable and as such requires no complex knowledge on device programming.

PoKeys57CNC is a blend between general purpose PoKeys device and motor controller. The device is targeted primarily for controlling up to 8 STEP/DIR signal driven motors (stepper motors, servo drives, etc.) in various applications with the addition of powerful PoKeys device features. Device contains dedicated connectors for connections with motor drivers, pendants, (HD44780-compatible) LCD module, etc. In addition, 5 analog inputs with 12-bit resolution are available. The device also features four galvanically-isolated open-collector outputs and 0 to 10 V analog output.

The device runs the PoIL core and is fully compatible with PoBlocks graphical programming software, bringing Programmable Logic Controller to a motor controller board. PoBlocks can be used to simply automate different peripherals and interchange data with other software applications that are using PoKeys57CNC device.

PoKeys USB products integrate support for virtual USB keyboard and USB joystick, which can be used to emulate a standard USB keyboard and joystick. Digital input pins can be mapped to virtual keyboard and joystick keys, while analog inputs can be mapped to virtual joystick axes. Configuration is simple by using our intuitive graphical PoKeys configuration application, where each function can also be tested.

A dedicated PoExtBus/PoNET connector can be used to extend the number of digital outputs for additional 80 outputs in the form of either relay outputs or open-collector outputs. It can also be used to connect various additional peripherals (e.g. PoKeysKBD48CNC pendant) and I²C sensors.

Third-party application developers that are adding the support for PoKeys devices, are encouraged to use the supplied communication DLL that can be simply used in the different .NET framework based applications and various other programming languages that provide support for ActiveX interface. There is even an open-source cross-platform C library available at <https://bitbucket.org/mbosnak/pokeyslib>.

To aid developers that are communicating with PoKeys devices on the low-level, the extensive documentation on device communication protocol can be downloaded free of charge from the product webpage.

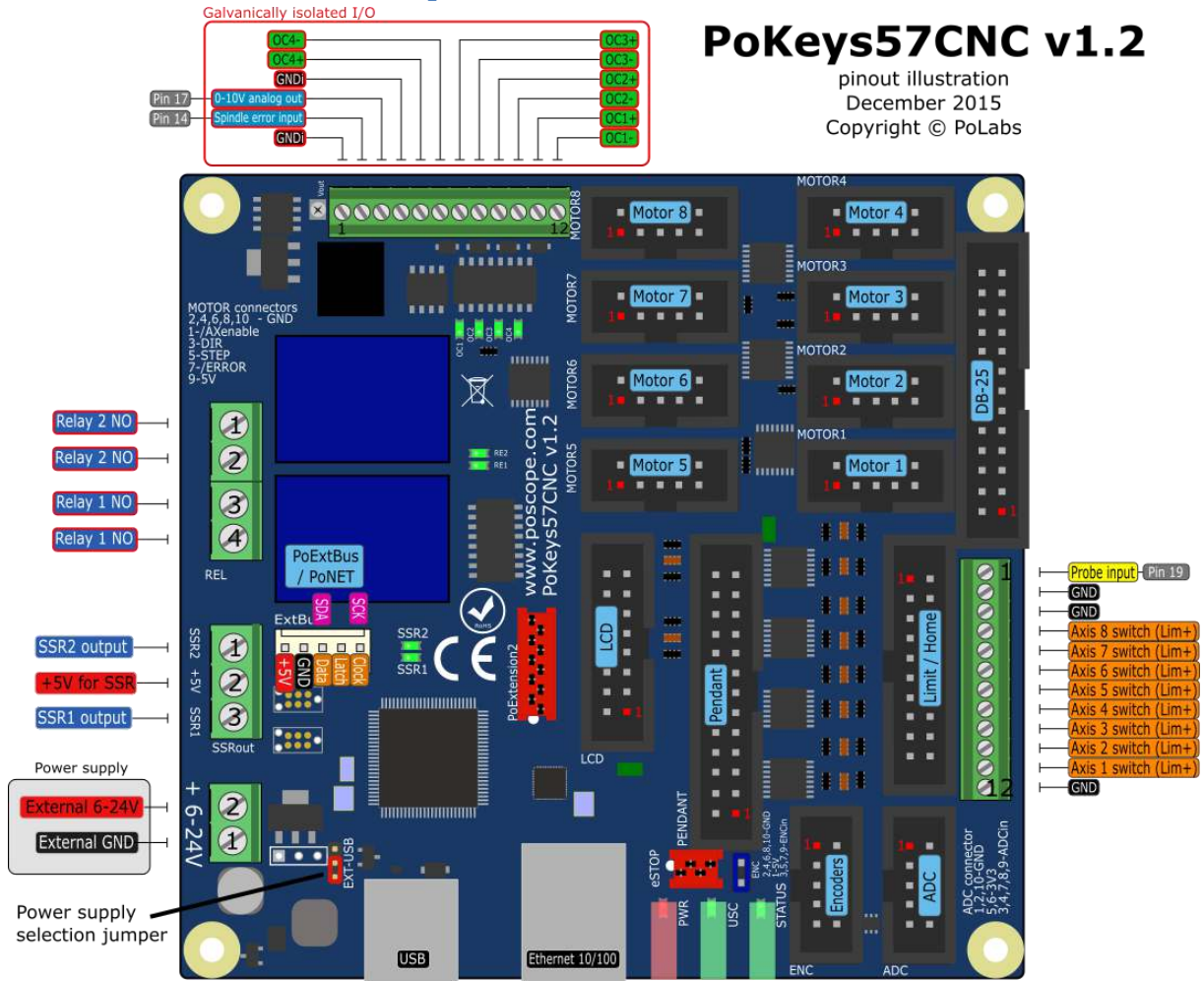
2. Features

- Compatible with USB 1.1/2.0 HID standard,
- standard English USB keyboard simulation (with triggering support for up/down keys),
- standard USB joystick simulation (6 axes, 32 buttons with triggering support),
- Ethernet 10/100 with DHCP client or fixed IP support,
- TCP or UDP connection with the device,
- Modbus TCP support (access to digital IO, analog inputs, encoder values, digital counters values, PWM outputs, LCD display, PoExtBus devices, matrix keyboard status),
- web interface with newly designed dashboard and I/O status display with multiple user accounts,
- 28 digital inputs or outputs (software configurable) with pull-up resistors and available as virtual USB keyboard keys. There are additional 4 dedicated digital outputs,
- 5 analog inputs (12-bit) with digital low-pass filtering (4 analog inputs also include analog low-pass filter with 1.9 kHz cut-off frequency),
- multiple encoder pair inputs with three additional dedicated high-speed encoder and one ultra high-speed encoder inputs,
- digital counters on specific digital input pins,
- high performance 8-axis 125 kHz pulse engine with dedicated motor connectors,
- up to 16x8 matrix keyboard with triggered keys/alternate function support,
- up to 4 high-speed fully configurable PWM outputs (25MHz PWM timer) - two of them with open-collector transistor outputs,
- dedicated connector for HD44780-based character LCD (up to 4x20 characters),
- dedicated connector for PoPendant1,
- PoExtBus support for adding up to 10 external shift registers (e.g. PoExtBusOC16, PoExtBusRE, etc.),
- PoNET devices support (48-key CNC keyboard),
- fail-safe support in case of communication interruption,
- support for up to 100 sensors, that can be connected to I²C bus, 1-wire bus or on the general purpose analog inputs,
- intuitive and user-friendly software,
- third-party support via communication DLL library and extensive protocol specification document that allows porting to other systems.

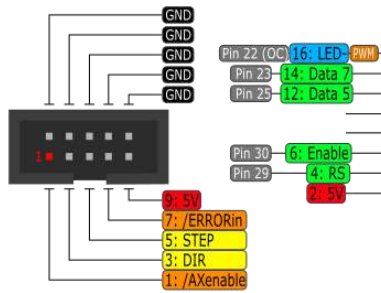
3. Device hardware description

PoKeys57CNC v1.2

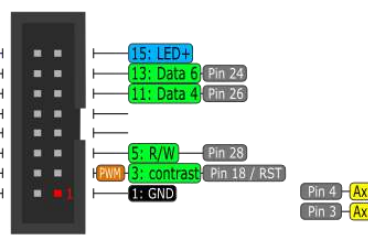
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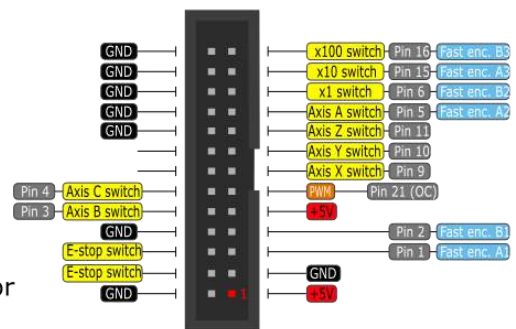
Motor connectors 1-8



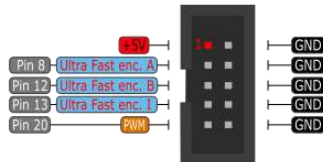
LCD connector



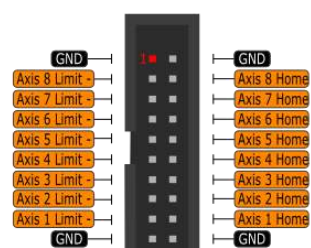
Pendant connector



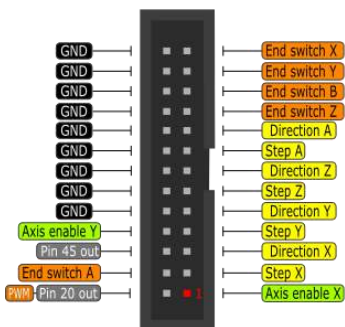
Encoders connector



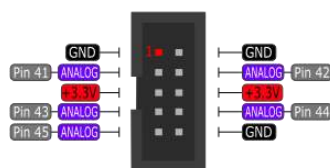
Axis switches connector



DB-25 connector

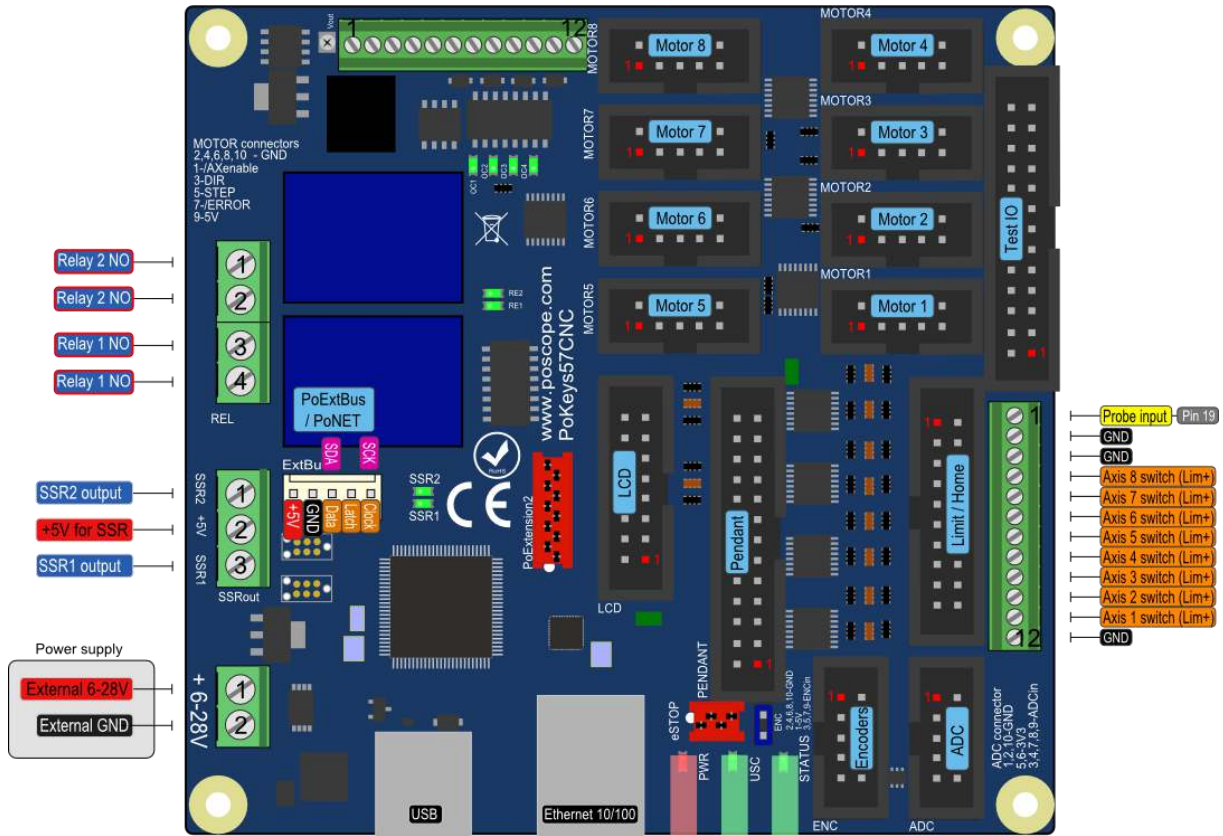


Analog inputs connector

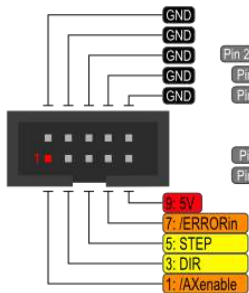


PoKeys57CNC

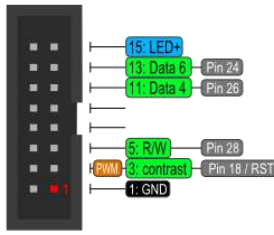
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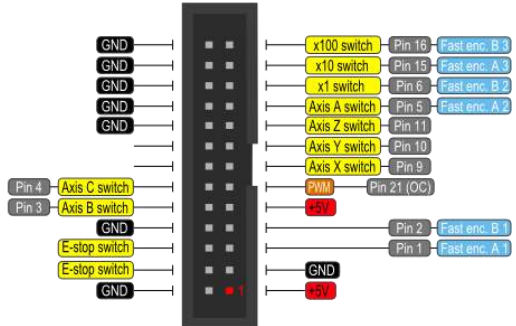
Motor connectors 1-8



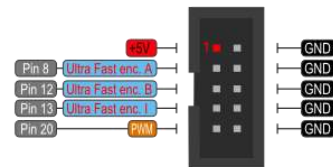
LCD connector



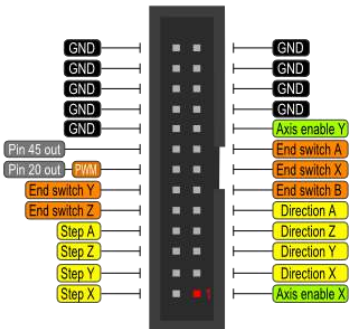
Pendant connector



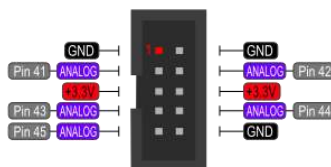
Encoders connector



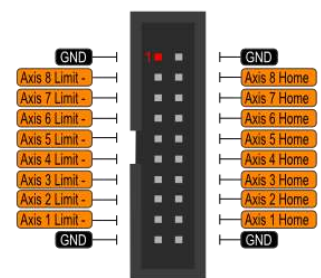
Test IO connector



Analog inputs connector



Axis switches connector



3.1. PoKeys57CNC connector pinout

Pin types

| Type code | Description |
|--------------|--|
| DI5P | 5 V digital input with input filtering |
| DI33P | 3,3 V digital input with input filtering |
| DO5 | 5 V digital output |
| DO5_D | 5 V digital output without series resistor |
| DIO33 | 3,3 V digital input or output without filtering |
| OCOC | Opto-coupled open-collector output |
| OCSSR | Open-collector outputs for SSR |
| REL | Relay output |
| AN33 | 3,3 V analog input without filtering |
| AN33F | 3,3 V analog input with 1,9 kHz low-pass filtering |

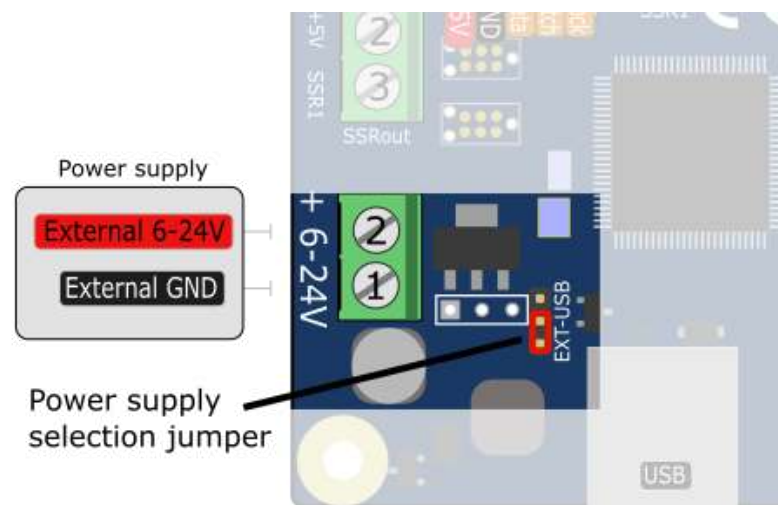
See chapter 3.2 *Pin types* for details on the listed pin types.

Power supply

| Pin | Type | Function |
|----------|--------------|---|
| 1 | Supply input | Positive power supply 6-26V (marked with +) |
| 2 | Supply input | Negative power supply (ground) |

PoKeys57CNC requires external 6-26V power supply to be connected to the board in order for the device to operate correctly (**device may not operate according to the specifications if the external power supply is not present**). The device uses switching power converter to scale down the input power supply to 5V. The power supply should be capable of providing at least 2.5W.

The PoKeys57CNC v1.2 features a jumper to select the power supply source. Move the jumper to the 'USB' position during testing the board without the external power supply connected. Otherwise, put the jumper to the 'EXT' position.



SSR (Solid State Relay) connector

| Pin | Type | Function |
|-----|-------|--|
| 1 | OCSSR | SSR2 output |
| 2 | +5V | +5V output (power supply to SSR relay) |
| 3 | OCSSR | SSR1 output |

The solid state relays should be connected between +5V output and corresponding SSR output pin.

Note: all +5V output pins on the board share the same power supply and the current is distributed to all loads.

Relays connector

| Pin | Type | Function |
|-----|------|----------------|
| 1 | REL | Relay 2 NO |
| 2 | REL | Relay 2 common |
| 3 | REL | Relay 1 NO |
| 4 | REL | Relay 1 common |

Galvanically isolated I/Os

This connector contains special I/O signals that are galvanically isolated from the rest of the board. Signals on pins 2 and 3 should only be referenced to GNDi points (available on pins 1 and 4).

| Pin | Type | Label | Function |
|-----|------|-------|--|
| 1 | GNDi | GNDi | Isolated ground connection (for use only with signals on this connector) |
| 2 | DI5P | SpEr | Spindle error input |
| 3 | - | 10V | 0-10V analog output |
| 4 | GNDi | GNDi | Isolated ground connection |
| 5 | OCOC | OC4+ | Open collector output 4 |
| 6 | OCOC | OC4- | |
| 7 | OCOC | OC3+ | Open collector output 3 |
| 8 | OCOC | OC3- | |
| 9 | OCOC | OC2+ | Open collector output 2 |
| 10 | OCOC | OC2- | |
| 11 | OCOC | OC1+ | Open collector output 1 |
| 12 | OCOC | OC1- | |

LCD connector

| Pin | Type | Label | Function |
|-----|-------|-------|---|
| 1 | GND | GND | Ground |
| 2 | +5V | +5V | +5V power supply for LCD |
| 3 | DIO33 | RST | LCD contrast voltage, also used as PoKeys pin 18 with PWM and reset pin (see Device recovery mode for more details) |
| 4 | DIO33 | RS | LCD RS signal, also used as PoKeys pin 29 ¹ |
| 5 | DIO33 | R/W | LCD R/W signal, also used as PoKeys pin 28 |
| 6 | DIO33 | E | LCD Enable signal, also used as PoKeys pin 30 ¹ |

¹ Digital counter functionality can be enabled for this pin

| | | | |
|----|-------|------|--|
| 7 | - | - | not connected |
| 8 | - | - | not connected |
| 9 | - | - | not connected |
| 10 | - | - | not connected |
| 11 | DIO33 | D4 | LCD D4 signal, also used as PoKeys pin 26 |
| 12 | DIO33 | D5 | LCD D5 signal, also used as PoKeys pin 25 |
| 13 | DIO33 | D6 | LCD D6 signal, also used as PoKeys pin 24 |
| 14 | DIO33 | D7 | LCD D7 signal, also used as PoKeys pin 23 |
| 15 | +5V | LED+ | +5 V power supply for LCD backlight with 4,7 Ω resistor in series |
| 16 | OC | LED- | Open-collector output (max. 100 mA), also used as PoKeys pin 22 with PWM |

Pendant connector

| Pin | Type | Label | Function |
|-----|-------|-----------|--|
| 1 | +5V | +5V | +5 V power supply to pendant (used for encoder/MPG power) |
| 2 | GND | GND | Ground |
| 3 | GND | GND | Ground |
| 4 | DI33P | E-stop | E-stop signal input, also used as PoKeys pin 52 (connect E-stop switch between pins 4 and 6) - see notes below |
| 5 | DIO33 | FastEncA | Encoder channel A, also used as PoKeys pin 1 ² |
| 6 | GND-E | E-Stop | E-stop switch GND - see notes below |
| 7 | DIO33 | FastEncB | Encoder channel B, also used as PoKeys pin 2 ² |
| 8 | GND | GND | Ground |
| 9 | +5V | LED+ | +5 V power supply for pendant LED |
| 10 | DI33P | Ax-B | Axis B selection signal, also used as PoKeys pin 3 ² |
| 11 | OC | LED- | Open-collector output (max. 100 mA), also used as PoKeys pin 21 with PWM |
| 12 | DI33P | Ax-C | Axis C selection signal, also used as PoKeys pin 4 ² |
| 13 | DI33P | Ax-X | Axis X selection signal, also used as PoKeys pin 9 ² |
| 14 | - | - | not connected |
| 15 | DI33P | Ax-Y | Axis Y selection signal, also used as PoKeys pin 10 ² |
| 16 | - | - | not connected |
| 17 | DI33P | Ax-Z | Axis Z selection signal, also used as PoKeys pin 11 ² |
| 18 | GND | GND | Ground |
| 19 | DI33P | Ax-A | Axis A selection signal, also used as PoKeys pin 5 ² |
| 20 | GND | GND | Ground |
| 21 | DI33P | Step x1 | Step x1 selection signal, also used as PoKeys pin 6 ² |
| 22 | GND | GND | Ground |
| 23 | DI33P | Step x10 | Step x10 selection signal, also used as PoKeys pin 15 ² |
| 24 | GND | GND | Ground |
| 25 | DI33P | Step x100 | Step x100 selection signal, also used as PoKeys pin 16 ² |
| 26 | GND | GND | Ground |

Note: E-stop switch can be connected either to dedicated E-stop connector (red 4-pin connector) or to pendant connector (a combination of both is also allowed since both are wired in series).

² Digital counter functionality can be enabled for this pin

- a) E-stop switch is connected to dedicated 4-pin E-stop connector between pins 2 and 3. Jumper 'NeST' must be removed and inserted into the pendant connector between pins 4 and 6
- b) E-stop switch is connected to pendant connector (between pins 4 and 6). Jumper 'NeST' must be present
- c) Two E-stop switches are connected - one to dedicated 4-pin E-stop connector (between pins 2 and 3) and one to pendant connector (between pins 4 and 6).

Encoders connector

| Pin | Type | Label | Function |
|-----|-------|-------|---|
| 1 | +5V | +5V | Axis enable signal (inverted) |
| 2 | GND | GND | Ground |
| 3 | DIO33 | uFEA | Ultra-fast encoder A-channel signal input, also used as PoKeys pin 8 |
| 4 | GND | GND | Ground |
| 5 | DIO33 | uFEB | Ultra-fast encoder B-channel signal input, also used as PoKeys pin 12 |
| 6 | GND | GND | Ground |
| 7 | DIO33 | uFEI | Ultra-fast encoder index signal input, also used as PoKeys pin 13 |
| 8 | GND | GND | Ground |
| 9 | DIO33 | PK20 | PoKeys pin 20 with PWM ³ |
| 10 | GND | GND | Ground |

ADC connector

| Pin | Type | Label | Function |
|-----|------------|-------|---------------|
| 1 | GND | GND | Ground |
| 2 | GND | GND | Ground |
| 3 | AN33F | PK41 | PoKeys pin 41 |
| 4 | AN33F | PK42 | PoKeys pin 42 |
| 5 | +3,3V | +3,3V | |
| 6 | +3,3V | +3,3V | |
| 7 | AN33F | PK43 | PoKeys pin 43 |
| 8 | AN33F | PK44 | PoKeys pin 44 |
| 9 | AN33/DIO33 | PK45 | PoKeys pin 45 |
| 10 | GND | GND | Ground |

³ Digital counter functionality can be enabled for this pin

Motor connectors 1-8

| Pin | Type | Label | Function |
|-----|------|----------|--|
| 1 | DO5 | /AXEn | Axis enable signal (inverted) |
| 2 | GND | GND | Ground |
| 3 | DO5 | DIR | Direction signal |
| 4 | GND | GND | Ground |
| 5 | DO5 | STEP | Step signal |
| 6 | GND | GND | Ground |
| 7 | DI5P | /ERRORin | Error input signal (from stepper driver to PoKeys) |
| 8 | GND | GND | Ground |
| 9 | +5V | 5V | +5V output to stepper driver |
| 10 | GND | GND | Ground |

Axis switches connector

| Pin | Type | Label | Function |
|-----|------|-------|--------------------------|
| 1 | GND | GND | Ground |
| 2 | GND | GND | Ground |
| 3 | DI5P | AX8- | Axis 8 limit- switch |
| 4 | DI5P | AX8 H | Axis 8 home switch |
| 5 | DI5P | AX7- | Axis 7 limit- switch |
| 6 | DI5P | AX7 H | Axis 7 home switch |
| 7 | DI5P | AX6- | Axis 6 (C) limit- switch |
| 8 | DI5P | AX6 H | Axis 6 (C) home switch |
| 9 | DI5P | AX5- | Axis 5 (B) limit- switch |
| 10 | DI5P | AX5 H | Axis 5 (B) home switch |
| 11 | DI5P | AX4- | Axis 4 (A) limit- switch |
| 12 | DI5P | AX4 H | Axis 4 (A) home switch |
| 13 | DI5P | AX3- | Axis 3 (Z) limit- switch |
| 14 | DI5P | AX3 H | Axis 3 (Z) home switch |
| 15 | DI5P | AX2- | Axis 2 (Y) limit- switch |
| 16 | DI5P | AX2 H | Axis 2 (Y) home switch |
| 17 | DI5P | AX1- | Axis 1 (X) limit- switch |
| 18 | DI5P | AX1 H | Axis 1 (X) home switch |
| 19 | GND | GND | Ground |
| 20 | GND | GND | Ground |

Additional limit switches

| Pin | Type | Label | Function |
|-----|------|-------|--------------------------|
| 1 | GND | GND | Ground |
| 2 | DI5P | AX1+ | Axis 1 (X) limit+ switch |
| 3 | DI5P | AX2+- | Axis 2 (Y) limit+ switch |
| 4 | DI5P | AX3+ | Axis 3 (Z) limit+ switch |
| 5 | DI5P | AX4+ | Axis 4 (A) limit+ switch |
| 6 | DI5P | AX5+ | Axis 5 (B) limit+ switch |
| 7 | DI5P | AX6+ | Axis 6 (C) limit+ switch |
| 8 | DI5P | AX7+ | Axis 7 limit+ switch |

| | | | |
|----|------|-------|---|
| 9 | DI5P | AX8+ | Axis 8 limit+ switch |
| 10 | GND | GND | Ground |
| 11 | GND | GND | Ground |
| 12 | DI5P | Probe | Probe input <i>On PoKeys57CNC v1.0, v1.1 and v1.2 external pull-up resistor must be used</i> |

DB-25 (LPT-port) IO connector

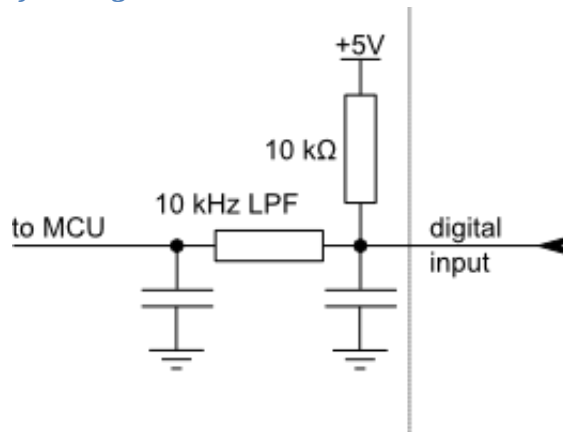
Warning: on PoKeys57CNC v1.1 the pinout is not compatible with the LPT-based stepper drivers since the physical pin numbering sequence in PoKeys57CNC v1.1 differs from that of a real DB-25 connector. Check the pinout diagrams above.

The connector on the PoKeys57CNC v1.2 is compatible with the LPT-based stepper drivers.

| Pin | Type | Label | Function |
|-----|-------|--------|-------------------------------------|
| 1 | DO5 | /AXEn1 | Axis 1 (X) enable signal (inverted) |
| 2 | DO5 | STEP1 | Step signal for axis 1 (X) |
| 3 | DO5 | DIR1 | Direction signal for axis 1 (X) |
| 4 | DO5 | STEP2 | Step signal for axis 2 (Y) |
| 5 | DO5 | DIR2 | Direction signal for axis 2 (Y) |
| 6 | DO5 | STEP3 | Step signal for axis 3 (Z) |
| 7 | DO5 | DIR3 | Direction signal for axis 3 (Z) |
| 8 | DO5 | STEP4 | Step signal for axis 4 (A) |
| 9 | DO5 | DIR4 | Direction signal for axis 4 (A) |
| 10 | DI5P | AX3+ | Axis 3 (Z) limit+ switch |
| 11 | DI5P | AX5+ | Axis 5 (B) limit+ switch |
| 12 | DI5P | AX2+ | Axis 2 (Y) limit+ switch |
| 13 | DI5P | AX1+ | Axis 1 (X) limit+ switch |
| 14 | DO5_D | PK20 | PoKeys pin 20 (output only) |
| 15 | DI5P | AX4+ | Axis 4 (A) limit+ switch |
| 16 | DO5_D | PK45 | PoKeys pin 45 (output only) |
| 17 | DO5 | /AXEn2 | Axis 2 (Y) enable signal (inverted) |
| 18 | GND | GND | Ground |
| 19 | GND | GND | Ground |
| 20 | GND | GND | Ground |
| 21 | GND | GND | Ground |
| 22 | GND | GND | Ground |
| 23 | GND | GND | Ground |
| 24 | GND | GND | Ground |
| 25 | GND | GND | Ground |
| 26 | GND | GND | Ground |

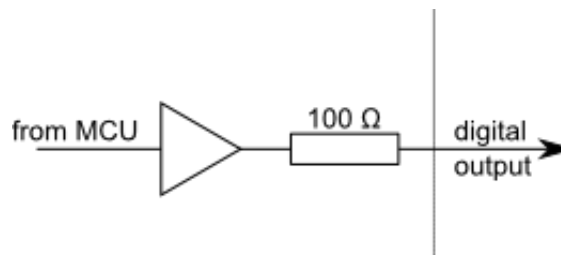
3.2. Pin types and specifications

Type DI5P: Digital input with filtering



| Symbol | Parameter | Min | Max | Unit |
|-----------------|-------------------------------------|-----|-----|------|
| $V_{DI5P,MAX}$ | maximum voltage applied to DI5P pin | - | 5,5 | V |
| $V_{DI5P,LOW}$ | applied voltage for LOW state | - | 0,2 | V |
| $V_{DI5P,HIGH}$ | applied voltage for HIGH state | 1,6 | - | V |

Type DO5: 5 V digital output



| Symbol | Parameter | Min | Max | Unit |
|----------------|---|-----|-----|------|
| $I_{DO5,MAX}$ | maximum current supplied by DO5 pin | - | 8 | mA |
| $V_{DO5,LOW}$ | voltage of LOW state (no current) | - | 0,1 | V |
| $V_{DO5,HIGH}$ | voltage of HIGH state (no current) | 4,9 | - | V |
| $R_{DO5,HIGH}$ | internal resistance of the digital output | 100 | TBD | Ohm |

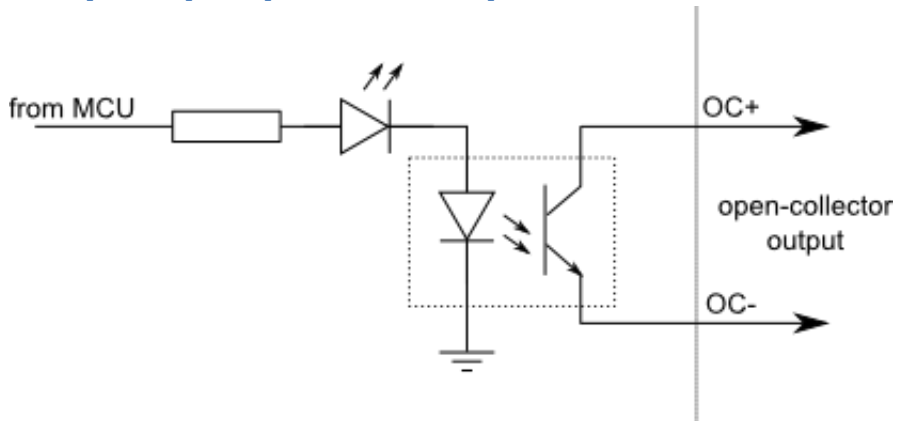
Type DO5_D: 5 V digital output without resistor

| Symbol | Parameter | Min | Max | Unit |
|-------------------|-------------------------------------|-----|-----|------|
| $I_{DO5_D,MAX}$ | maximum current supplied by DO5 pin | - | 50 | mA |
| $V_{DO5_D,LOW}$ | voltage of LOW state (no current) | - | 0,1 | V |
| $V_{DO5_D,HIGH}$ | voltage of HIGH state (no current) | 4,9 | - | V |

Type DI033: 3,3 V digital input or output

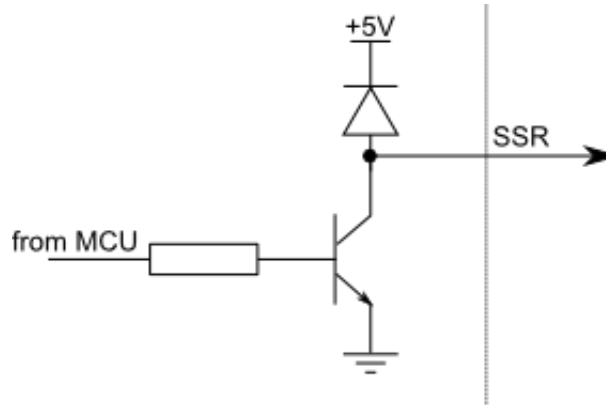
Digital pin directly connected to MCU.

| Symbol | Parameter | Min | Max | Unit |
|-----------------------------------|--------------------------------------|-----------------------|------|---------|
| I_{pu} | pull-up current | 0 ($V_i \geq 3.3V$) | -100 | μA |
| Pin used as digital output | | | | |
| $I_{DO33,MAX}$ | maximum current supplied by DO33 pin | - | 4 | mA |
| $V_{DO33,LOW}$ | voltage of LOW state (no current) | 0 | - | V |
| $V_{DO33,HIGH}$ | voltage of HIGH state (no current) | - | 3,3 | V |
| Pin used as digital input | | | | |
| $V_{DI5,MAX}$ | maximum voltage applied to DI5 pin | - | 5,0 | V |
| $V_{DI5,LOW}$ | applied voltage for LOW state | - | 0,8 | V |
| $V_{DI5,HIGH}$ | applied voltage for HIGH state | 2,0 | - | V |

Type OCOC: opto-coupled open-collector output

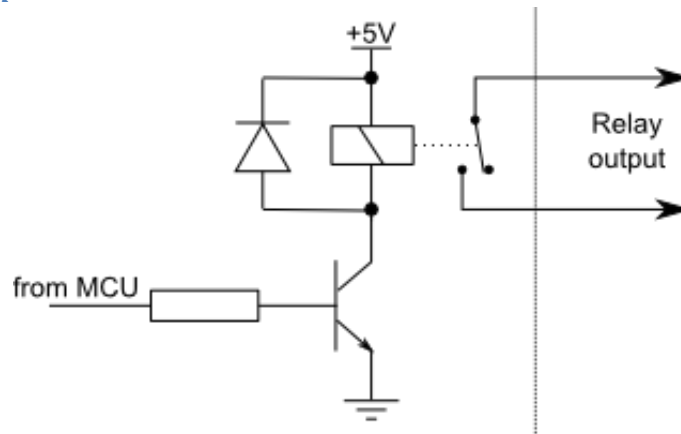
| Symbol | Parameter | Min | Max | Unit |
|-----------------|--|-----|------|-----------|
| $I_{OCOC,MAX}$ | maximum output current | - | 50 | mA |
| $V_{OCOC,DIFF}$ | maximum voltage applied between OC+ and OC- | - | 50 | V |
| $V_{OCOC,ISO}$ | isolation voltage (AC for 1min, R.H. 40-60%) | - | 3000 | V_{RMS} |

Type OCSSR: open-collector output for SSR (Solid State Relay)



| Symbol | Parameter | Min | Max | Unit |
|-----------------|--------------------------------------|-----|-----|------|
| $I_{OCSSR,MAX}$ | maximum current sunk by OCSSR pin | - | 500 | mA |
| $U_{OCSSR,MAX}$ | maximum voltage applied to OCSSR pin | - | 5 | V |

Type REL: relay output



| Symbol | Parameter | Min | Max | Unit |
|------------------|--------------------------------------|-----|-----|------|
| $I_{REL,28VDC}$ | maximum current switching at 28 VDC | - | 10 | A |
| $I_{REL,125VAC}$ | maximum current switching at 125 VAC | - | 10 | A |
| $I_{REL,240VAC}$ | maximum current switching at 240 VAC | - | 7 | A |

Type AN33: 3.3 V analog input

| Symbol | Parameter | Min | Max | Unit |
|----------|--|------|-----|------|
| V_{IA} | analog input voltage on ADC related pins | -0.5 | 3.3 | V |

Type AN33F: 3.3 V analog input with low-pass filter

| Symbol | Parameter | Min | Max | Unit |
|----------|---|------|-----|------|
| V_{IA} | analog input voltage on ADC related pins | -0.5 | 3.3 | V |
| f_{LP} | cut-off frequency of the analog low-pass filter | 1.6 | 2.2 | kHz |

3.3. Status LEDs

- TBD

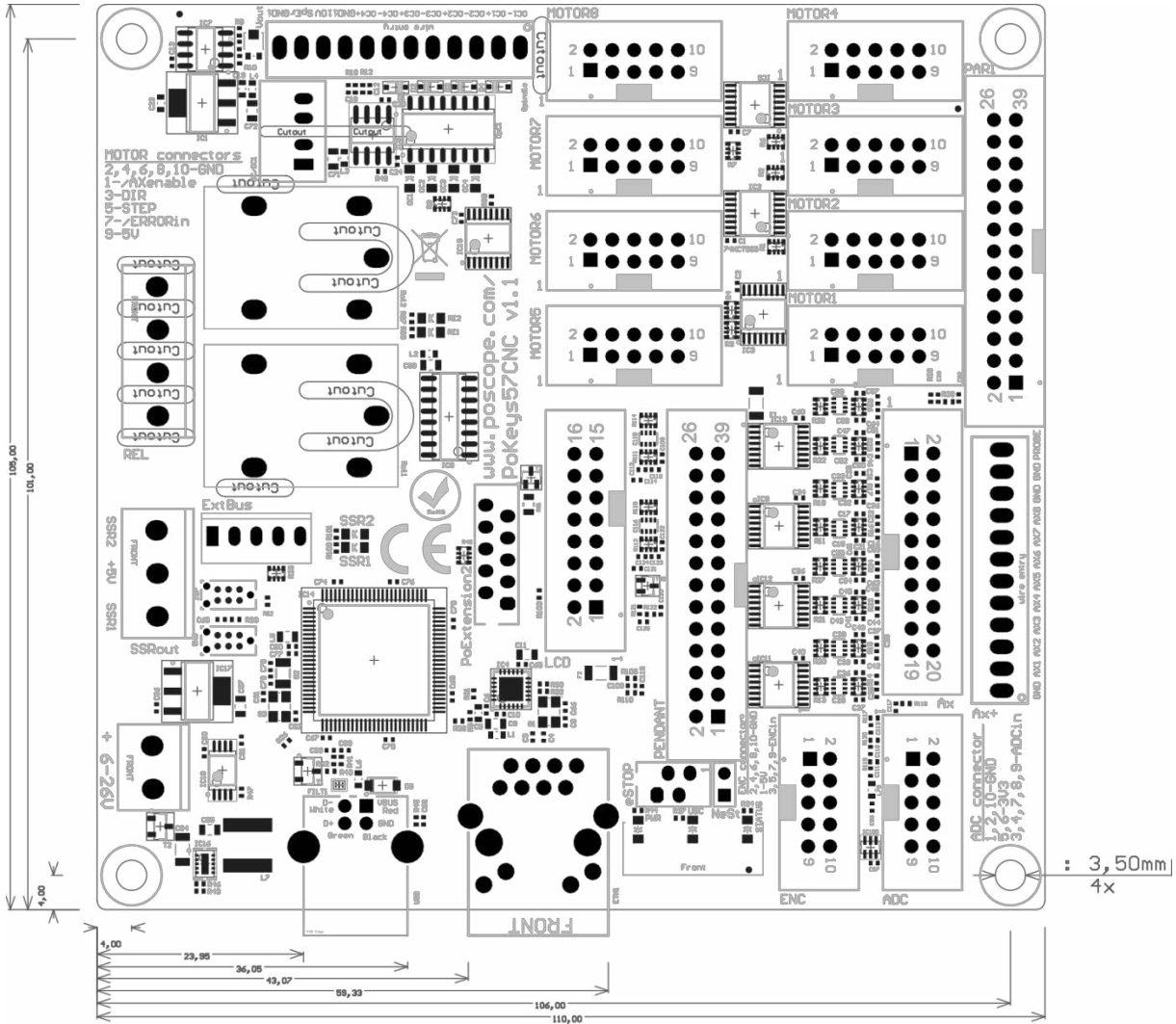
4. Requirements

- 6-26 V power supply with 2.5 W or more,
- one available USB 1.1 or USB 2.0 port,
- Ethernet connection between host computer and PoKeys57CNC device,
- USB HID device driver enabled operating system (Windows 98 SE/ME/2000/XP/Vista, Linux, Mac OS),
- included software requires Windows XP/Vista/7/8/8.1 with .NET framework 3.5 installed.

5. Technical specifications

5.1. PoKeys57CNC dimensions

Measurements are in mm.



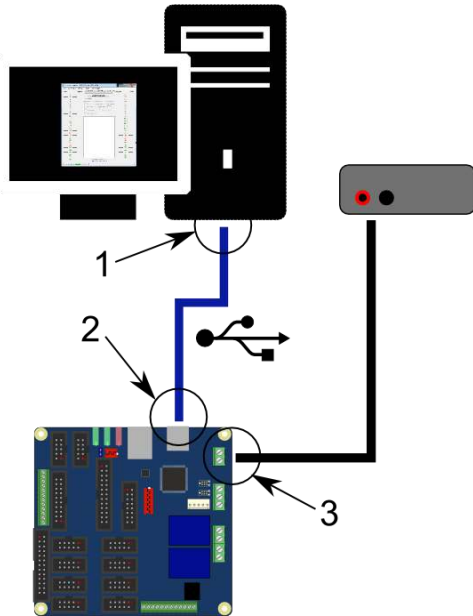
5.2. Environment specifications

| Parameter | Min | Typ | Max | Unit |
|-----------------------|-----|-----|---------------------|------|
| Power supply range | 6 | - | 26 | V |
| Operating temperature | 0 | - | 60 | °C |
| Storage temperature | -40 | - | 85 | °C |
| Humidity | 5 | - | 95 (non-condensing) | % RH |

6. Installation

6.1. Using USB

PoKeys57CNC is a USB 1.1/2.0 compliant device.



Step 1: Locate a free USB 2.0 port on your computer (1) and PoKeys57CNC board (2) and connect them with a standard USB cable.

Step 2: Connect the PoKeys57CNC board to an appropriate power supply (3).

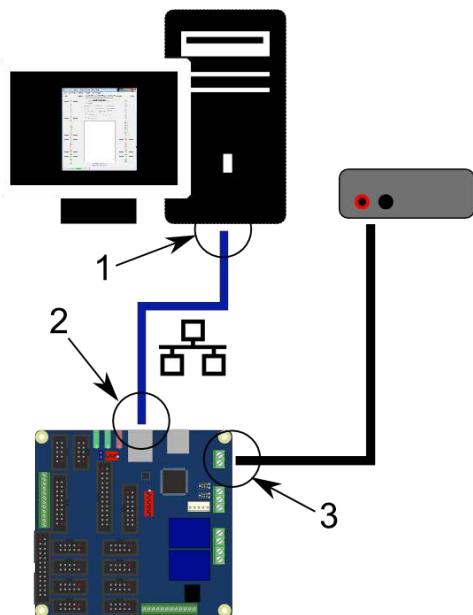
Step 3: Install PoKeys software

Step 4: Open PoKeys application, connect to your PoKeys57CNC device and enable Fast USB interface (go to Settings > Enable Fast USB interface).

Step 5: Remove the USB cable from PoKeys57CNC device and insert it again. The computer will find a new device and search for drivers. See FAQ section of the manual if driver installation fails.

6.2. Using Ethernet - direct connection between PoKeys57CNC and computer

Network firewalls must allow all traffic on TCP/UDP port 20055 between PoKeys57CNC device and PoKeys-related software running on a computer.



Step 1: Locate ethernet ports on your computer (1) and PoKeys57CNC board (2) and connect them with RJ-45 cable (standard network cable).

Step 2: Connect the PoKeys57CNC board to an appropriate power supply (3).

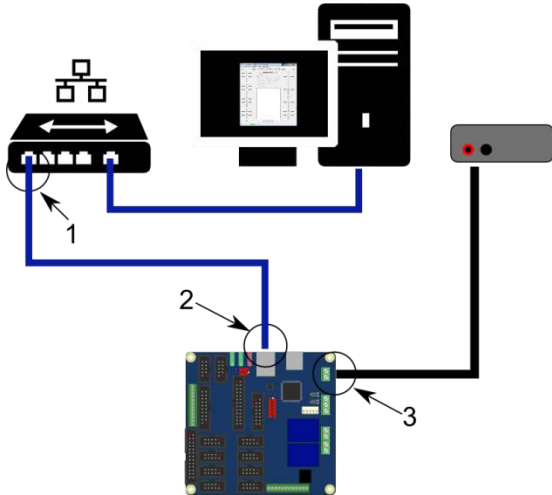
Step 3: Configure your computer's network card with a static IP address in the 192.168.x.x range

Step 4: Install PoKeys software

Step 5: Start PoKeys software, select the PoKeys57CNC device in the list and click on 'Configure' button. Select the unique IP address for the PoKeys57CNC device in the same range as the computer's network card

6.3. Using Ethernet - PoKeys57CNC connected to a network with DHCP server

Network firewalls must allow all traffic on TCP/UDP port 20055 between PoKeys57CNC device and PoKeys-related software running on a computer.



Step 1: Locate ethernet ports on your router (1) and PoKeys57CNC board (2) and connect them with RJ-45 cable (standard network cable).

Step 2: Connect the PoKeys57CNC board to an appropriate power supply (3).

Step 3: Install PoKeys software

6.1. Using USB and Ethernet

PoKeys57CNC device can also be connected to computer by using both the USB and Ethernet connection. In this case, applications will detect two instances of PoKeys57CNC devices and USB connection will be selected by default by third-party applications.

Follow the above instructions on connecting the PoKeys57CNC device over Ethernet and USB.

6.2. Motor drivers and peripherals installation

Connect motor drivers to dedicated 10-pin axis motor connectors, marked as MOTOR1, MOTOR2 ... MOTOR8.

Connect pendant to the dedicated pendant connector.

7. PoKeys configuration options

7.1. Digital inputs and outputs

Unlike generic PoKeys devices, PoKeys57CNC doesn't have generic pin headers with fully customizable pin functions. Certain pins of the dedicated connectors on PoKeys57CNC can be reused for other purposes if not used by the specific peripheral device. See the connector pinout diagram to discover which pins can be reused as digital inputs or digital outputs. Pin numbers were assigned according to the available functions of each pin in order to keep the device back-compatible with 3rd party software.

Although primarily targetted for CNC applications, PoKeys57CNC shares the same virtual USB keyboard and joystick capability of PoKeys USB series of devices. Digital pins can be mapped to virtual keyboard keys or virtual joystick buttons. On activation, PoKeys device sends a USB message with the key code and modifier associated with this pin. Moreover, PoKeys57CNC device can also simulate a series of key presses, what is called a macro sequence. Up to 64 different macro sequences can be setup with the combined total length of 3584 characters with each macro sequence shorter than 128 keys. All macros can be labelled with a 7-character name.

An extension to the USB keyboard mapping described above, PoKeys supports also triggered mapping of inputs to USB keyboard keys. In triggered mapping mode, only pin state transitions (low-to-high or high-to-low trigger a USB key press) with different key combinations for each transition.

Type-matic like repeat and delay is an additional extension to the triggered key mapping. Instead of relying on the user's system to trigger key repeat events, PoKeys can be configured to simulate repeated key presses at the predefined rate (period between two key presses is adjustable in 5 ms cycles – 0.78 to 200 repeats possible⁴) after a predefined delay (adjustable in steps of 5 ms – 0 to 1275 ms possible).

PoKeys configuration software usage

There is graphical representation for configuration of each PoKeys device's pin on left and right side of main window. To change pin function, click on pin name and change its function in central 'Pin settings' frame.



Figure 1: PoKeys configuration window

⁴ The maximum repeat rate depends on the user's system

There are 6 main pin functions possible: inactive, digital input, triggered digital input, digital output, analog input, depending on the capabilities of each pin.

Inactive

Any pin (except those fixly mapped to an activated peripheral) can be set as inactive. Inactive pin is put in high-Z state with internal pull-up resistors enabled.

Digital input

Any free pin can be configured as digital input by selecting 'Digital input' option box. If the pin polarity is wished to be inverted, check the 'Invert pin' box.

There are several additional possibilities for digital input pin functions.

Direct key mapping - only if connected over USB

Digital input set up for direct key mapping acts like a keyboard key. When there is a high state on pin (on low state when using inverted option), PoKeys device sends a key associated with this pin. Select a keyboard key from drop-down box and check appropriate key modifiers (Shift, Ctrl, ...).

Triggered digital input

Triggered digital input function is activated by selecting 'Triggered input' option box. This pin mode enables user to select a key that is pressed only when a transition in a signal occurs. Different keys can be selected for 'LOW-to-HIGH' or 'Key up' event and for 'HIGH-to-LOW' or 'Key down' event. Selecting the keys is similar to Direct key mapping described above.

Digital output

Most of the available pins (check the pin capabilities in device pinout section of this manual) can be configured as digital output by selecting 'Digital output' option box. If the polarity of the pin is wished to be inverted, check the 'Invert pin' box. On startup, all pins (although optionally configured as digital output) are by default initialized in high-Z state (behaving like inputs). To use the outputs, SetPinData should be called before attempting to set the output state. However, there is an option to disable this behaviour - use the 'Settings > Initialize outputs on startup' option to either enable or disable output activation on PoKeys startup.

View status of digital inputs and outputs

Go to 'Peripherals > Digital inputs and outputs...' to display the status dialog as shown below.

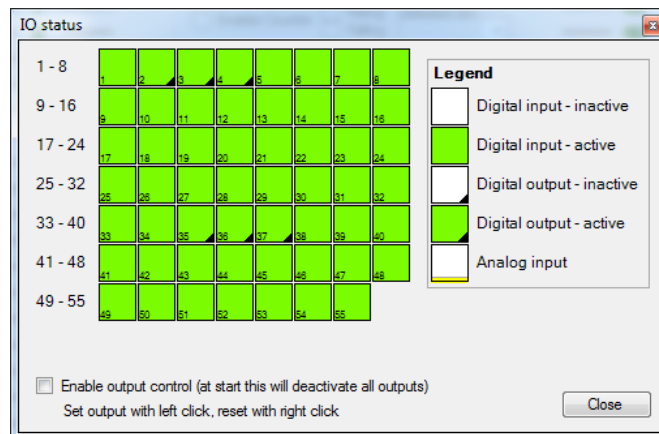


Figure 2: Input and output status dialog

There are 55 pins represented as colored squares in the dialog, organized in the rows of 8 pins. Each square contains a pin index number in the lower left corner, while the lower right corner is used to indicate a digital output (small black triangle is displayed on pins, configured as digital outputs). The color of the square resembles the current state of the pin – green for the activated (HIGH state) and white for the unactivated (LOW state).

To change the digital output state, first enable 'Enable output control' option, then either left or right click with mouse on the square representing the digital output to activate or deactivate this output.

7.2. Digital counters

Selected pins of the PoKeys device can be setup to count the number of signal transitions on those pins. Pin digital counter can be setup to be incremented/decremented on rising, falling or rising and falling edges of the input signal. If needed, additional pin can be selected to toggle between incrementing and decrementing mode.

Digital counters are implemented using interrupts and can therefore detect short signal pulses (even shorter than 1 microsecond). If switches are used in the combination with digital counters, external debouncing circuit must be installed to keep the digital counters from counting additional pulses due to switch contact bouncing on making or braking the contact.

Check PoKeys device pinout section to discover which pins are compatible with digital counter option.

PoKeys configuration software usage

To setup digital counter inputs, first set the selected pin as 'Digital input' and if digital counter is available on the selected pin, the 'Enable counter' option will be enabled. Check this option and check 'rising' and/or 'falling' edge counting option.

To enable selection between incrementing or decrementing counter modes, a direction pin can be selected in the 'Direction pin' drop-down menu. If no pin is selected, the counter mode defaults to incrementing mode.

Digital counters values status page (menu 'Peripherals > Digital counters values...') can be used to check the proper working of the configured digital counters

7.3. Encoders

PoKeys devices can handle decoding of up to 26 pairs of quadrature encoder signals. A and B signals of 25 'normal' encoders can be connected to any digital input and are intended for hand-driven rotational encoder switches with the quadrature signal frequencies up to 1 kHz.

Three fast encoders input pairs are available only on selected input pins (pins 1-2 as encoder 1, pins 5-6 as encoder 2, pins 15-16 as encoder 3) and can handle quadrature signal frequencies to about 100 kHz. When activated, fast encoders logically replace the 'normal' encoders 1, 2 and 3.

Although fast encoders can track encoders at high speed, using this feature can have an impact on device performance. It is not advised to use these to track axis position using a high-resolution encoder in connection with Pulse engine feature.

Ultra-fast encoder support is available on pins 8, 12 with the optional index signal input on pin 13. This feature uses hardware specialized hardware decoder and can handle even higher frequencies (up to 5 MHz with digital filtering disabled), but only x2 and x4 step multiplication factors are available.

Similarly as simple digital inputs, encoders can be assigned to direct key mapping or keyboard macro (only when USB connection is used). This is possible for both directions (CW and CCW) separately - the keyboard mapping of pin A is activated on positive change of the encoder value, while the keyboard mapping of pin B is activated on negative change of the encoder value.

Except for ultra-fast encoders, the encoder value can be multiplied by 1x (one 'tick'), 2x or 4x. The 4x mode increments encoder value on every signal edge and increases the resolution of the encoder for a factor of 4.

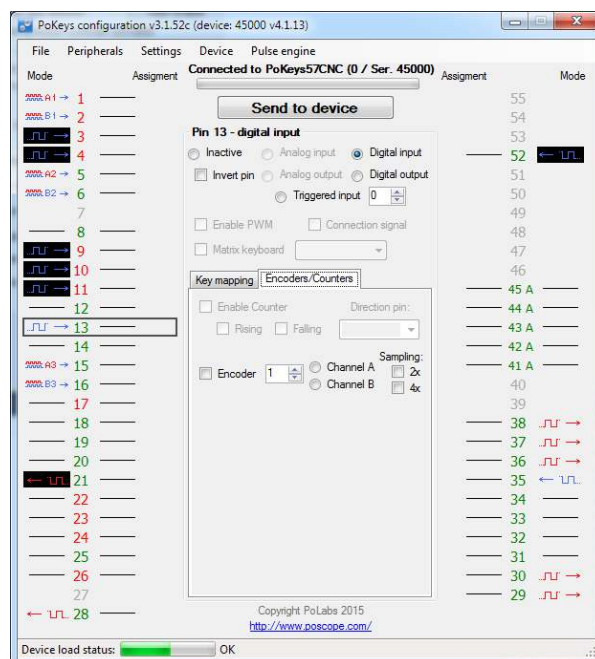


Figure 3: Encoder settings in PoKeys application

PoKeys configuration software usage

To enable encoder input on the selected pin, define the pin as digital input, switch to 'Encoders/Counters' tab, select encoder index with numerical up-down selector and select appropriate encoder channel. The last step is to check the box 'Encoder'.

To assign a key combination associated with the encoder, use the same procedure as described in the 'Digital inputs and outputs' section.

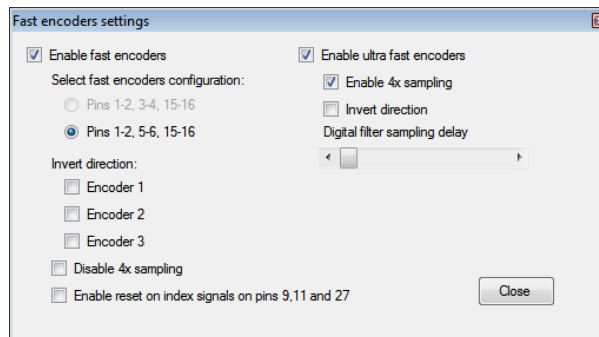
Enabling fast encoders

To enable fast encoders, go to menu 'Peripherals > Fast encoders settings', then check 'Enable fast encoders' option. There are additional options for inverting the encoders' directions, disabling 4x step multiplication and enabling the index signal on pins 9, 11 and 27. If index signal input is enabled, encoder value is automatically reset on low to high index signal transition.

Fast encoders inputs are fixed to pins 1-2 for fast encoder 1, pins 5-6 for fast encoder 2 and pins 15-16 for fast encoder 3.

Enabling ultra-fast encoders

To enable ultra-fast encoders, go to menu 'Peripherals > Fast encoders settings', then check 'Enable ultra-fast encoders' option. There are additional options to enable 4x step multiplication and inverting the encoder direction. Digital filter sampling delay slider enables setting the digital filter delay parameter - leftmost position equates to no digital filtering, rightmost position equates to digital filtering with filter delay constant set to 1000 (sampling frequency reduced to less than 25 kHz).

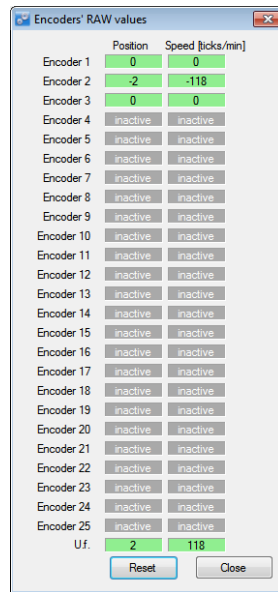


Displaying encoder raw values

To open encoder raw values dialog, go to Peripherals menu and select 'Encoder RAW values'. The following dialog below appears. It simply shows the list of all encoders and their current values. In additional column, current encoder speed is displayed.

Status of the fast encoders is displayed in green, while the status of an ordinary encoder is displayed in light grey. Inactive encoders are displayed as dark grey boxes.

At the bottom of the window, there is a command button that can be used to reset the encoders' values.



The screenshot shows a window titled "Encoders' RAW values" with a table of data. The table has two columns: "Position" and "Speed [ticks/min]". The rows are labeled "Encoder 1" through "Encoder 25", and "Uf.". The "Position" column contains values: 0, -2, 0, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive. The "Speed" column contains values: 0, -118, 0, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive, inactive. At the bottom of the table, there are two buttons: "Reset" and "Close".

| | Position | Speed [ticks/min] |
|------------|----------|-------------------|
| Encoder 1 | 0 | 0 |
| Encoder 2 | -2 | -118 |
| Encoder 3 | 0 | 0 |
| Encoder 4 | inactive | inactive |
| Encoder 5 | inactive | inactive |
| Encoder 6 | inactive | inactive |
| Encoder 7 | inactive | inactive |
| Encoder 8 | inactive | inactive |
| Encoder 9 | inactive | inactive |
| Encoder 10 | inactive | inactive |
| Encoder 11 | inactive | inactive |
| Encoder 12 | inactive | inactive |
| Encoder 13 | inactive | inactive |
| Encoder 14 | inactive | inactive |
| Encoder 15 | inactive | inactive |
| Encoder 16 | inactive | inactive |
| Encoder 17 | inactive | inactive |
| Encoder 18 | inactive | inactive |
| Encoder 19 | inactive | inactive |
| Encoder 20 | inactive | inactive |
| Encoder 21 | inactive | inactive |
| Encoder 22 | inactive | inactive |
| Encoder 23 | inactive | inactive |
| Encoder 24 | inactive | inactive |
| Encoder 25 | inactive | inactive |
| Uf. | 2 | 118 |

Figure 4: Encoders' RAW values

7.4. Pulse engine

PoKeys57CNC is a hybrid device between a USB PoKeys, Ethernet PoKeys nad PoKeysCNCaddon. As such, it contains an external pulse generator on-board, which is capable of driving of up to 8 axes controlled by STEP/DIR signals with maximum pulse frequency of 125 kHz.

The pulse engine is fully configurable in terms of:

- Axis switches configuration: each switch (Limit-, Limit+ and Home/Ref) can be independently enabled, inverted and positioned either on dedicated pins (pin value of 0) or standard PoKeys pins that are listed in the device pinout
- Axis motion control configuration: each axis can be configured to optionally use an internal motion controller in either position or speed mode
- Homing/referencing procedure: motion of the reference position search can be inverted if home/ref switch is positioned in the positive end of the axis travel. The speed of the homing procedure can be configured in percents of the maximum axis speed.
- Internal motion controller parameters: such as maximum speed, acceleration and deceleration can be individually configured for each axis.
- Integrated MPG jog mode: where PoKeys can handle the MPG jogging directly - encoder index and step multiplier can be individually configured
- Other axis settings: axis enable signals, direction inversion, soft limits, etc.

See the description of the Pulse engine status/control dialog on the next page.

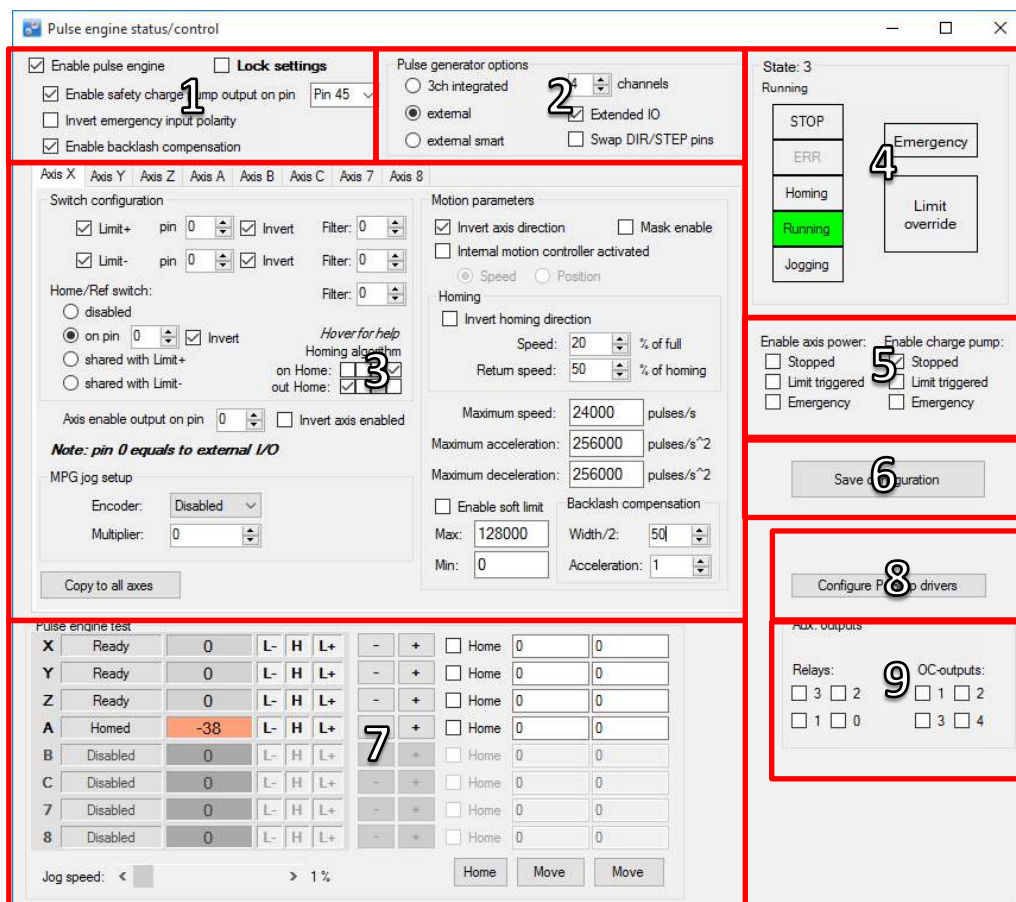


Figure 5: Pulse engine status/control dialog

Pulse engine status/control dialog parts

1. Main Pulse engine settings:
 - a. Enable pulse engine: main switch to enable or disable Pulse engine functionality
 - b. Lock: when Lock is enabled, the main Pulse engine settings and Pulse generator settings are disabled
 - c. Enable safety charge pump output: configure the pin for the charge pump output
 - d. Invert emergency input polarity: PoKeys expects NC (normally closed switch to be used as emergency switch) and HIGH signal state on emergency input indicates an emergency. If NO switch is used, the polarity of the signal must be inverted by selecting this option
 - e. Enable backlash compensation: check this option to enable the backlash compensation in PoKeys device.
2. Pulse generator options: PoKeys57CNC contains an external pulse generator on-board, thus external pulse generator option with 'Extended IO' must be selected. Up to 8 axes can be enabled
3. Axis configuration - see next page
4. Pulse engine state display and control: this panel displays current PoKeys Pulse engine state and allows the user to change between the states
 - a. STOP: stopped mode - the Pulse engine is deactivated momentarily and produces no pulses. Transition to STOP mode is instantaneous - if there is any motion being executed, the pulse generation will cease immediately after switching to STOP mode.
 - b. ERR: error mode - if PoKeys detects any event that results in error (emergency stop, limit stop, etc.), this mode will automatically be activated. As STOP mode, the transition is instantaneous
 - c. Homing: in this mode, PoKeys is executing the homing procedure. The selected axes are referenced in regards to the position of Home/Ref switch. PoKeys executes homing procedure in two steps - in first step, coarse position of the switch is located using faster motion in the negative direction of the axes (unless Homing direction is inverted in the settings). When the switch is located, the fine position of the reference position is located using slower motion in the positive direction of the axis (again, if not inverted in the settings) until the Home/Ref switch is released.
 - d. Running: normal operating mode
 - e. Jogging: jogging mode - in this mode, PoKeys Pulse engine can use the values from the encoders to directly jog the configured axes
 - f. Emergency: this field indicates whether device entered Emergency state
 - g. Limit override: switch that allows the user to activate the limit override
5. Enable axis power and enable charge pump: these options select, when the axis enable and chargepump output signals are activated (besides normal operating modes)
6. **Save configuration** button: after the settings are changes, this button must be clicked to send the settings to device and save them to the on-board non-volatile memory. Since this operation may produce interruptions in the motion, it is suggested to stop any motion before commencing configuration save.
7. Pulse engine testing panel:
8. Additional configuration options - here, additional configuration dialogs can be opened
9. Auxilary outputs: these can be used to test the on-board auxilary outputs

- a. Relays 0 and 1 control the SSR outputs
- b. Relays 2 and 3 control the on-board relays
- c. OC-outputs control the galvanically isolated open-collector outputs

Axis configuration panel

This panel contains settings for each axis.

The screenshot shows the Axis configuration panel with the following settings highlighted by numbered callouts:

- 1:** Limit+ pin (0) and Limit- pin (0) in the Switch configuration section.
- 2:** Home/Ref switch configuration, specifically the 'on pin' (0) and 'Invert' checkbox.
- 3:** Axis enable output on pin (0) in the Axis enable output section.
- 4:** Encoder selection (Disabled) in the MPG jog setup section.
- 5:** Copy to all axes button.
- 6:** Invert axis direction checkbox in the Motion parameters section.
- 7:** Homing Speed (20) and Return speed (50) in the Homing section.
- 8:** Maximum acceleration (256000) in the Motion parameters section.
- 9:** Max soft limit (12000) in the Backlash compensation section.
- 10:** Width/2 (50) in the Backlash compensation section.

Figure 6: Axis configuration panel

1. Limit switch configuration: individual limit switch (on axis positive and negative ends) can be individually enabled and inverted (in NO switches are used). Since PoKeys57CNC uses external pulse generator with extended IO, 0 should be selected as pin number.
2. Home/Ref switch configuration: this switch can be configured as a separate switch or shared with either Limit+ or Limit- switches. See below for Homing algorithm description.
3. Axis enabled output: pin 0 should be selected in dedicated signal pin on motor connector is to be used. The state of the signal can be inverted if motor drivers require it.
4. MPG jog setup: select encoder and multiplier factor to setup direct MPG jogging that is active in Jogging operating mode
5. Copy to all axes: all settings are copied to all other axes by clicking on this button
6. Motion configuration: axis direction can be inverted here. Optionally, internal motion controller can be activated, allowing PoKeys device to produce the motion signals based on position or speed reference setup. The 'Mask enable' option is for testing purposes and enables third-party software to enable individual axes independently.
7. Homing configuration: use these settings to invert homing direction and set the speed of the motion during homing procedure
8. Motion parameters: use these fields in case that Internal motion controller is enabled to setup the maximum speed, acceleration and deceleration values. When the value is entered

into the fields, **confirm the value by pressing 'Enter' ('Return') key** - the field will change color from red to white.

9. Soft limits configuration: optionally, soft limits can be configured for each axis. When internal motion controller detects the current position has gone out of these limits, the motion is softly stopped and only motion in the out-of-limit direction is allowed.
10. Backlash compensation: PoKeys devices support backlash compensation feature. Enter the size of the backlash (in pulses) and the maximum acceleration used for compensation.

Homing algorithm configuration

PoKeys devices support customization of the homing algorithm. The algorithm is based on executing selected actions on different events:

- On Home event (home switch contact is detected) - this event happens when the machine touches and activates the home switch (configured in the options above)
- Out Home event (home switch contact is released) - this event happens when the machine backs off the switch or gets past the home switch.

On these two events, the combination of the following actions can be configured (selection boxes from left to right):

- Stop and reset the position - this action marks last position as home position and commands the motion to stop. It also finishes the homing procedure for the axis
- Arm the encoder index for stop - this action arms the encoder index input for the selected axis. On the next encoder index signal, the position of the axis is marked as home, axis is commanded to stop and the homing procedure for the axis is finished. Fast encoders index inputs 1, 2, 3 (pins 9, 10 and 11 on PoKeys57CNC and 9, 11 and 27 for other PoKeys devices) are used for axes 1, 2, 3, while ultra fast encoder index input is used for axis 4.
- Reverse direction - reverse the homing direction
- Slow down - slow down the homing speed to the reduced speed, as configured

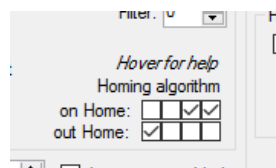


Figure 7: Homing algorithm selection boxes - default configuration (reverse and reduce speed on home and stop on home release)

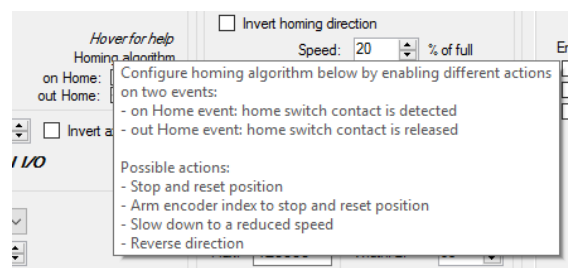
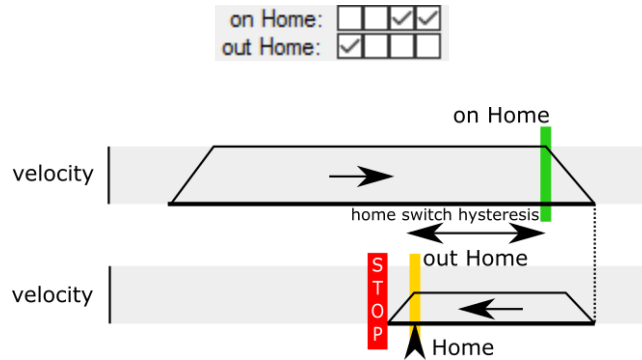


Figure 8: Built-in help

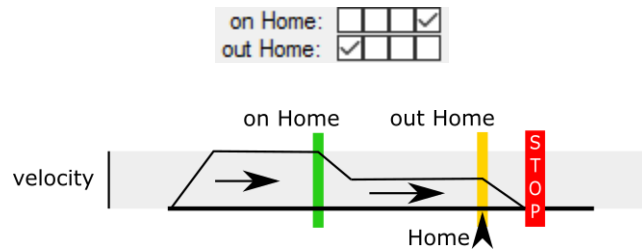
Common homing algorithm configurations

Although the homing algorithm is configurable, there are some standard configurations that fit most CNC machine configurations:

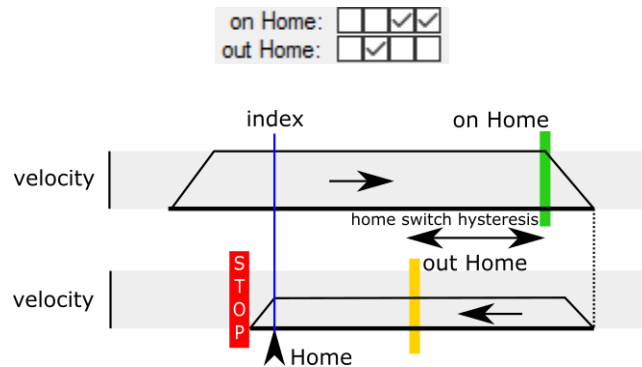
1. Standard homing configuration



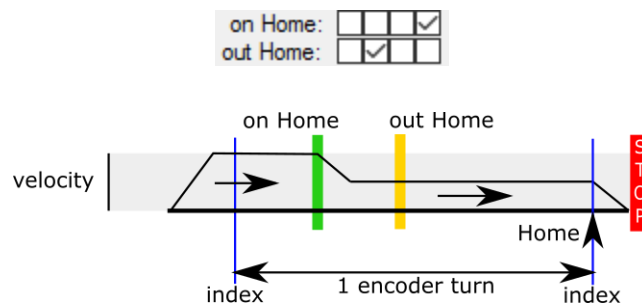
2. Homing without reverse



3. Homing with encoder index - standard



4. Homing with encoder index - without reverse



Limit and home switch filters

The limit and home switch inputs support digital filtering. The filter value defines the minimum time for the limit or home switch signal activation (1 unit equals to 100 μ s = 0.0001 s) - possible values are between 0 (no filtering) to 254 (25.4 ms).

PoStep drivers configuration

If PoStep60-256 drivers are connected with PoKeys57CNC device using PoExtension2 bus, configuration (step mode, temperature limit, motor current settings) of the drivers can be done via PoKeys57CNC device. Status of the drivers (temperature, voltage, input states, faults) can also be displayed.

In order to establish connection between PoStep drivers and PoKeys57CNC, configure unique I2C addresses to each PoStep device using PoStep configuration tool (Figure 12). PoKeys device functions as a proxy between the PC application and PoStep drivers.

Open PoStep driver configuration dialog using the 'Configure PoStep drivers' button on the Pulse engine dialog. Select one of the axes and select the I2C address for the driver (the address must be set to the value equal to what was set in the PoStep configuration tool in previous step).

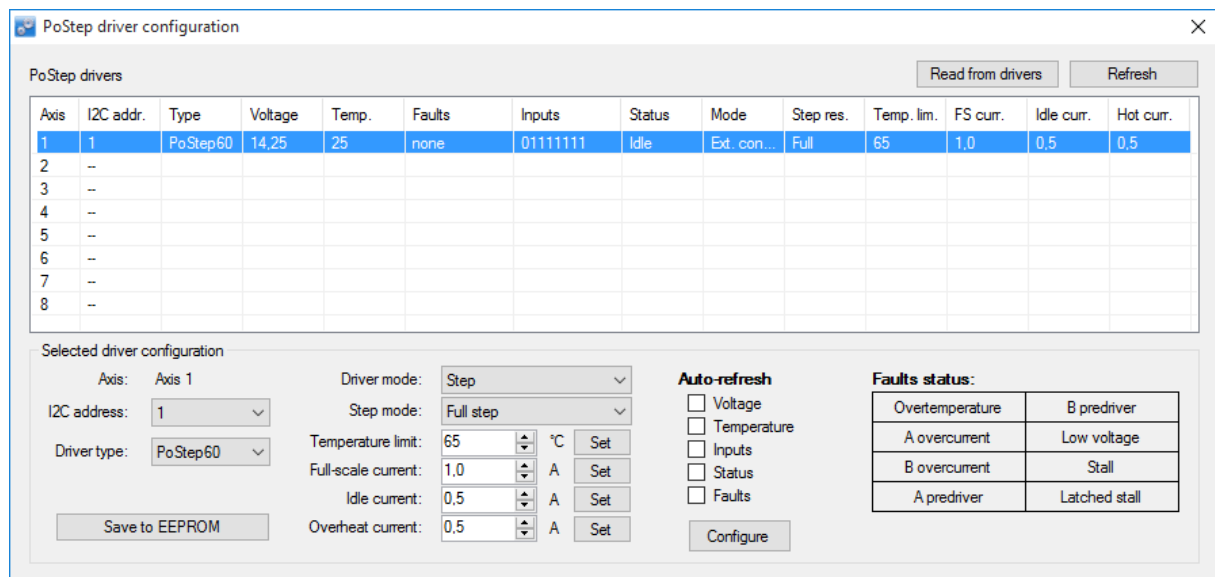


Figure 9: PoStep driver configuration dialog

The configuration dialog contains the list of PoStep drivers on the top and selected driver configuration and status at the bottom. In top right, there are buttons to retrieve settings from the PoStep device and to refresh the settings.

Once the device is configured, the driver mode, step mode, temperature limit and current settings are made available to the user. PoKeys device automatically configures the PoStep driver according to the selected values. Numeric selection settings require the user to press the 'Set' button. Although, the settings are sent to PoStep drivers, they are only valid until the PoStep device is reset - to save the settings as default startup settings, click on 'Save to EEPROM'.

Automatic refresh of PoStep status can be enabled by configuring the auto-refresh options. Select the values to refresh and click on 'Configure'. PoKeys will periodically scan through PoStep devices and retrieve their statuses.

Connecting PoStep drivers to PoKeys57CNC

Connect PoStep drivers (PoStep60-256) in parallel with PoKeys57CNC device using PoExtension2 bus. All connectors on the PoExtension2 bus must be crimped in parallel to each other (take care of the connector polarity) - see pictures below.

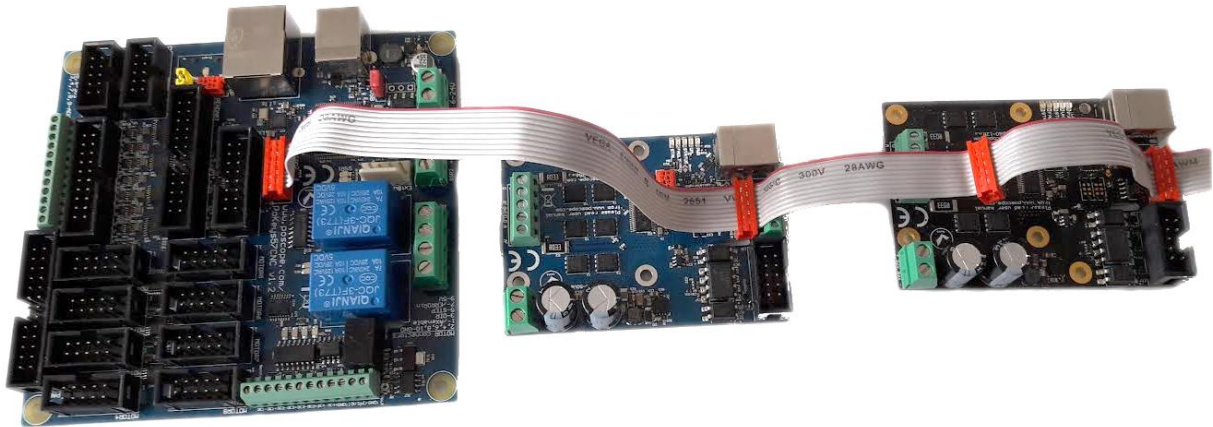


Figure 10: Two PoStep60-256 stepper motor drivers connected to PoKeys57CNC device

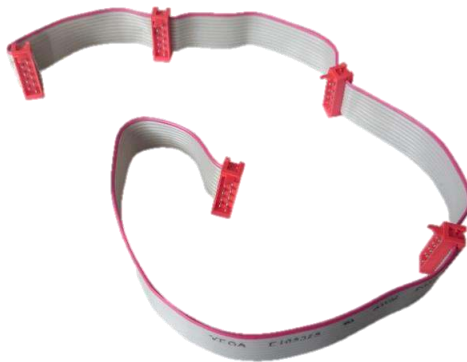


Figure 11: PoExtension2 cable for connecting PoStep drivers with PoKeys57CNC device

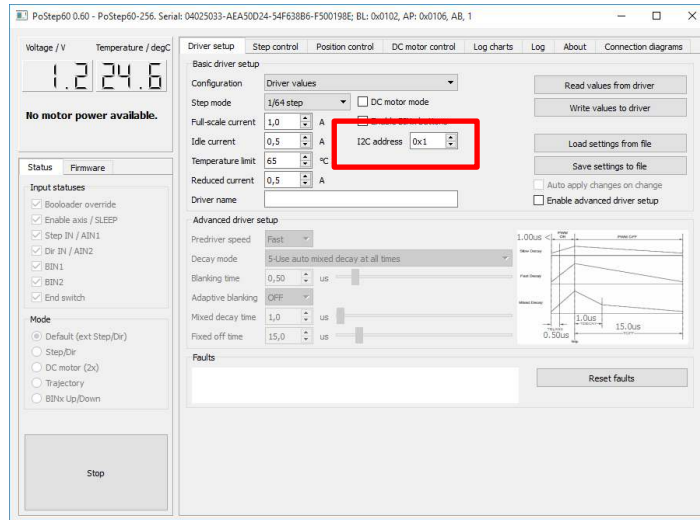


Figure 12: I2C address configuration in PoStep configuration tool

7.5. Matrix keyboard

Matrix keyboard is a set of buttons, connected into a mesh. All buttons in a row share one contact, same goes for each of the buttons in the column. If a button is pressed, a key press is detected with a periodic scanning of each of the rows and columns. PoKeys devices use digital outputs for setting the voltage levels on rows and read column voltage levels using digital inputs that already have internal pull-up resistors, so no external circuitry is needed.

PoKeys devices support matrix keyboards of up to 16x8 in size, simpler 3x3, 4x3, 4x4 and others are of course fully supported.

Similarly to simple digital inputs, keys of the matrix keyboard connected to the PoKeys device can be configured as USB keyboard keys. Direct mapping, mapping to macro sequence and triggered mapping are all supported. Additional alternate function can be used to assign two different keyboard keys to each of the matrix keyboard buttons. If additional (and freely selectable from the list of digital inputs) Fn+ input pin is inactive, the default function key is used. If the Fn+ key input pin is activated, an alternate function key is used instead of the default.

On all devices, the status of key presses of the matrix keyboard can be read using the PoKeys library commands without the need to setup the mapping described above.



Figure 13: Standard 4x3 matrix keyboard

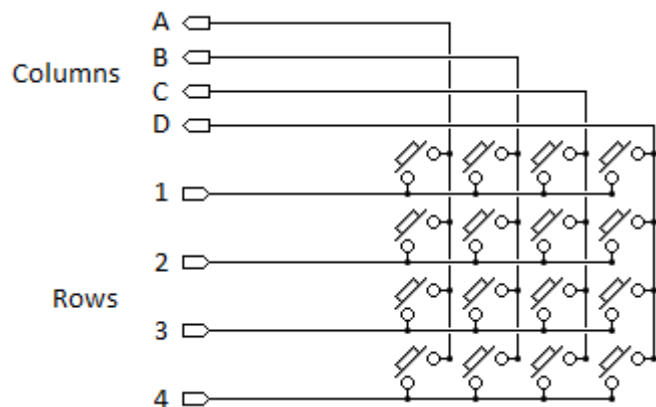


Figure 14: 4x4 matrix keyboard internal structure

PoKeys configuration software usage

Before any matrix keyboard configuration can be done, go to 'Peripherals > Matrix keyboard...', check the 'Enable matrix keyboard' option and select the number of rows and columns. Close the dialog and continue by selecting column and row pins.

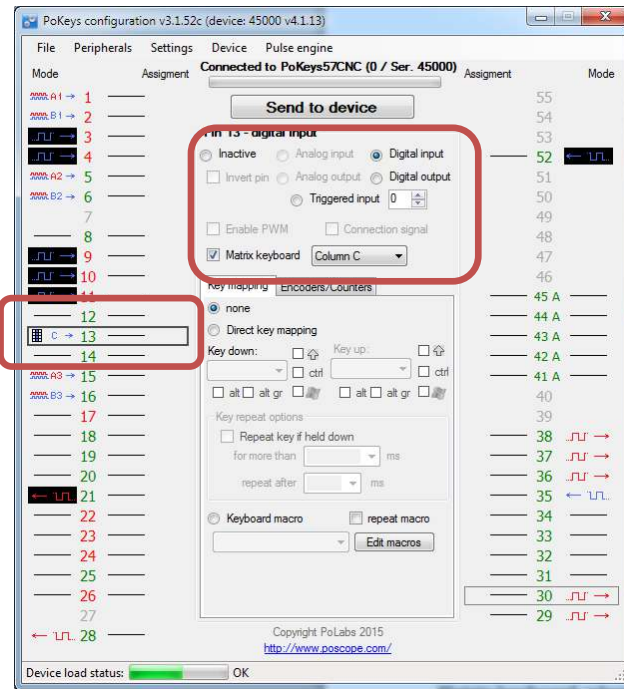


Figure 15: Assigning row and column pins

Matrix keyboard column selection

Each free digital input pin can be assigned as matrix keyboard column input. Make sure the selected pin is configured as digital input, then check the 'Matrix keyboard' option for the pin and select the appropriate column letter from the list.

Matrix keyboard row selection

Each free digital output pin can be assigned as matrix keyboard row output. Make sure the selected pin is configured as digital output, then check the 'Matrix keyboard' option for the pin and select the appropriate row number from the list.

Keyboard mapping configuration

Open the 'Peripherals > Matrix keyboard...' menu for configuration of the keyboard mapping. Matrix keyboard is schematically drawn in the dialog below. On the right, key mapping settings can be selected. To setup mapping, click on one of the keys in the matrix keyboard drawing and select appropriate key mapping options on the right.

To test the matrix keyboard, first make sure that the settings have been saved to device (close the Matrix keyboard dialog and click on 'Send to device' button). The matrix keyboard dialog can then be used to test the matrix keyboard – just press any key on your matrix keyboard and the appropriate button in the matrix keyboard drawing will be highlighted.

To setup different key presses for 'key press' and 'key release' events, check 'Triggered mapping' option and select different settings for 'Down key' ('key press' event) and 'Up key' ('key release' event).

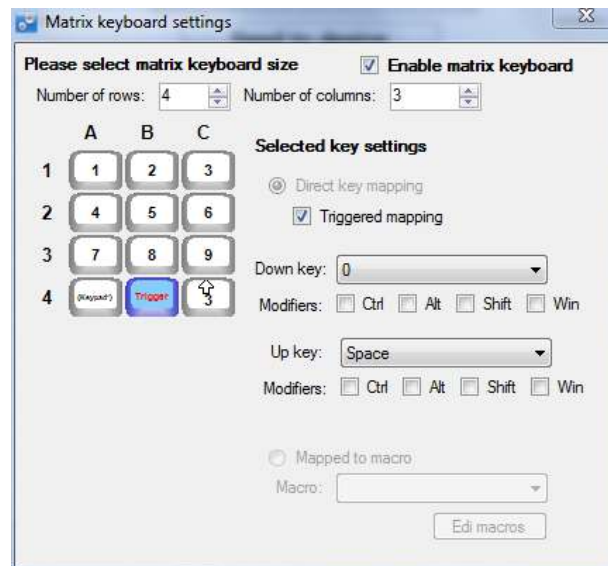


Figure 16: Matrix keyboard configuration for a 4x3 matrix keyboard

7.6. Analog inputs

Analog input function is only available on pins 41 to 45. These analog inputs can also be freely mapped to any of the 6 joystick axis; X, Y, Z, rotation X, rotation Y and throttle.

Analog inputs have a resolution of 12 bits and are sampled at a fixed rate of 10 kHz, then fed through adjustable digital low-pass filter with the following equation

$$y(k) = y(k - 1) * \frac{filter}{filter + 1} + u(k) * \frac{1}{filter + 1}$$

where $y(k)$ is the output analog value, $u(k)$ is a new A/D sample and $filter$ is a user-adjustable constant. For proper operation of the digital filter, an analog low-pass filter with a cut-off frequency of 5 kHz must be used on each analog input. The following equation gives the relation between value of $filter$ and filter's cut-off frequency:

$$f_c = \frac{10 \text{ kHz}}{2\pi * filter}$$

Sample $u(k)$ is produced according to the following equation

$$u(k) = \frac{U(k)[V]}{3.3 \text{ V}} * 4095$$

where $U(k)$ (in Volts) is a voltage present on the selected analog input pin.

PoKeys configuration software usage

To open analog inputs dialog, go to Peripherals menu and select 'Analog inputs and outputs'. Dialog below appears. To enable display of analog input channel, check the appropriate check box. It is enabled only when the input is set up as analog input.

The progress bar displays the current voltage at the pin with the maximum at 3.3V. Below the input selection boxes user can set low-pass filtering for analog inputs. When analog input signal appears to

be flickering or jumping due to analog signal noise, move the value for the filter to the right towards label 'slow signals' and then press Set button.

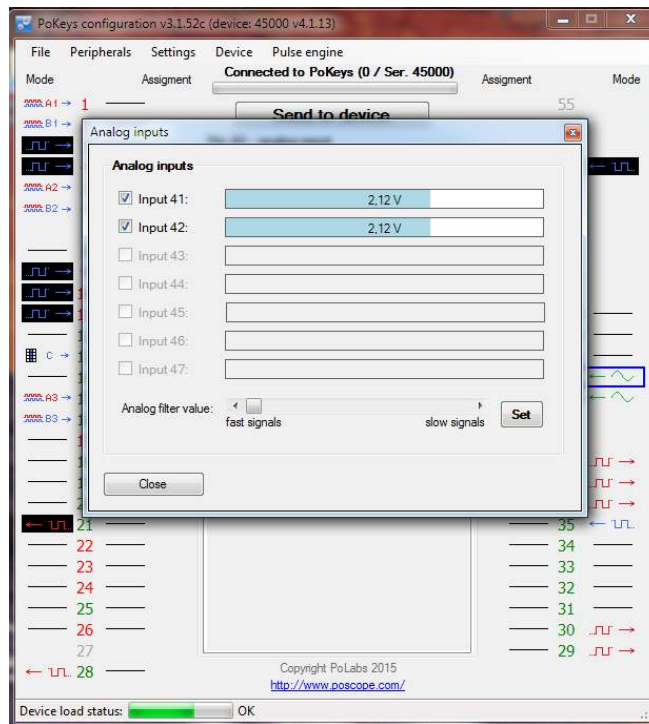


Figure 17: Analog inputs and outputs dialog

7.7. Joystick mapping

Each axis of the PoKeys virtual joystick can be assigned an analog input source. In addition, analog to digital mapping option can be enabled, which allows user to connect an analog joystick to a PoKeys devices and simulate key presses for each direction of the joystick. User can freely select dead band and saturation ranges.

Besides mapping the analog inputs to virtual joystick axes, digital inputs (or encoder switching events) can be mapped to any of the 32 virtual joystick buttons (either directly or 'triggered') or 4-way POV hat selector. The triggered mapping to joystick buttons enables used to select different pins that triggers selected joystick button on off-to-on transition (Down Event) and on on-to-off transition (Up Event).

PoKeys configuration software usage

Joystick axis and buttons mapping can be setup via Joystick mapping dialog. Go to 'Peripherals' and select 'Joystick settings...'. The dialog on Figure 18 appears.

Each axis can be assigned an analog input. In addition, analog to digital mapping option can be enabled. This allows user to connect an analog joystick to a PoKeys devices and simulate key presses for each direction of the joystick. To do so, first check 'Map to key' option. Then set the dead band (when input value will be between lower and upper dead band margins, no keys will be activated) using sliders. In the lower part of the window, select the mapping options.

For simple direct mapping (pin input status is directly reflected in joystick button status) use the 'Direct mapping' option and select pin number to be associated with selected joystick button. If more advanced behavior is needed (joystick button is pressed for a short time only on transitions of pin status), user should select 'Triggered mapping' option to select one pin that triggers selected joystick button on off-to-on transition (Down Event) and one pin that triggers this joystick button on on-to-off transition (Up Event).

If joystick button mapping is to be used in connection with encoder inputs, use 'Triggered mapping' option (encoder's values cannot be directly translated into direct mapping) and select a pin with the appropriate encoder channel. For example: pins 5 and 6 are set up as digital inputs with encoder (channel A on pin 5 and channel B on pin 6). When pin 5 is selected as Down event pin for joystick Button 2 and pin 6 is selected as Down event pin for joystick Button 3, rotating the encoder in positive direction will trigger joystick Button 2 on each detent. Similarly, rotating the encoder in negative direction, joystick Button 3 will be triggered on each detent. Up Event pin option cannot be used in connection with encoders.

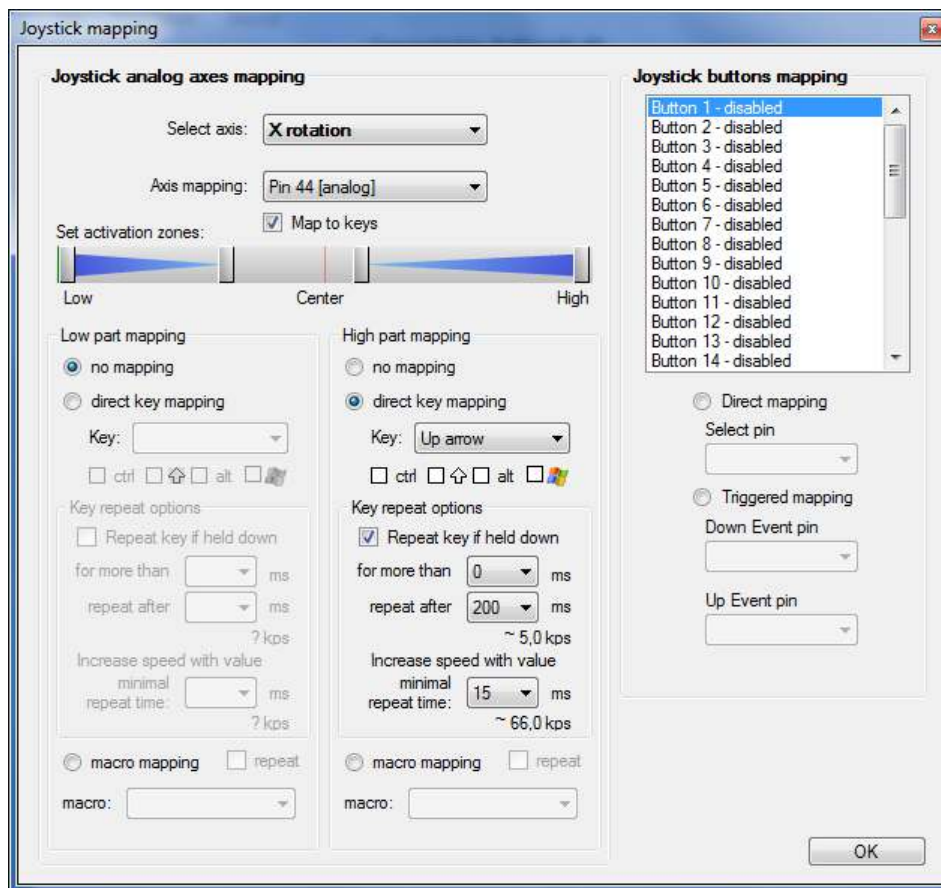


Figure 18: Joystick mapping settings

7.8. PWM outputs

PoKeys57CNC device supports PWM output function on 4 pins (pins 18, 20, 21 and 22). Different duty cycles can be assigned to each PWM output however, all outputs share the same PWM period. PWM outputs can be easily amplified using an external transistor and used for control of loads with

increased current demand - pins with such function embedded are marked as OC (open-collector) in the pinout diagram. PoKeys PWM outputs can also be used to drive various R/C servo motors that accept PWM signal with 50 Hz frequency (20 ms PWM period) and duty cycles between 5 and 10 % (1 to 2 ms).

PoKeys devices have an in-built PWM module that operates at a fixed clock frequency (25 MHz). Both the PWM period and the PWM duty cycles must be expressed as number of module clock cycles (i.e. 20 ms PWM period equates to $0.020 \times 25\,000\,000 = 500\,000$).

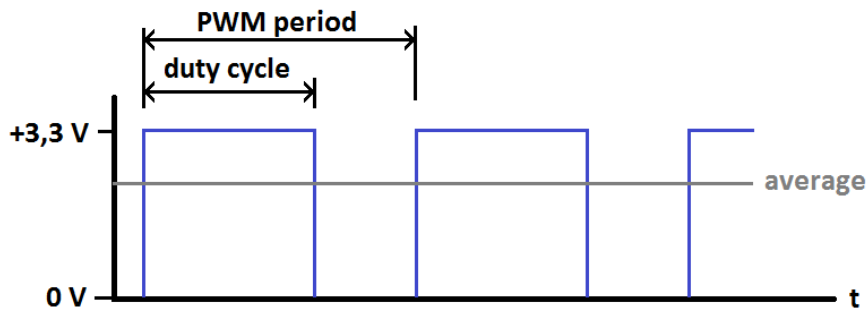


Figure 19: PWM output

PoKeys configuration software usage

PoKeys device’s PWM (pulse width modulation) module can be setup via Peripherals > PWM outputs....

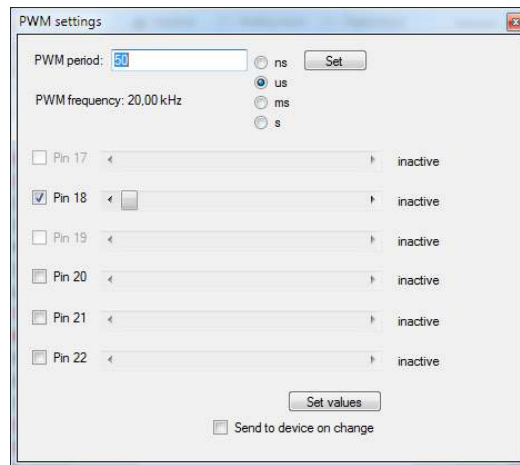


Figure 20: PWM outputs settings

In this window, user can enter PWM period and set PWM duties for each channel. Channels can be independently enabled or disabled. After a change is made, user must click 'Set values' button or check 'Send to device on change' checkbox. Left position of a slider means 0% and right position 100% respectively.

7.9. LCD

PoKeys devices support connecting one alphanumeric LCD module up to a size of 4x20 (4 rows, 20 columns). The selection of the module is limited by support for HD44780 or compatible chipset. Usually these displays come in various sizes - 1/2/4 line with 8/16/20 characters and colors (black letters on green background, white letters on blue background ...).

PoKeys57CNC device has a dedicated connector for such LCD displays - see the pinout section of the manual for connector pinout description.

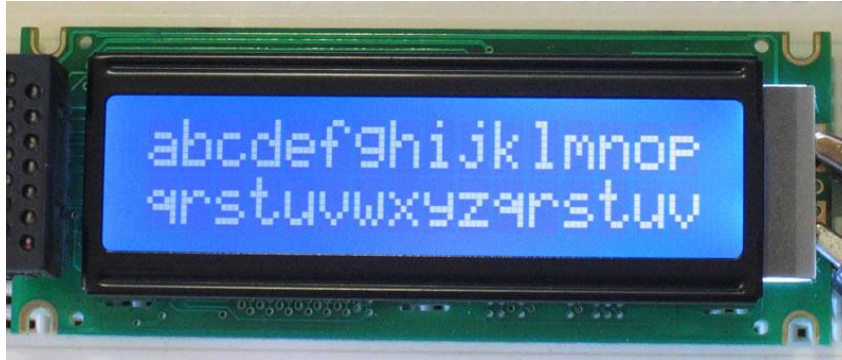


Figure 21: Typical 2x16 character LCD

LCD display can be used to display various data. A third-party application or a script can execute all supported operations, including LCD initializing, clearing, moving cursor, setting display shifting mode, custom character defining and displaying text.

PoKeys57CNC devices by default function in buffered LCD mode. In this mode, any LCD-related command that is sent to PoKeys device is first buffered and when possible, PoKeys device executes the LCD refresh on its own. In this mode, some LCD operations are not operational – cursor movement is controlled by the PoKeys device and cursor move or display commands may not work as expected. If this low-level control is desirable, buffered mode must be deactivated first. In other cases, it is advisable to use buffered mode in order to allow better load balancing in PoKeys devices and in the end obtain greater communication speed.

Before LCD initialization, the LCD module size (number of rows and columns) must be specified and appropriate pin assignment (primary or secondary, see the table above) must be selected. Secondary pins must be selected in case of matrix LED display 2 in use.

PoKeys configuration software usage

Functions of this interface can be tested through PoKeys settings application. Just open Peripherals > Test LCD... and dialog below will appear.

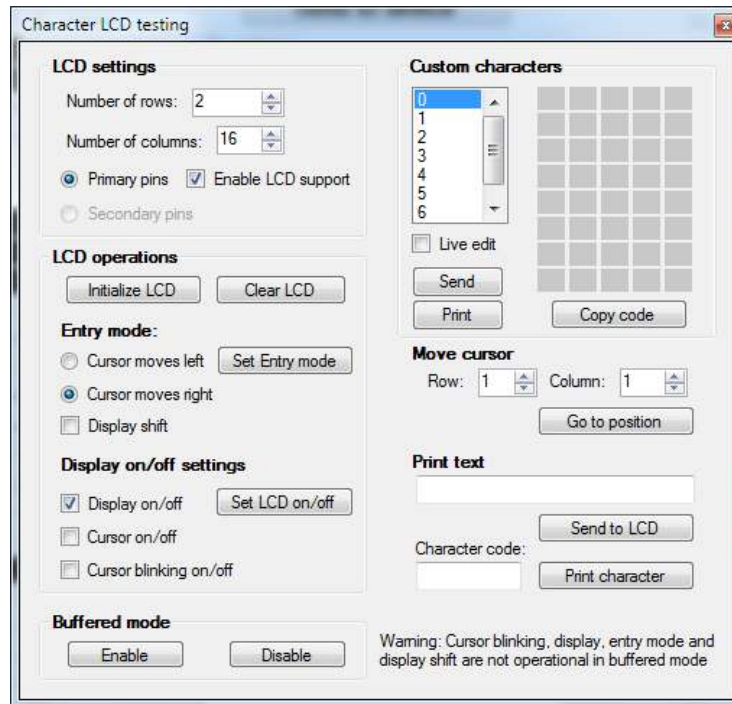


Figure 22: Character LCD testing dialog

LCD settings

In this part, user can set number of rows and columns in the LCD used. Support for LCD can be enabled or disabled also.

LCD operations

Before user can start using the LCD, LCD module must be initialized. This is done via 'Initialize LCD' button. Button 'Clear LCD' clears LCD display and moves cursor to home position. LCD module is initialized automatically by PoKeys device on device startup if 'Enable LCD support' option is enabled.

User can also set entry mode settings of LCD module. Cursor can be set-up to move either right (normally) or left after each character displayed. If 'Display' shift is enabled, whole display shifts with every new character displayed.

Settings are processed after user clicks button 'Set Entry mode' and work only in 'unbuffered' mode described above.

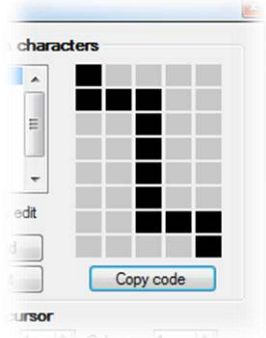
Display on/off settings

User can set on/off switches for whole display, cursor and cursor blinking.

Settings are processed after user clicks button 'Set LCD on/off' work only in 'unbuffered' mode described above.

Custom characters

Simple interface enables to draw up to 8 custom characters. These characters can then be used on display. Selecting 'Live edit' mode will transfer the character each time a change is made to any of the pixels. Character can be previewed via button 'Print', which puts current custom character on the LCD display. The 'Copy code' button can be used to export the character data in a form of C-style array, as shown in the table below.

| LCD custom character editor | Produced code |
|---|--|
|  | <pre> unsigned char uCustomChar[8] = { 0x10, 0x1C, 0x04, 0x04, 0x04, 0x04, 0x07, 0x01, }; </pre> |

Move cursor

This section enabled user to move cursor to any position on the screen works only in 'unbuffered' mode described above.

Print text

Sends entered text to display module. If advanced characters are needed, enter character code in lower text box and press 'Print character'.

7.10. PoExtBus

PoExtBus bus support enables user to add additional ten 8-bit shift registers to add up to 80 additional digital outputs to PoKeys device.

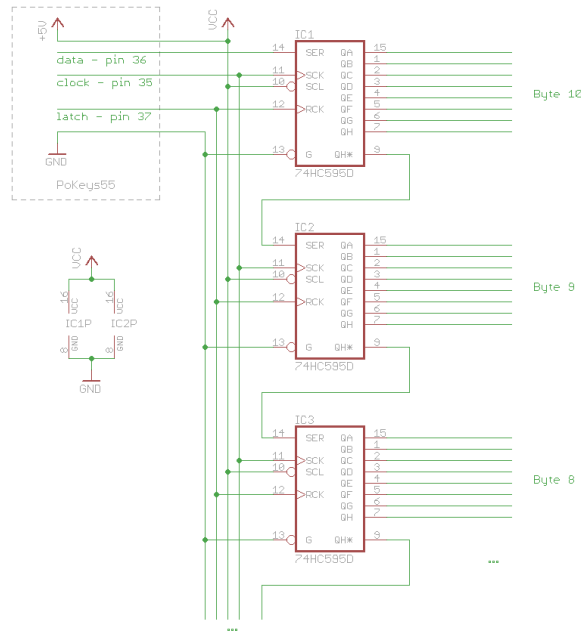


Figure 23: PoExtBus outputs chaining

PoKeys configuration software usage

To set-up and test PoExtBus, open 'Peripherals' > PoExtBus...'. The dialog below (Figure 24) appears. By using mouse left and right clicks, user can turn on or off each of the outputs.

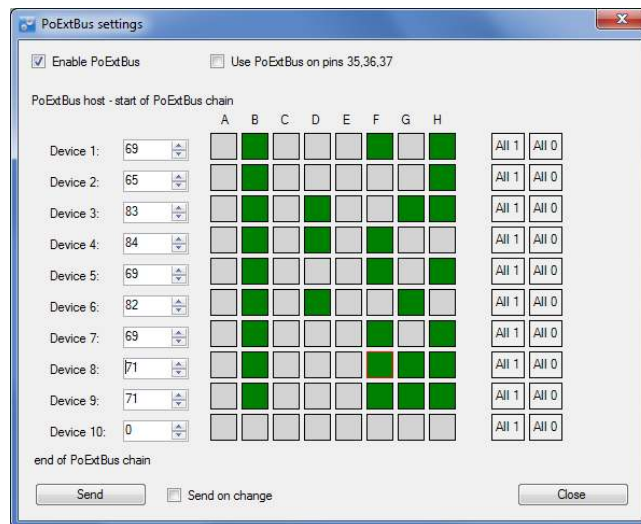


Figure 24: PoExtBus setup dialog

PoExtBus connector type

- Female wire-side connector: Molex 22-01-2055
- Cable contacts: 08-50-0032 (5 pcs needed)
- Prepared cables: 88941-0700 (5 pcs needed)

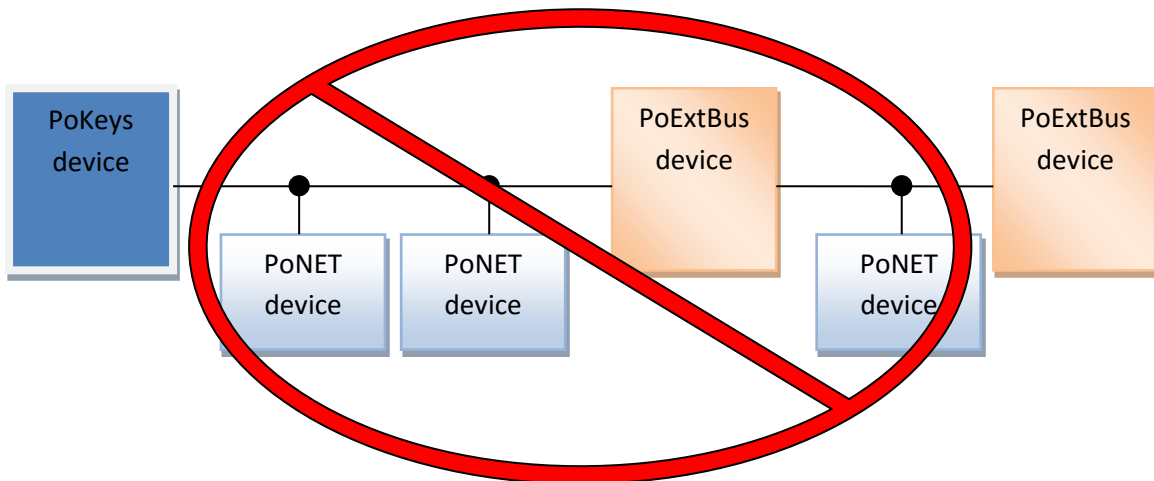
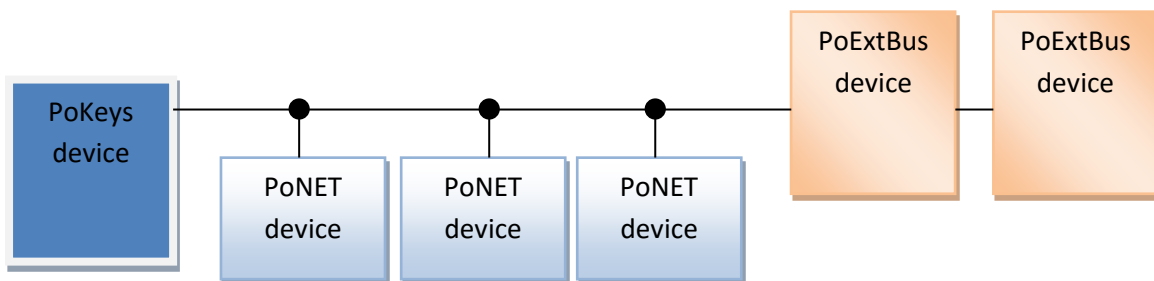
7.11. PoNET

PoKeys57CNC device supports PoNET devices (such as kb48CNC CNC keyboard).

Multiple PoNET and PoExtBus devices can be linked together. While the PoNET devices and PoExtBus devices share the same PoExtBus/PoNET connector, user should pay attention in connecting devices of both types together (see the schematics below).

All PoNET devices must be connected in parallel to each other and directly to the PoExtBus/PoNET connector, while the PoExtBus devices should be connected in series after the PoNET devices, as described below

- **PoNET devices must be connected in parallel to each other**
- **PoExtBus devices must be connected in series**
- **There should be no PoExtBus device between PoKeys device and PoNET devices**



Adding new devices

After connecting new PoNET device, go to 'Peripherals > PoNET...'. The following dialog will appear

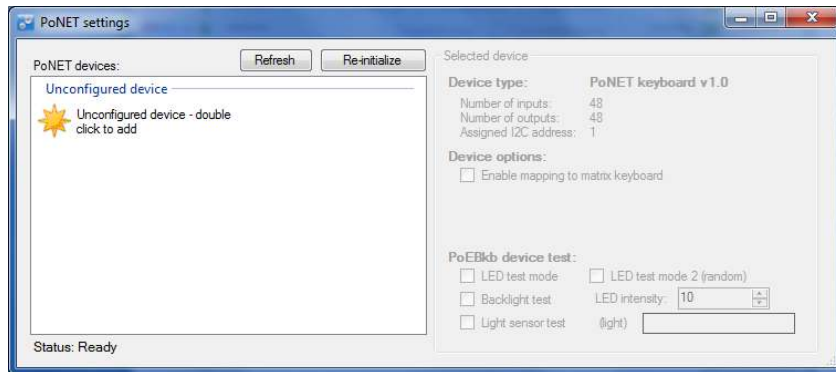


Figure 25: PoNET settings dialog with an unconfigured device

In order to register new device, double click on the 'Unconfigured device' icon. In the next 10 seconds press any key on the device that is about to be added. If the process is successful, status LED on the device will stop blinking and will be constantly lit. The device will also be listed as in the dialog below:

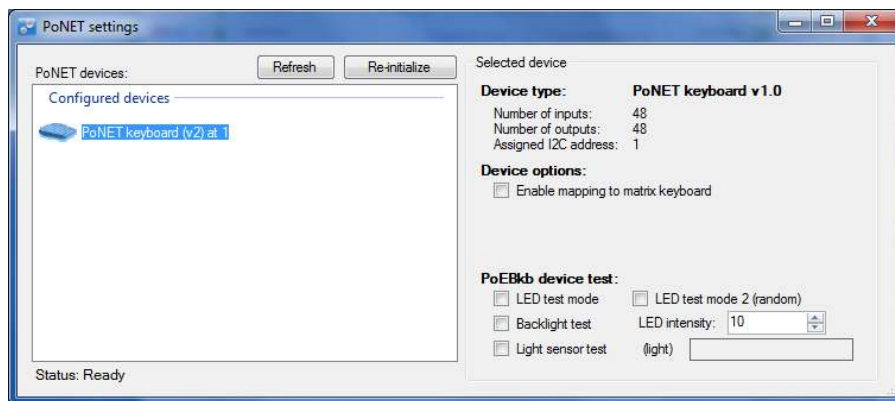


Figure 26: PoNET settings dialog with a successfully configured device

PoNET kb48CNC keyboard



The device can be virtually mapped to PoKeys matrix keyboard. Third party software can set the status of LEDs under the keys, read the light sensor that measure the amount of light in the environment and set the intensity of the LEDs.

To map the PoNET keyboard to PoKeys matrix keyboard, initialize the PoNET bus as described above in 'Adding new devices', select the keyboard in the device list and check the checkbox 'Enable mapping to matrix keyboard'.

7.12. Failsafe settings

PoKeys devices support the configuration of the failsafe state for the digital outputs, PWM outputs, PoExtBus devices and PoKeys Pulse engine.

When the communication with the device is interrupted for longer than a period defined in the failsafe configuration, peripherals listed above enter the failsafe mode, which can be setup in 'Failsafe settings' dialog (Peripherals > Failsafe settings...)

| Peripheral | Failsafe setting |
|------------------|--|
| Digital outputs | Active Off / Active On |
| PoExtBus outputs | Active Off / Active On |
| PWM outputs | Fixed duty cycle in % |
| Pulse engine | No setting – Pulse engine enters emergency mode on failsafe activation |

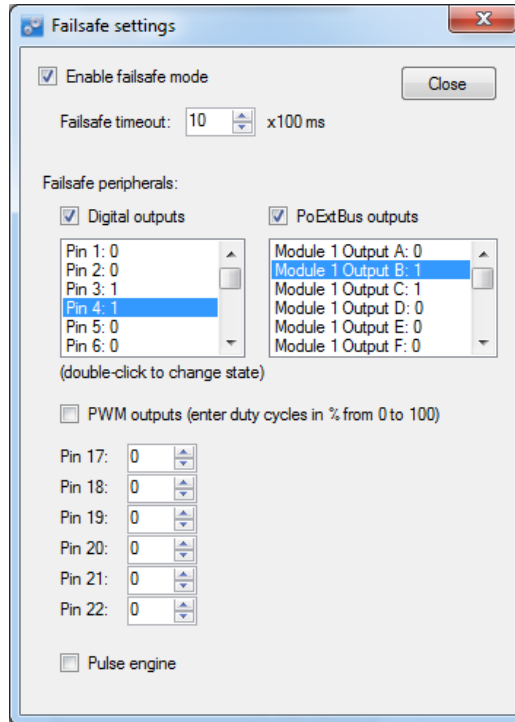


Figure 27: Failsafe settings dialog

7.13. Peripheral communication protocols

I²C protocol

The I²C bus was designed by Philips in the early '80s to allow easy communication between components which reside on the same circuit board. Philips Semiconductors migrated to NXP in 2006. The name I²C translates into "Inter IC". Sometimes the bus is called IIC or I²C bus.

PoKeys devices support communication with I²C slave devices, connected to the PoExtBus/PoNET connector. As I²C, PoNET and PoExtBus use the same connector, PoExtBus, PoNET and I²C functions are automatically switched by the PoKeys device.

Marking the pin closer to the edge of the PoKeys57CNC board as pin 1, the I²C devices should be connected as follows:

| | |
|--------------|------------------------|
| Pin 1 | Power supply 5V |
| Pin 2 | Ground |
| Pin 3 | Serial data |
| Pin 4 | |
| Pin 5 | Serial clock |

Protocol can be tested via PoKeys configuration software. Click on Peripherals > I²C bus test... The following dialog appears.

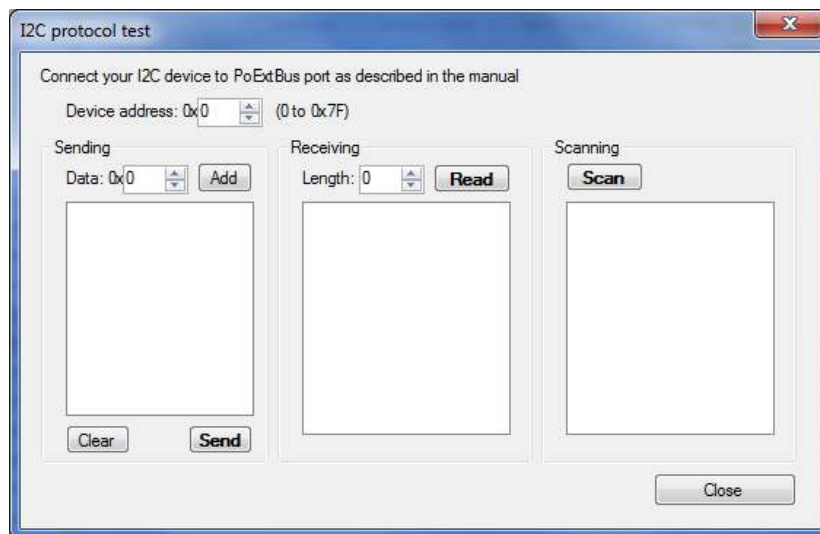


Figure 28: I²C protocol test dialog

1-wire

1-Wire is a device communications bus system designed by Dallas Semiconductor Corp. that provides low-speed data, signaling, and power over a single signal wire. 1-Wire is similar in concept to I²C, but with lower data rates and longer range. It is typically used to communicate with small inexpensive devices such as digital thermometers and weather instruments.

PoKeys devices support communication with 1-Wire slave devices (without parasitic power supply), connected to the pin 55 with external pull-up resistor (of approximately 5 kΩ).

Protocol can be tested via PoKeys configuration software. Click on Peripherals > 1-Wire bus test... The following dialog appears.

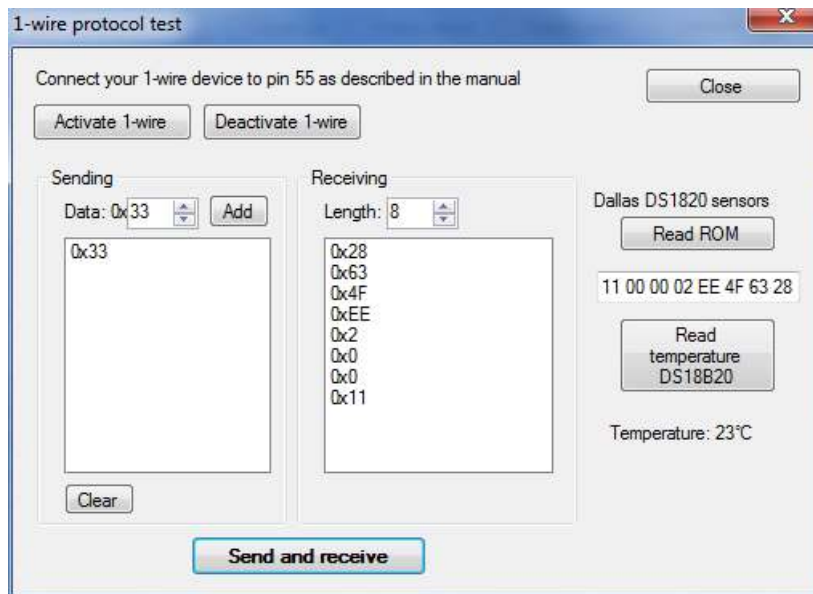


Figure 29: 1-Wire protocol test dialog

7.14. EasySensors

PoKeys57 series devices implement a feature called EasySensors. It is an improvement of the original support for various sensors in PoKeys56 series devices. EasySensors feature allows the user to setup up to 100 sensors on various communication buses (including I²C, 1-wire, DHTxx 1-wire and analog inputs). The feature is accessible in Peripherals > EasySensors menu.

EasySensors configuration dialog

The main EasySensors configuration dialog contains a list of all configured sensors with corresponding sensor information. Here, the sensory type, reading and refresh rate can be changed.

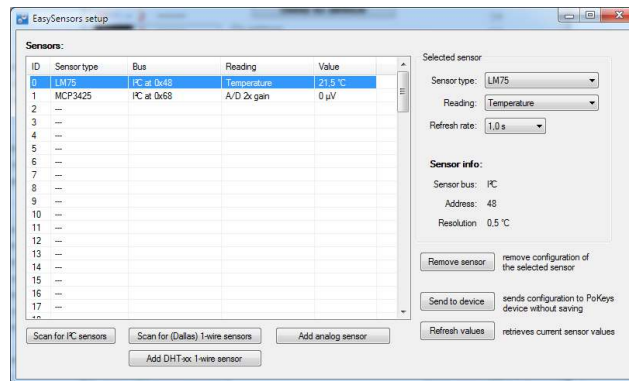


Figure 30: EasySensors configuration dialog

The changed sensor entries are marked with red color - in order for the changes to take effect, click on 'Send to device' button, which transfers the EasySensors configuration to device (note that this action does not save the settings to device's non-volatile memory and 'Send to device' on main PoKeys configuration window must be clicked to do that).

There are 4 types of sensors supported and each type of sensor can be added by clicking a corresponding button at the bottom of the dialog.

Scan for I²C sensors

This command opens the 'Add I²C sensor' dialog, which is automatically populated with detected I²C devices and sensor type suggestions. Sensor type, reading and refresh rate can be changed using the selections on the right part of the diagram. In order to add the configuration of I²C sensor, check the corresponding item in the detected I²C devices list and click on 'Finish'.

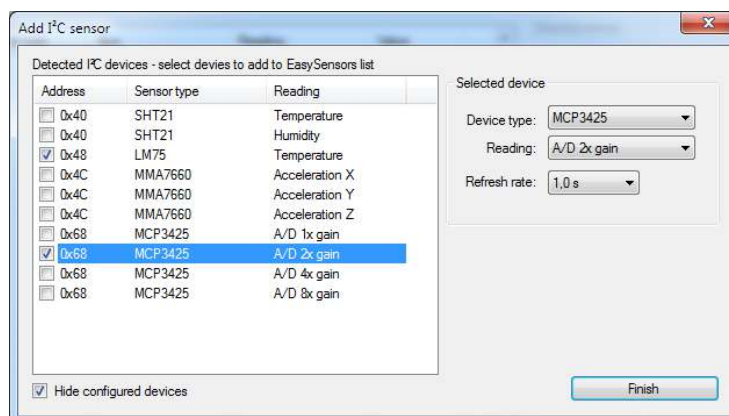


Figure 31: Scanning for I²C sensors

Scan for 1-wire sensors

The command opens the 'Add 1-Wire sensor' dialog that allows the user to select PoKeys pin, where the 1-Wire bus is connected to. By clicking 'Scan', PoKeys device scans the 1-Wire bus for devices. The EasySensors 1-wire bus implementation can detect multiple 1-Wire devices on the bus at once and thus simplifying the configuration process.

The list of available devices is then shown in the 'Detected devices' list (if 'Hide configured devices' option is selected, already configured 1-Wire devices are not displayed in the list). On the right side, reading type and refresh rate of the selected sensor can be configured.

To add the sensor to the EasySensors list, check the checkbox of the sensor in the list and click 'Finish'.

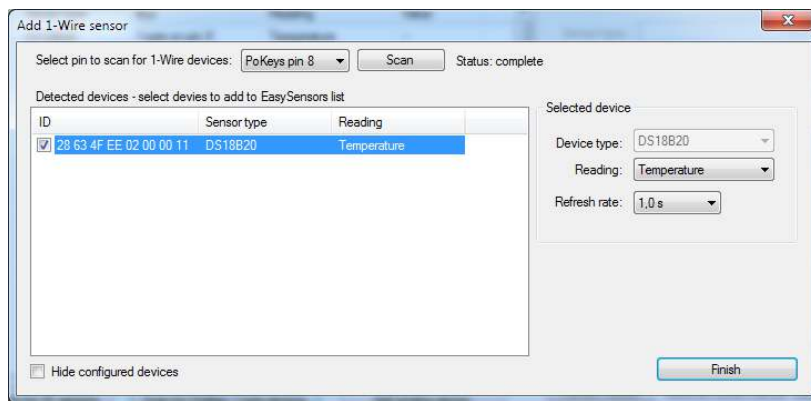


Figure 32: Scanning for I²C sensors

Add DHTxx 1-Wire sensor

Three types of DHTxx 1-Wire sensors are supported by PoKeys device (sensors differ in temperature and humidity resolution and accuracy). Any of the available PoKeys pins can be selected as DHTxx 1-Wire bus, but only one sensor can be connected per pin.

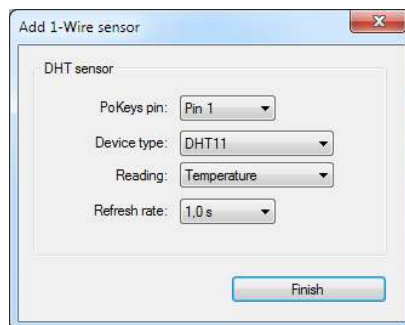


Figure 33: Adding the DHTxx 1-Wire sensor

Add analog sensor

EasySensors feature supports reading of simple analog sensors connected to PoKeys analog inputs. A linear transformation is applied to analog input reading to produce the sensor value. There are two possible ways to set up the sensor

- a) Using gain and offset: specify the gain and offset characteristics of the sensor. The gain specifies the number of sensor units per 1 V of analog voltage, while the offset specifies the sensor value of analog voltage input of zero.

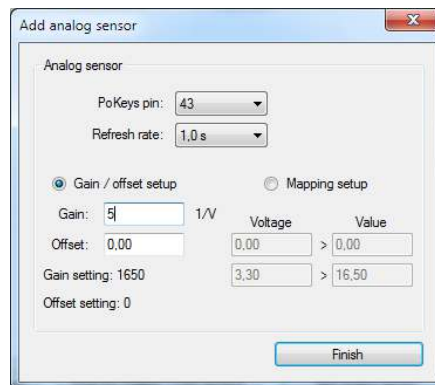


Figure 34: Analog sensor setup with gain / offset option

- b) Using two point mapping: in this mode, two sensor values with corresponding analog voltage must be entered into the fields provided. Gain and offset of the sensor are automatically calculated.

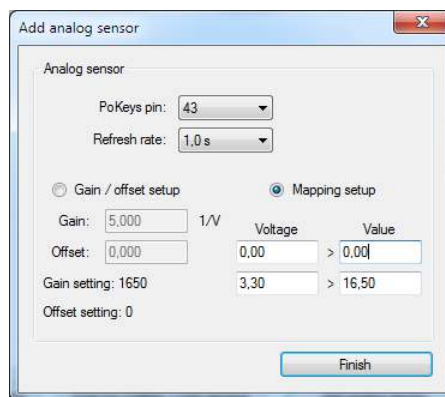


Figure 35: Analog sensor setup with mapping

Analog sensors use the following formula to convert the analog input voltage into sensor reading

$$u = AD_{val} * \frac{A_{gain}}{4096} + A_{offset}$$

where AD_{val} is a measurement of the analog-to-digital converter (a value between 0 and 4095), A_{gain} is gain (32-bit integer number) and A_{offset} is result offset (32-bit integer number). The value of u is a integer number that gets divided by 100 for the display (the temperature of 15.58 °C is represented by $u = 1558$). A gain of 330 therefore gives the true voltage on the analog input pin. The analog sensor dialog shows the gain and offset settings in the bottom left corner of the dialog and should not be confused with Gain and Offset setup parameters.

List of supported sensors

- LM75 (Maxim, TI, NXP) temperature sensor for the temperature range -55 °C to +125 °C with the resolution of 0.5 °C. The sensor has configurable address and up to 8 sensors can be connected.
- SHT21 (Sensirion) temperature and humidity sensor for the temperature range -40 °C to +125 °C with the resolution of 0.01 °C and air relative humidity in range 0 to 100 %.
- Si7020 (SiLabs) air temperature and relative humidity sensor
- Si1141 (SiLabs) IR and visible light intensity and reflection
- MCP3425 (Microchip) A/D converter with selectable gain
- MCP9600 (Microchip) thermocouple to temperature converter
- iAQ-Core C (AMS) indoor air quality module, measures VOC (volatile organic compound) and CO₂ levels
- MMA7660 (NXP) 3-axis accelerometer
- LIS2DH12 (ST) 3-axis accelerometer
- BH1750 (Rohm) light sensor
- BME280 (Bosch) air temperature, relative humidity and absolute pressure
- ADS1115 (TI) 16-bit 4-channel A/D converter with selectable gain (up to 16x)
- DS18B20 (Maxim) temperature sensor for the temperature range of -55 °C to +125 °C with the resolution of 0.0625 °C. As each sensor has its own unique sequence ID, up to 10 sensors can be connected to PoKeys.
- DS18S20 (Maxim) temperature sensor
- DS2413 (Maxim) GPIO inputs
- DHT11, DHT21 and DHT22 (AM2302) temperature and humidity sensors

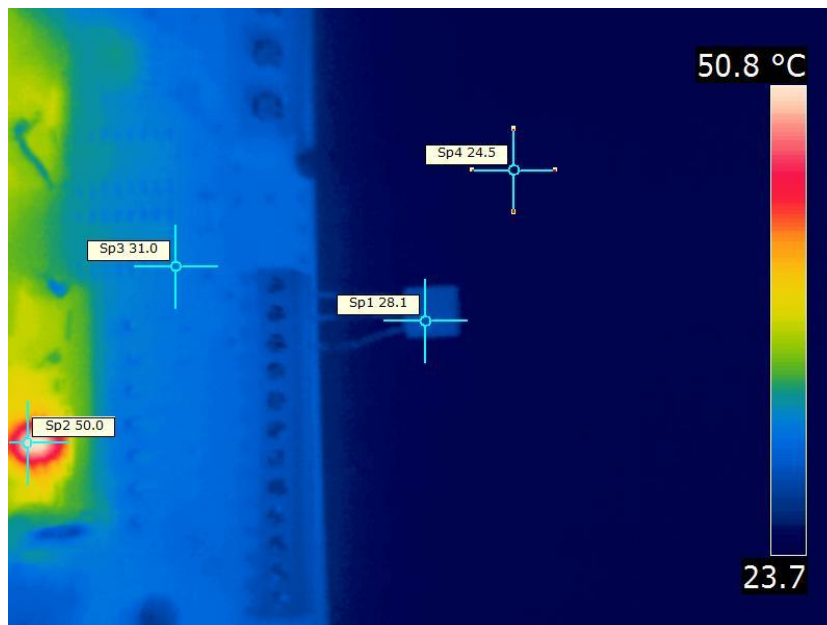


Figure 36: Thermal image of a temperature sensor being connected directly to a circuit board. The thermal conductivity of the sensor's leads causes the sensor to register higher temperature than the ambient real temperature. Use properly longer connections between sensor and sensor host board for the accurate readings

7.15. USB interface configuration

The operation of the USB PoKeys devices can be adjusted in the Device > USB interface', as shown on the figure below.

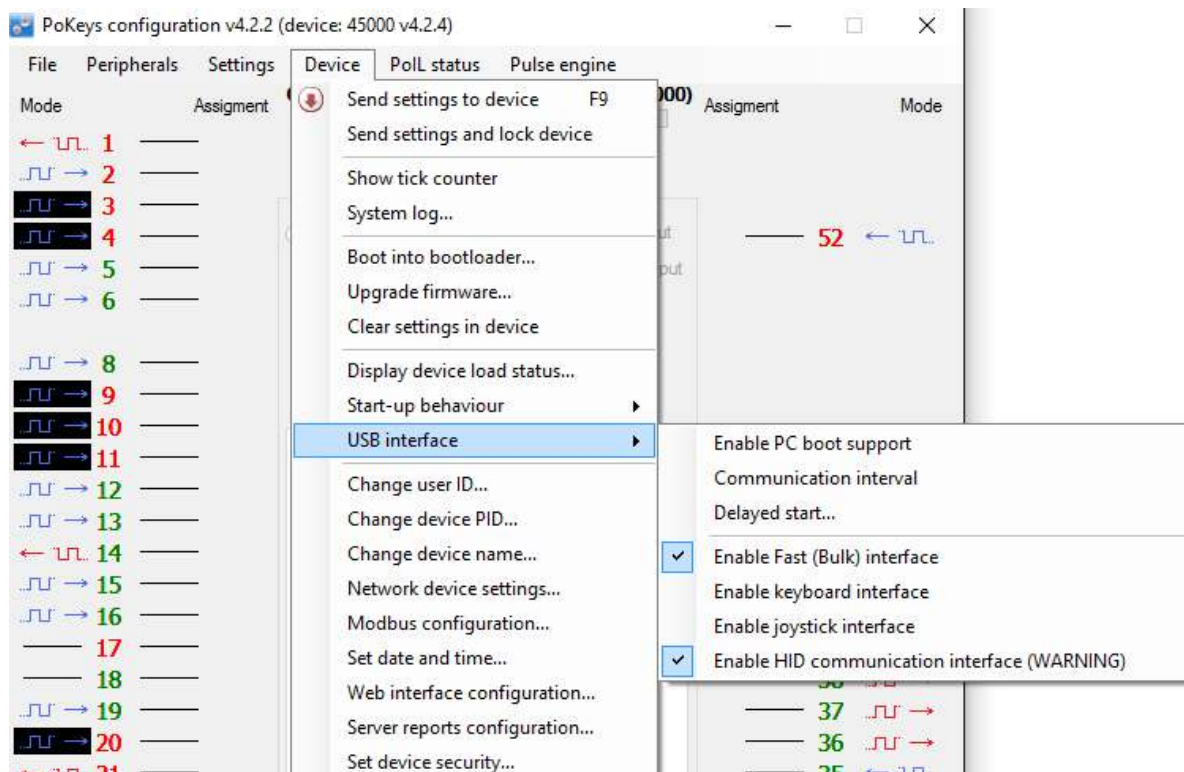


Figure 37: Accessing USB interface options

By adjusting these options, the user is given the possibility to configure how device reacts on the system start, change the communication interval and configure which interfaces are visible to the system. In some situations, omitting the unused interfaces can result in achieving better performance of the device due to lower load to the system drivers.

Start options

USB PoKeys devices can be configured to either report the support for boot operation or not. Some PC BIOS versions have problems configuring non-simple (plain keyboard and mouse) devices and may halt the boot sequence if such device is present. By omitting the PC boot support, this is usually overcome.

If this however does not fix the problems during the boot sequence, delayed start option give the possibility to delay the PoKeys device registration on USB for the predetermined delay, which will result in BIOS not detecting the device and continuing the boot sequence. Adjust the value according to your system in this case.

Communication interval

By default, PoKeys USB devices use 1 millisecond communication interval for the communication interface. If for any reason slower communication is required, it can be adjusted using the Communication interval settings dialog. Communication intervals between 1 millisecond and 20 milliseconds can be configured.

Enabling/disabling the interfaces

Each USB PoKeys device uses 4 USB interfaces (i.e. USB devices) and thus appears as 'USB Composite Device' in the Device manager. If not needed, some (or all) interfaces can be disabled.

Note: if all communication interfaces are disabled, configuration of the device will no longer be possible. In that case, follow the instructions in the section 'Restoring factory defaults' to restore the device's functionality.

7.16. Network device functionality

PoKeys57CNC device can be connected to Ethernet 10/100 network with standard RJ-45 cable.

By default, the device is set to use the DHCP functionality of the network router. User can later turn on or off the DHCP support. If DHCP is not required or available, fixed IP address must be defined for the device. To set the network settings of the device, go to Device menu and click Network device settings...



Figure 38: Device network settings

The device communicates using TCP and UDP port of 20055. **Please ensure the firewall settings allow communication with this port. Also, please make sure that your network card (which you have connected the PoKeys device to) has an IP address assigned with the subnet mask 255.255.255.0 (check it in IPv4 settings in your system).**

By default, PoKeys device is configured to close the connection with the host after 3 seconds of inactivity. This connection timeout value can be set in the dialog, shown in Figure 38.

Device discovery

Unless PoKeys device is configured with a fixed IP address or static DHCP lease option is enabled on the router, user has no direct display of what IP the PoKeys device is configured or assigned with. Therefore, PoKeys device feature an automatic discovery mechanism that uses discovery packets sent from software looking for PoKeys device and discovery response packets that PoKeys device constructs as an answer to a discovery. The discovery response packet contains vital PoKeys device information that can be used to identify and find the PoKeys device in the network.

In case the DHCP server is not available in the network or if discovery packet was received from different subnet than the one used by PoKeys device, the device will change to a temporary IP address from the same subnet (defaulting to 255.255.255.0 subnet mask) that the request was sent from. This temporary address can be recognized by ending in .250 and should only be used to find a misconfigured device and setup it with proper network configuration. The discovery process can be disabled under Device > Network device settings by clicking 'Advanced' button.

More information on this mechanism can be found in the Protocol specification document.

Default network settings

| | |
|------------------|----------------|
| DHCP: | enabled |
| Port: | 20055 |
| Security: | Full access |

Connecting to device in other network

When the device is not detected automatically (either there is a firewall blocking the UDP broadcast messages or the device is not in the same network as a computer), custom IP address of the device can be entered by clicking on the 'Network settings...' button on the 'Connect to device' dialog. The following dialog appears.

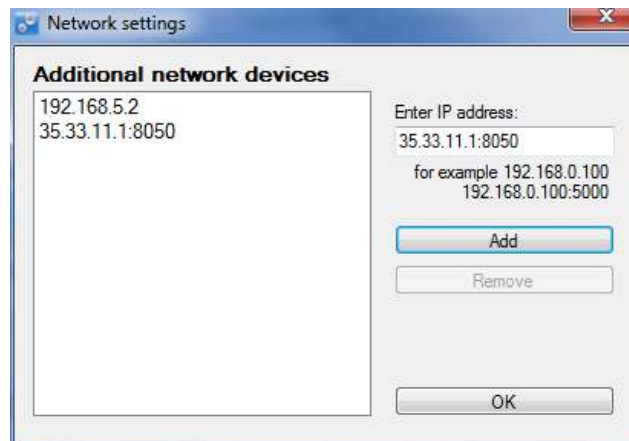


Figure 39: Additional network settings

IP address of the device can be entered in the text box on the right and added to the list by clicking the button 'Add'. The list of additional devices is saved on application exit.

Security

Due to exposed nature of a network device, an authentication mechanism was implemented in network PoKeys that allows three levels of access rights:

- Full access (default): the device is fully accessible from the network
- Read-only access: unauthorized users are allowed only to fetch a limited set of data from the device, while an authenticated users can access all functions of the device
- Full lock: unauthorised users can not neither read or write to the device. A user password is required to unlock access.

The security is set up in PoKeys configuration software – on the Device menu, click Set device security... The password can contain any character and can be up to 32 characters long.



Figure 40: Device security settings window

Web interface (dashboard)

Network PoKeys devices can be monitored through the simple web interface (that is already enabled by default).

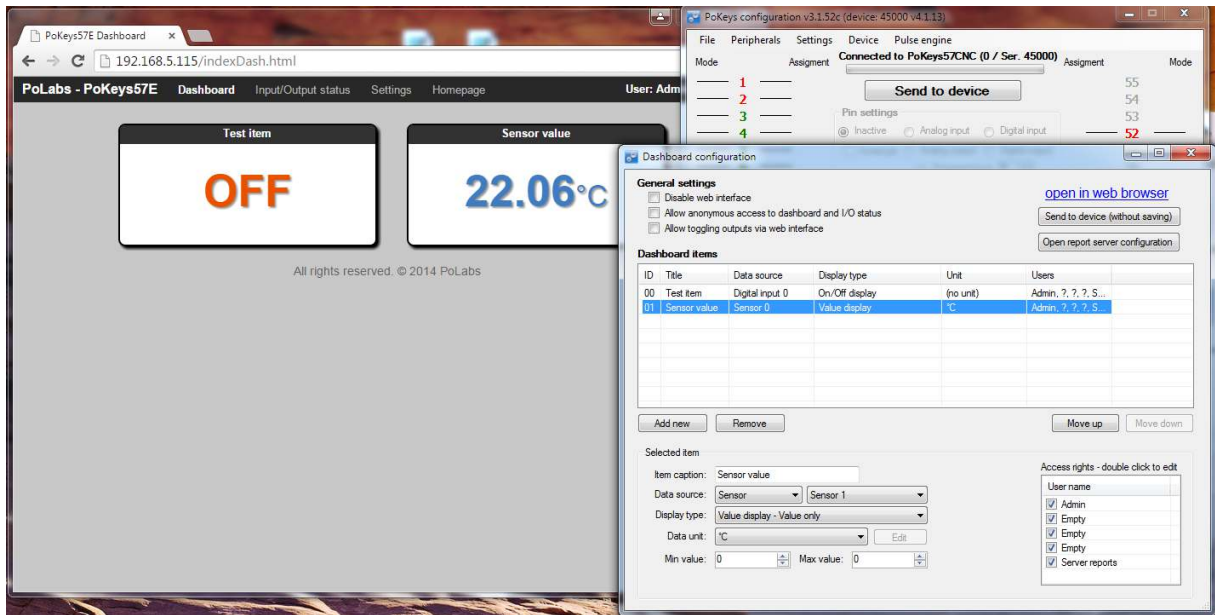


Figure 41: PoKeys device web interface

The interface can be disabled or configured in dialog accessible via menu Device->Web interface configuration. The following dialog appears

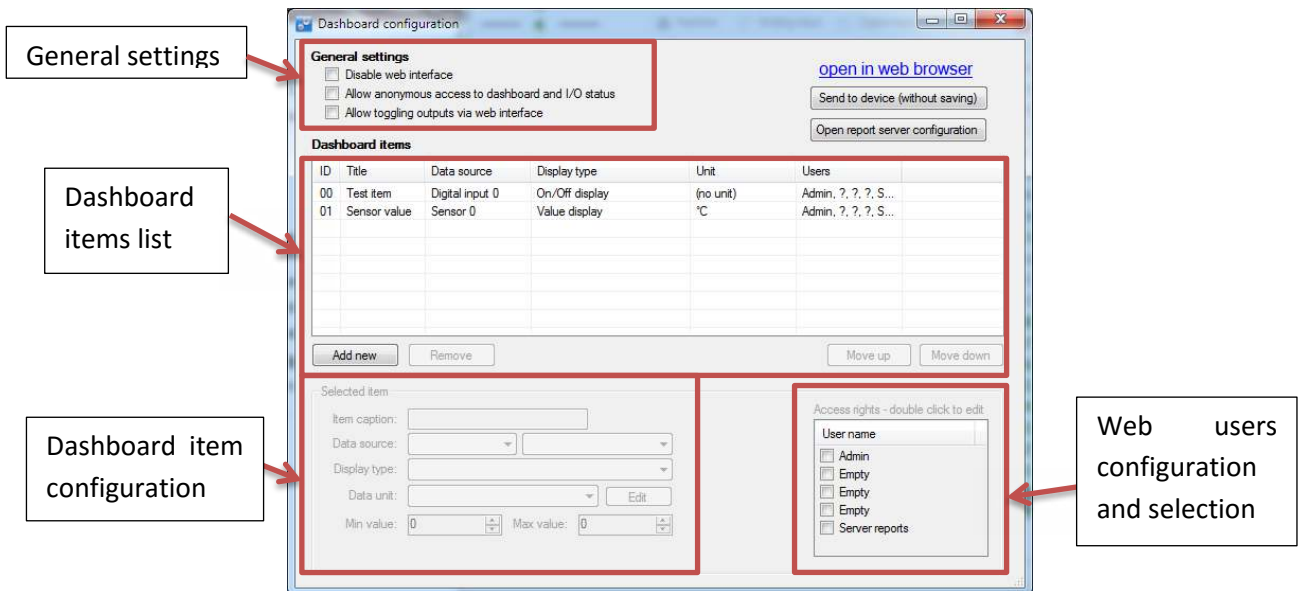


Figure 42: Web interface settings – Dashboard configuration

The dialog presents the following three options in the upper left corner:

- Disable web interface: check this field to disable web interface.
- Allow anonymous access to dashboard and I/O status: if this field is checked, users can access web interface directly without entering user name and password.

- Allow toggling outputs via web interface: if this field is checked, users can toggle the pins that are setup as outputs. If this field is unchecked, users are only presented with the status of each pin.

Dashboard items configuration

Up to 100 dashboard items can be configured. In order to add a new item, click on 'Add new' and enter the item information in the fields below ('Selected item' settings).

| Selected item | |
|---------------|----------------------------|
| Item caption: | Sensor value |
| Data source: | Sensor Sensor 1 |
| Display type: | Value display - Value only |
| Data unit: | °C Edit |
| Min value: | 0 |
| Max value: | 0 |

| Access rights - double click to edit | |
|--|--|
| User name | |
| <input checked="" type="checkbox"/> Admin | |
| <input checked="" type="checkbox"/> Empty | |
| <input checked="" type="checkbox"/> Empty | |
| <input checked="" type="checkbox"/> Empty | |
| <input checked="" type="checkbox"/> Server reports | |

Figure 43: Dashboard item configuration

The following settings are available for each item:

- Item caption: a string of up to 13 characters describing the item (note: some web services have limitations on what characters can be used - the software will provide you with a warning if incorrect characters are used)
- Data source: select the data source from available sources (digital inputs or outputs, PoExtBus outputs, Sensors, digital counters, PoIL shared slot data) with respective index of the item from the second list
- Display type: there are different display type options available based on the data source type. The digital signals can be represented by ON/OFF value with optional On/Off or On/Off/Toggle buttons. The (analog) value signals can be represented by numeric value display with optional bar graph. The numeric value can be made editable - double-click on the displayed value shows an editor box, that allows the user to enter a new value, which is sent back to device (for use with PoIL shared data values).
- Data unit: the PoKeys device comes preconfigured with a variety of data units. If the desired unit is missing from the list, up to 20 custom units can be configured.
- Min/max value: use the minimum and maximum value boxes to set the values for the bar graph boundaries.
- Access rights: select users from the list that should have access to the selected item.

Custom unit editing

PoKeys device contains 20 custom units that allow the user to setup additional units if needed. Since the units are displayed on a dashboard in a web browser, HTML code for the unit can be entered, allowing different text formatting.



Figure 44: Custom unit editor

Managing the web user accounts

The dashboard configuration dialog contains a list of available users. To edit the user, double-click on the entry in the list - a 'User account' dialog will pop up, allowing the changes to user name and password.

By default, PoKeys contains a user named 'Admin' with password set to 'root0'. Both the username and password of this user can also be changed.

Usernames and passwords can be configured for up to 4 users with the length of each limited to 8 (ASCII) characters.

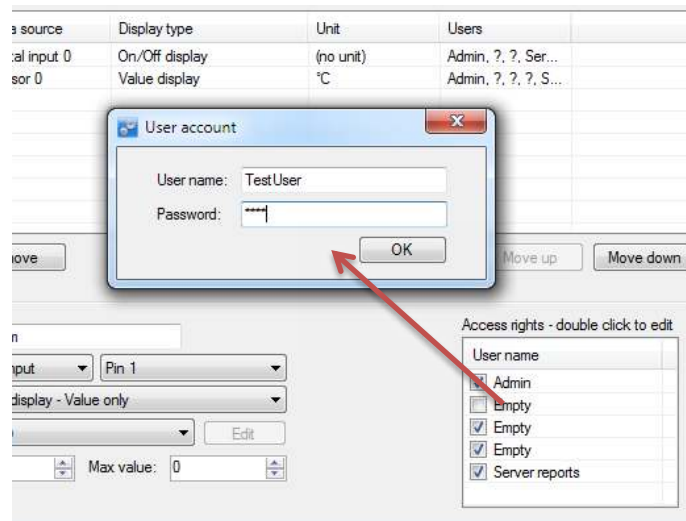


Figure 45: Editing user account

Accessing the dashboard items data

The information on dashboard items data and their values can be accessed by fetching the following files from the device:

- devStat.xml: contains values of all digital inputs and outputs, encoder values, analog inputs, sensors, PoIL shared data values and digital counters

- devData.xml: information on the PoKeys device (network configuration and some other device data)
- sensorList.xml*: contains information on dashboard items configuration and value
- sensorList.json*: same as above, but in json format
- setS.html*: is used to change the sensor value
- setDO.html: is used to change digital output value

The setS.html and setDO.html have the following syntax

http://<IP address>/setDO.html?Pin=<Pin ID>&State=<0/1/T>&u=<Username>&p=<Password>
 http://<IP address> /setS.html?Sensor=<Item ID>&State=<Value>&u=<Username>&p=<Password>

The <Pin ID> is 1-based PoKeys pin index (same as indicated on the device), while <Item ID> is 0-based dashboard item index of the current user.

Modbus

PoKeys57CNC device supports slave (server) operation of Modbus TCP communication protocol. Modbus TCP compatible devices on the network can read the values from the device and set the outputs. To elevate the security, user can define which peripherals are accessible via Modbus TCP.

Modbus TCP uses TCP protocol on port 502 (default), which can be changed in Modbus settings (accessible from the menu Device – Modbus configuration...). The Modbus TCP connection is disconnected after 3 seconds of inactivity (this default value can be changed in the Modbus settings).

Discrete inputs/outputs

Supported operations:

- 0x01: Read coils
- 0x02: Read discrete input
- 0x05: Write single coil
- 0x0F: Write multiple coils

| Address (0-based) | Access (R – Read, W – Write) | Description |
|--------------------------------------|------------------------------|--|
| 0-54 | R/W | 55 pin inputs/outputs |
| 100-126 (100-149 on PoKeys57 series) | R | Sensor OK statuses |
| 200-263 | R/W | PoIL shared data (binary data) - overlapped with 32-bit PoIL shared data at 1000-1127 (16-bit) |
| 1000-1127 | R | Matrix keyboard inputs |
| 1400-1527 | W | I2C Matrix keyboard LED |
| 1600-1727 | R/W | LED matrix |
| 2000-2079 | R/W | PoExtBus |
| 2000 | | Device 10 – Output H |
| 2001 | | Device 10 – Output G |
| ... | | |
| 2079 | | Device 1 – Output A |

Registers

Supported operations:

0x03: Read holding register

0x04: Read input register

0x06: Write single register

0x10: Write multiple registers

| Address (0-based) | Access (R – Read, W – Write) | Description |
|--------------------------------------|------------------------------|---|
| 0-1 | R | Serial number of the device (PoKeys57 only) |
| 10-16 | R | Analog inputs |
| 20-45 | RW | Encoder counter values (lower 16-bit) |
| 100-154 | RW | Digital counter values |
| 200-213 | RW | PWM |
| 200,201 | | PWM period (MSB first) |
| 202,203 | | PWM duty1 (MSB first) – pin 22 |
| ... | | |
| 212,213 | | PWM duty6 (MSB first) – pin 17 |
| 300-304 | RW | PoExtBus |
| 400-453 (400-499 on PoKeys57 series) | R | Sensors (32-bit values, LSB first) |
| 500-579 | RW | LCD buffer |
| 590 | W | LCD configuration (0=disabled, 1=primary or 2=secondary) - writing to this register will re-init and clear the LCD |
| 591 | W | Number of rows (lower byte) and number of columns (upper byte) of the LCD module |
| 592 | W | Not used |
| 593 | W | Clear LCD (both bytes = 0xAA) |
| 600 | R | Tick counter (lower 16-bit) |
| 700-751 | R[W] | Digital encoder values (32-bit values, LSB first) - any write to these registers causes the reset of the encoder value to 0 |
| 800-909 | RW | Digital counter values (32-bit values, LSB first) |
| 1000-1127 | RW | PoIL shared data (32-bit, LSB first) |

PoExtBus channel mapping:

| Address (0-based) | Register description | | | | | | | | | | | | | | | |
|-------------------|----------------------|---|---|---|---|---|---|---|----------|---|---|---|---|---|---|---|
| 300 | A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H |
| | Device 10 | | | | | | | | Device 9 | | | | | | | |
| 301 | A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H |
| | Device 8 | | | | | | | | Device 7 | | | | | | | |
| 302 | A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H |
| | Device 6 | | | | | | | | Device 5 | | | | | | | |

| | | | | | | | | | | | | | | | | |
|-----|----------|---|---|---|---|---|---|---|----------|---|---|---|---|---|---|---|
| 303 | A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H |
| | Device 4 | | | | | | | | Device 3 | | | | | | | |
| 304 | A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H |
| | Device 2 | | | | | | | | Device 1 | | | | | | | |

where

| | | | | | | | | | | | | | | | | |
|-----------|----|----|----|----|----|---|---|----------|---|---|---|---|---|---|---|-----------------------------|
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Modbus word bit |
| A | B | C | D | E | F | G | H | A | B | C | D | E | F | G | H | PoExtBus device bit mapping |
| Device 10 | | | | | | | | Device 9 | | | | | | | | |

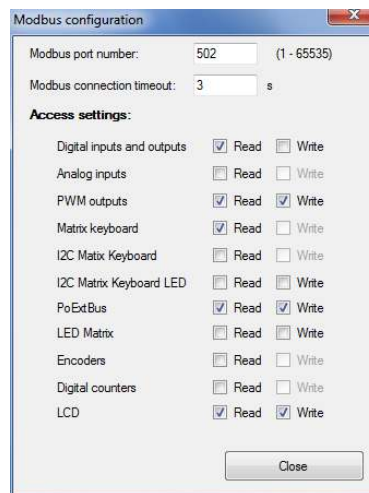


Figure 46: Modbus configuration

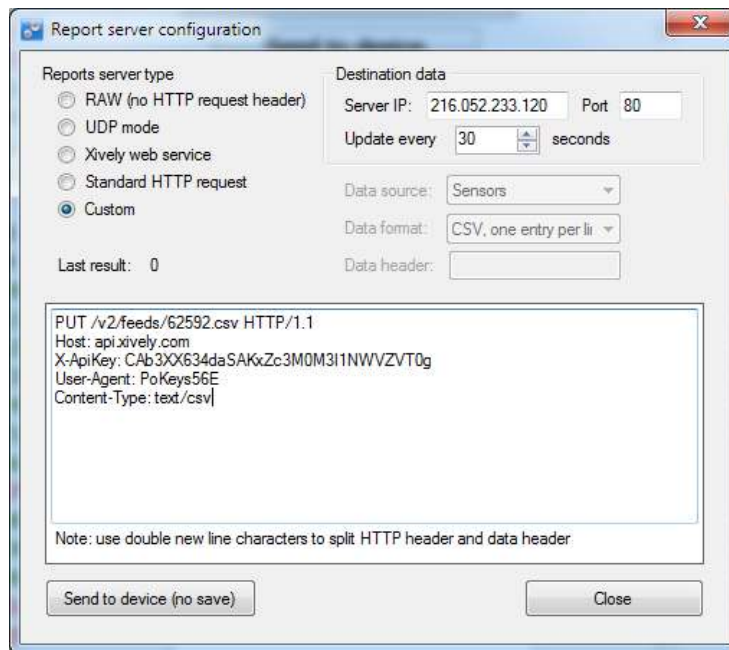
Reporting data to network server with PoKeys57CNC device

PoKeys57CNC devices can automatically report sensor values to various network servers using the HTTP POST, HTTP PUT or text-only protocols.

To use this reporting feature, user must specify reports type (RAW, UDP, Xively, Standard HTTP POST/PUT or custom), server IP, server port number and update rate.

Custom report type

The request header is constructed of two parts – HTML header and data header, divided by double new line character (\n). Example header (Xively.com web service):



```
PUT /v2/feeds/62592.csv HTTP/1.1
Host: api.xively.com
X-ApiKey:
CAb3XX634daSAKxZc3M0M3I1NwVZVT0g
User-Agent: PoKeys56E
Content-Type: text/csv
Content-Length: 010
Connection: close

Test1234,-15000.00
```

The HTTP header without 'Connection' and 'Content-length' tags must be provided by the user

The 'Connection' and 'Content-length' tags are automatically inserted by the PoKeys device

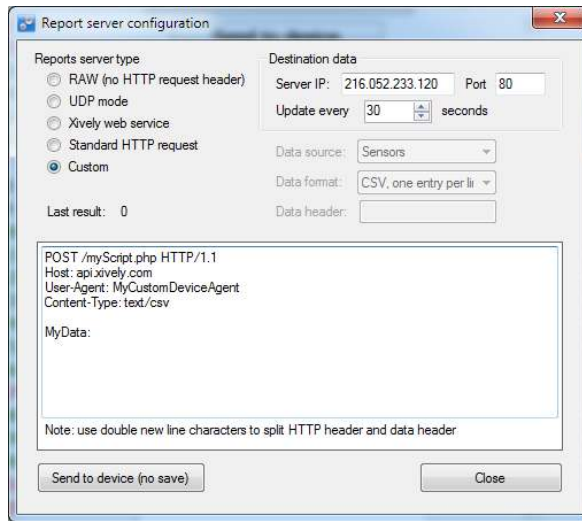
Data is inserted at the end of the packet

The above example is specified as

```
PUT /v2/feeds/62592.csv HTTP/1.1
Host: api.xively.com
X-ApiKey: CAb3XX634daSAKxZc3M0M3I1NwVZVT0g
User-Agent: PoKeys56E
Content-Type: text/csv
```

The extra new line at the end is essential.

More customized header:



```
POST /myScript.php HTTP/1.1
Host: api.xively.com
User-Agent: MyCustomDeviceAgent
Content-Type: text/csv
Content-Length: 010
Connection: close

MyData: Test1234,-15000.00
```

The HTTP header without 'Connection' and 'Content-length' tags must be provided by the user

The 'Connection' and 'Content-length' tags are automatically inserted by PoKeys device

The above example must be specified as

```
POST /myScript.php HTTP/1.1
Host: api.xively.com
User-Agent: MyCustomDeviceAgent
Content-Type: text/csv

MyData:
```

Again, an extra new line character in fifth line is essential.

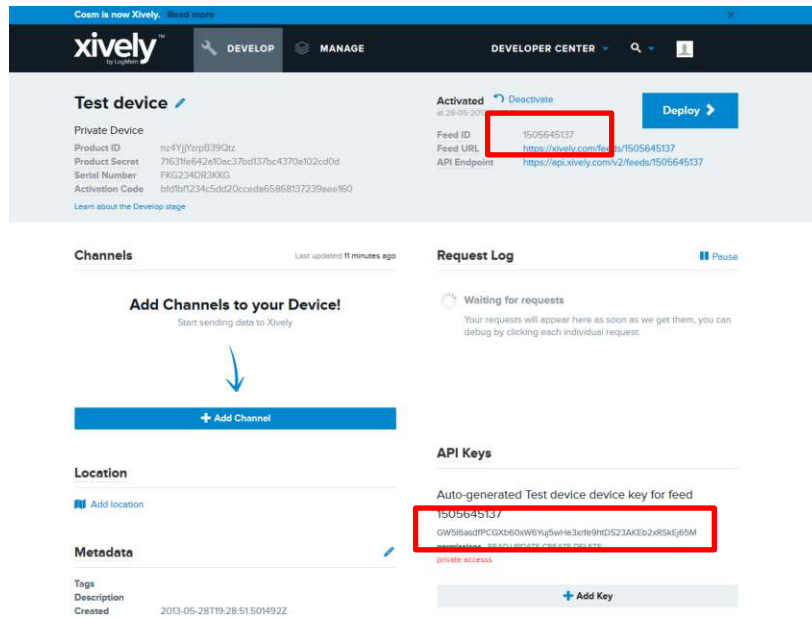
Total length of final header and data is limited to 350 bytes.

Setup for Xively web service

Xively web service is an on-line database service allowing users to connect sensor-derived data (eg. energy and environment data from objects) to the Web and to build their own applications based on that data.

PoKeys57CNC devices feature a direct support for the Xively web service. To configure PoKeys device for Xively, follow these steps:

1. Sign-up for a free account at <http://xively.com/>
2. Navigate to Develop and create a new private device
3. Under the created device information, you can find 'Feed ID' and 'API key' for your newly created device, as shown in the figure below.



4. Open Device > Server reports configuration. Check 'Xively web service' option.
5. Enter your Xively API key and Feed ID, created in step 3, leave other fields with default values

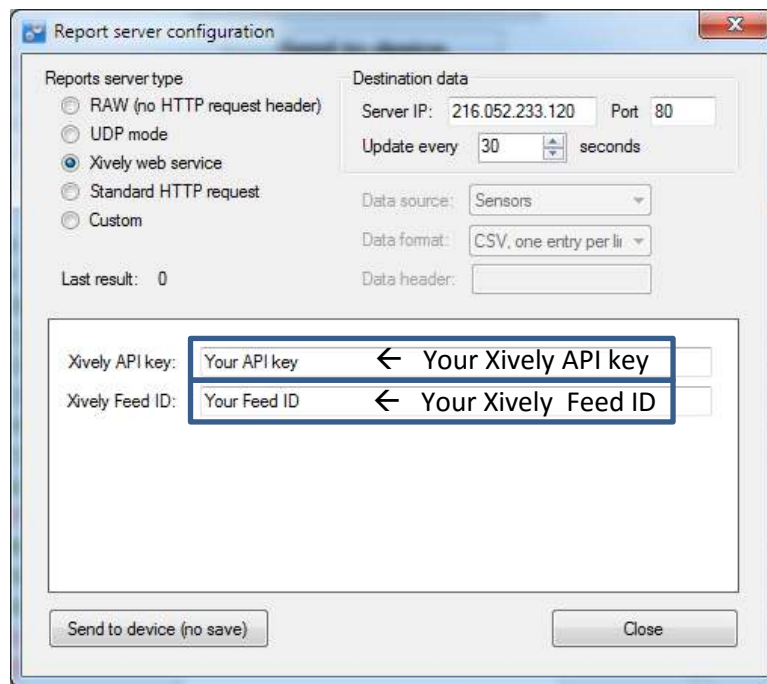


Figure 47: Reports server settings for Xively service

6. Select the update rate on the right
7. Click Send to device button. If you wish to save the settings to non-volatile memory, click 'Send to device' on main PoKeys screen.
8. Go back to Device > Web interface settings to edit the dashboard items. Define entries as described in the 'Web interface' chapter of this manual. To enable uploading of the

dashboard item to the Xively service, select 'Server reports' as the user. The 'Item caption' field is used to identify the datastream in the selected Xively feed.

Make sure that item caption does not contain any invalid characters for Xively channel name (+, -, _, letters and numbers are allowed)

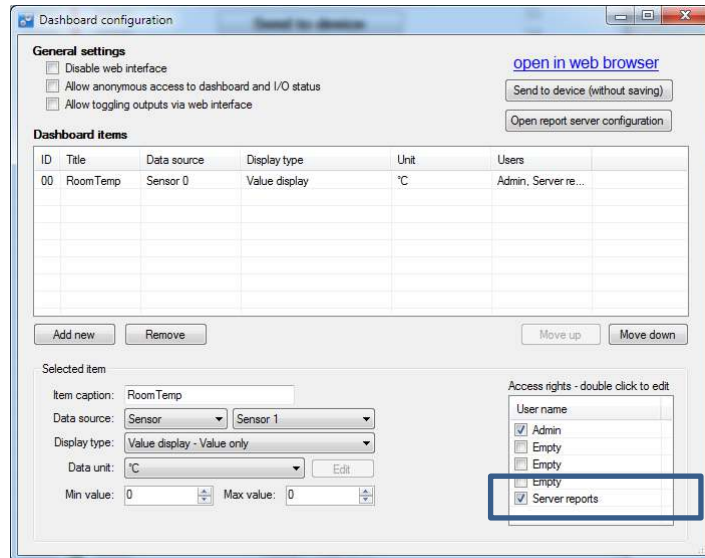
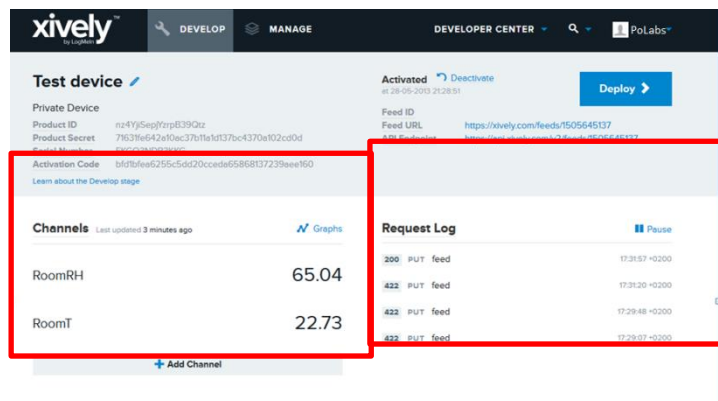


Figure 48: Item configuration for the Xively service

9. Save the settings again by clicking 'Send to device' button.
10. Make sure the PoKeys device has properly configured network settings and that it is connected to the internet
11. After a update interval, check the status of the Xively updates in the Xively 'Develop' page



12. Open your Xively feed by clicking the Feed URL – you should see the recorded data

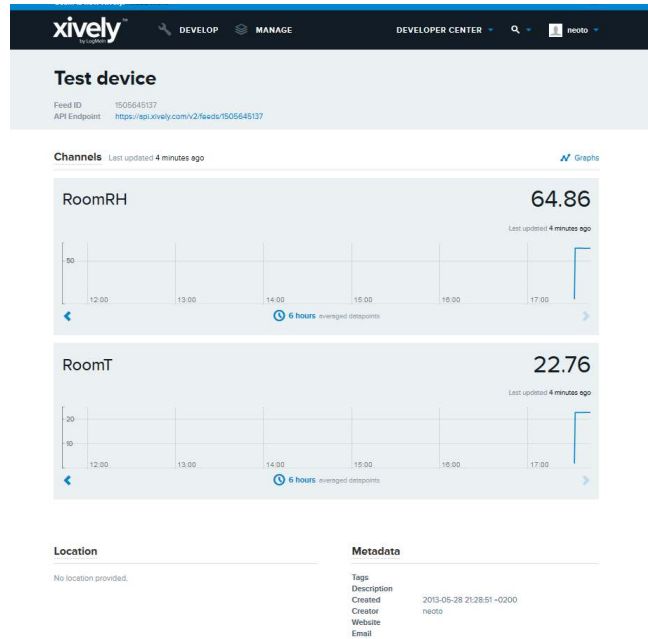


Figure 49: Xively feed overview page

Setup for standard HTTP POST or PUT data upload

Let's assume that the user wants to send sensor data to his server script that accepts POST method for data upload. The user's server script is available at the address www.userdomain.com/PoKeysDataUpload.asp. The user also wants that the data in the POST stream to have the HTTP type of 'text/plain' and preceded with the string 'MyData: '. The data should be transferred every 10 minutes. The settings are displayed in Figure 50.

To setup PoKeys to use these settings, the following steps must be taken (enter text without ' quotes):

1. Open Device > Server reports configuration.
2. Select 'Standard HTTP request' and check HTTP POST option
3. Enter 'www.userdomain.com/PoKeysDataUpload.asp' in the Destination field
4. Enter 'text/plain' in the 'Content-type' field.
5. Enter 'MyData: ' in the 'Data header' field
6. Enter the server's IP address and port number in the fields below.
7. Enter 600 in the update time field
8. Click Close and click Send to device button.
9. Go to Device > Web interface settings and define entries as described in the 'Web interface' chapter of this manual. To enable uploading of the dashboard item to the web server, select 'Server reports' as the user. The 'Item caption' field is used to identify the datastream.
10. Save the settings again by clicking 'Send to device' button.
11. Make sure the PoKeys device has properly configured network settings and that it is connected to the internet

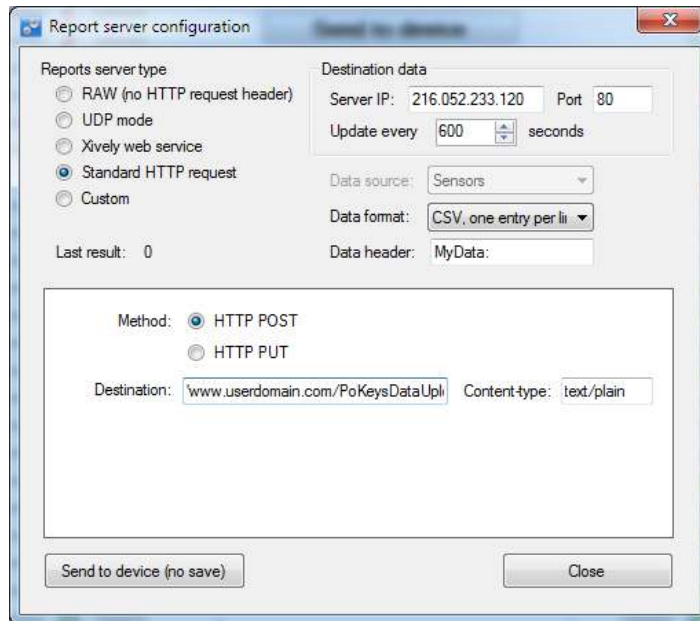


Figure 50: Example of HTTP POST service setup

7.17. Changing User ID number

Users can freely assign their own User ID number that represents a specific PoKeys device (enables distinguishing between different PoKeys devices in case there is more than one connected to a single host PC). To change the User ID number, go to 'Device' > 'Change user ID' menu. Simply enter any number between 0 and 255, and click the 'Change user ID' button.

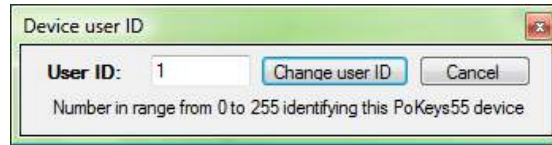


Figure 51: Device user ID dialog

7.18. Saving current configuration to file

To save the current configuration to a file, go to 'File' > 'Save' menu and select a new filename. To reload a saved configuration from a file, go to 'File' > 'Open' menu and select the appropriate file. To transfer new settings to the device, click on the 'Save to device' button.

7.19. PoIL core functionality

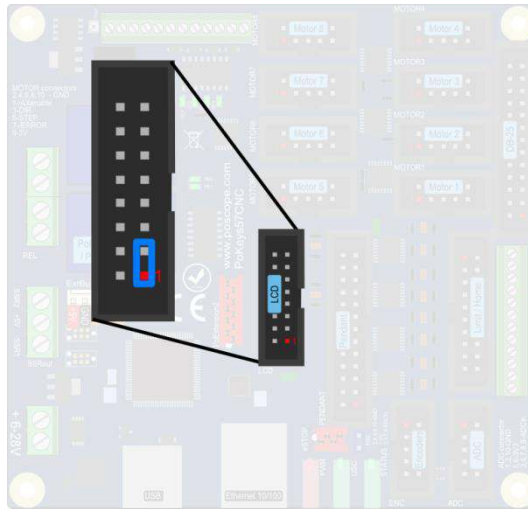
PoKeys57CNC contains PoIL core that is fully compatible with other PoKeys devices. Read the separate PoIL core documentation for more information.

Due to the omission of the 3V lithium backup battery, PoKeys57CNC does not support value retention in case of power failure.

8. Device recovery mode

If configuration editor cannot be used to reconfigure the device, use the following steps to start the device in the recovery mode. Recovery mode can be used to clear the configuration or update the firmware.

1. Disconnect PoKeys57CNC device from USB and remove power supply
2. Locate LCD connector on the PoKeys57CNC device and short the pins 1 and 3 as shown below



3. Reconnect the PoKeys device to USB (or reconnect power)
4. Green status light should start flashing rapidly and PoKeys device will connect in recovery mode
5. Open PoKeys configuration application
6. PoKeys configuration application should detect PoKeys57CNC device in recovery mode.
 - a. To reset the device configuration, use the option 'Clear settings'. By clicking this button and confirming your decision on the next dialog, settings will be erased.
 - b. To recover from bad firmware update, click 'Recover'.
7. After completing the operation, unplug PoKeys device and remove the short from the LCD connector
8. If resetting the configuration, ensure the device is properly cleared – replug PoKeys57CNC device, connect to it and execute Device > Clear settings in device.

9. Frequently asked questions

What software must be installed to operate the device?

On first use or when reconfiguring the device, the supplied software must be installed. If USB connection is to be used, device driver must be used that should be automatically installed by the setup package.

Can I use both USB and Ethernet connections?

Yes, both USB and Ethernet connections can be connected at the same time, but USB connection will have a priority over Ethernet.

Windows can not find drivers for PoKeys57CNC device

The drivers should automatically be installed by PoKeys setup package. If this is not the case and Windows reports unknown device, install the drivers manually by instructing the Windows device setup wizard to look for drivers in PoKeys installation folder (*C:\Program Files\PoLabs\PoKeys* by default).

I misconfigured the device and device no longer responds. What can I do?

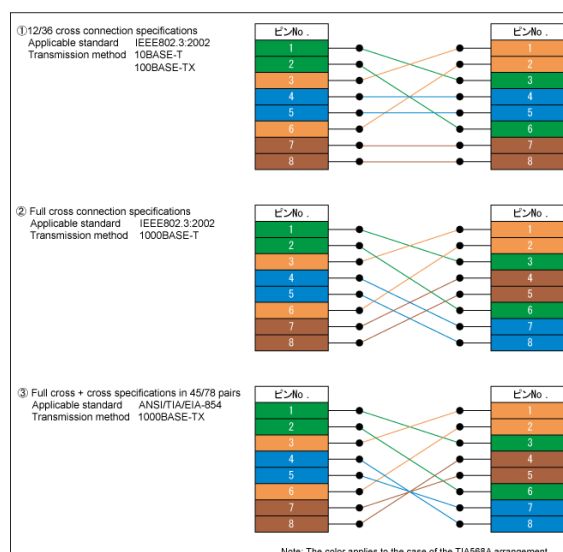
If you misconfigured the device in such a way that configuration utility cannot be used to repair the configuration, see the section 'Quick resetting the device configuration' in this manual.

There is spontaneous triggering of some of the pins. What is wrong?

Although the device implements basic noise filtering on the digital inputs, long wires between PoKeys device and switches can cause spontaneous triggering if those wires are located near high-power electrical wiring. Use twisted pair wires, shielding and try to route the signal wires away from power supply wires.

The connection with the PoKeys device cannot be established with 10BASE-T router

Please check that you are using proper cable that is supported by 10BASE-T standard. The following diagram shows the correct wiring for different connection standards.



(source: http://www.okidensen.co.jp/en/prod/cable/lan/img/cate6_n_fig05.gif)

10. Errata information

This section describes special limitations of the device.

PoKeys device resets when external power supply is applied or removed

If PoKeys device is connected to USB, the device resets when external power supply is either applied or removed.

External pull-up resistor needed on the probing input

On PoKeys57CNC v1.0, v1.1 and v1.2 hardware, external pull-up resistor is required for correct operation of the probing input.

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support: www.poscope.com



PoKeys Pulse engine v2 documentation

Version: 6/3/2016

SAFETY INFORMATION



This product is intended for integration by the user into a computer numerical control (CNC) machine. It is the user's responsibility to assess the overall system design and address all safety considerations that affect the users and equipment. The user assumes all responsibility for system design, including compliance with regulatory standards and codes issued by the applicable entities. PoLabs do not make any claims as to the suitability of this equipment for the user's application. Serious personal injury or equipment damage can occur from the improper integration, installation or operation of this product.

This product is not guaranteed to be fail-safe. The system that this equipment is used with shall be fitted with a separate means of fail-safe protection, emergency-stop capability and/or system power removal. This equipment may be connected to dangerous power sources, including electrical power sources. Dangerous voltage levels may be present at this equipment or at connected devices. Measures must be taken to prevent persons from contacting voltage sources which may be present. Equipment should be housed inside an enclosure suitable for the intended environment. Safety interlocks should be provided to prevent any and all dangers to personnel.

CNC machine tools are inherently dangerous, and can cause injury to operators and maintenance personnel. Operators and maintenance personnel shall be properly trained in the safe use, operation and maintenance of such machines. Automated machines that this equipment may be used with can move at any time. All persons exposed to such machines must understand the dangers that are present.

Description

PoKeys Pulse engine v2 (upgrade of the original PoKeys Pulse engine) is available on PoKeys56U, PoKeys56E and PoKeys57E devices and enables a direct control of a positioning systems that accepts step/direction signals (stepper motors, servo systems, etc.). PoKeys Pulse engine can operate in standalone (rapid positioning and speed control mode, homing, probing) or in slave mode (under the commands of the PC application). Each axis supports two end (limit) switch inputs, one home (reference position) switch input, which can be either a dedicated one or shared with limit switch inputs. All inputs can be fully configurable (input polarity, placement) using the PoKeys protocol (used by PoKeys application or a third party application for motion control).

In addition, operations in each axis can be limited using the soft limit function, where minimum and maximum permissible axis position is specified - once enabled, the axis is put to a stop when exceeding the allowed range, but is free to move in other direction.

Each axis can be assigned a different encoder with a customizable multiplication factor for the operation with MPG (manual pulse generator).

PoKeys Pulse engine also supports a dedicated emergency switch input, which stops the pulse generation.

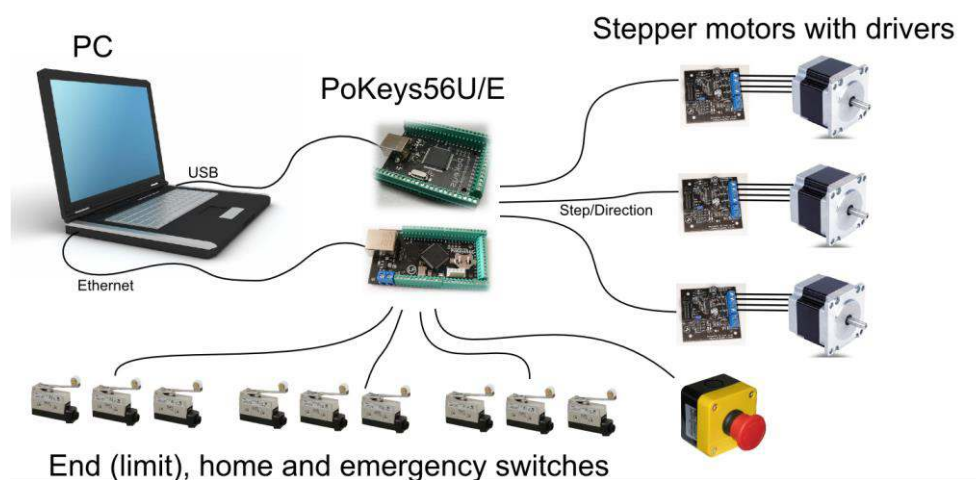


Figure 1: PoKeys Pulse engine connections for use with the integrated pulse generator

PoKeys Pulse engine v2 documentation

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Pulse generator selection

Pulse engine supports different pulse generators:

- Integrated pulse generator (for up to 3 stepper motors with step frequencies up to 25 kHz)
- External pulse generator without dedicated IO capabilities (for up to 8 stepper motors with step frequencies up to 125 kHz) using PoExtensionOC16 or third-party custom board.
- External pulse generator with dedicated IO capabilities (for up to 8 stepper motors with step frequencies up to 125 kHz, dedicated limit+, limit-, home/ref, axis error inputs, 3 relay outputs, 4 open-collector outputs, 0-10 V output) using PoKeysCNCadd-on (pictured below). PoKeysCNCadd-on inputs and outputs are galvanically isolated from PoKeys board.

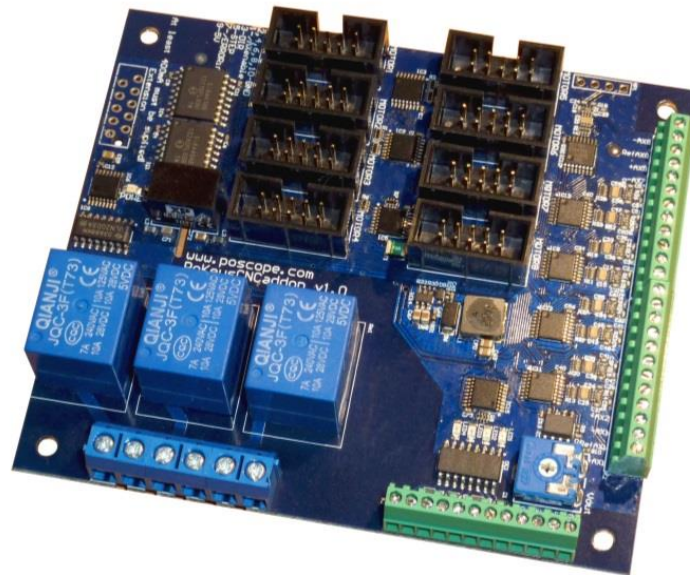


Figure 2: PoKeysCNCadd-on v1.0

PoKeys device pins in use

Integrated pulse generator - up to 3 axes at 25 kHz step frequency

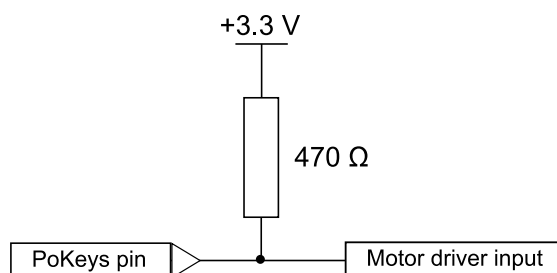
| Pin | Function |
|------|---|
| 38 | Direction output – x |
| 39 | Direction output – y |
| 40 | Direction output – z |
| 46 ! | Step output – x |
| 48 ! | Step output – y (external 470 Ω pull-up resistor required) |
| 49 ! | Step output – z (external 470 Ω pull-up resistor needed) |
| 52 | Emergency switch input |
| 53 | Safety charge pump 5 kHz output |

Inputs for limit, home and probing switches can be freely connected to any PoKeys pin and configured in software.

Remarks:

- **Watch for pin 47! It is not used for step output!**
- **All switch inputs expect normally closed (NC) switches and must be connected between specified PoKeys input pin and ground.**
- **We advise adding an additional 1 k Ω pull-up resistor on pins with an external switch**
- **Emergency switch must be connected in such way so that it cuts the power supply to the motors when the switch is activated.**

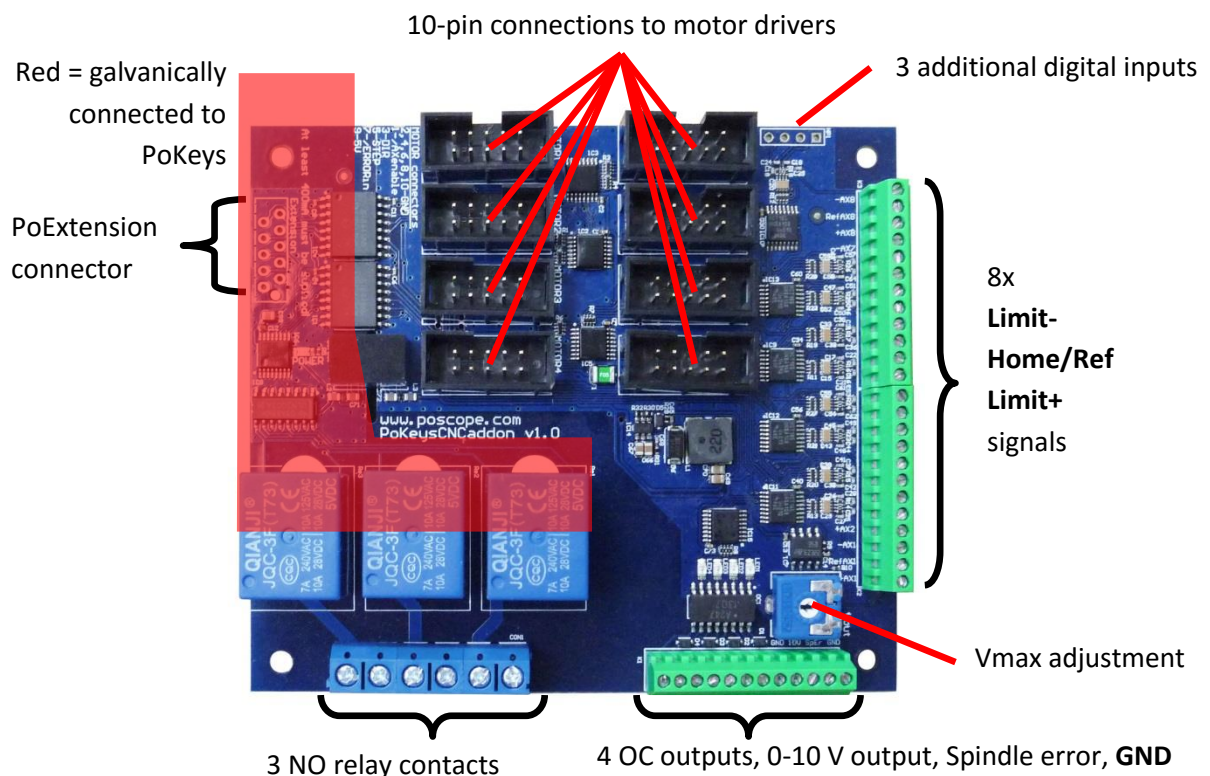
External pull-up resistor wiring for pins 48 and 49



External pulse generator with dedicated IO capability - up to 8 axes at 125 kHz step frequency¹

Please pay attention to connecting the PoKeysCNCaddon to PoKeys device. PoKeysCNCaddon connects to PoKeys using the Expansion port flat cable, attached to the board. The Expansion port signals should be connected to PoKeys as follows:

| Pin | Description | PoKeys56U pin | PoKeys56E/57E pin |
|----------------|---|------------------|----------------------|
| 1 (red) | 5 V power supply to the PoKeysCNCaddon - must supply at least 400 mA for correct operation | 5 V | 5 V |
| 2 | PoKeys ground (<i>not to be used for PoKeysCNCaddon IO</i>) | GND | GND |
| 3 | PWM signal for 0-10 V output | 17-22 | 17-22 |
| 4 | Signal for IO capabilities (output) | 38 | 38 |
| 5 | Signal for IO capabilities (output) | 37 | 37 |
| 6 | Signal for IO capabilities (output) | 36 | 36 |
| 7 | Signal for IO capabilities (input) | 35 | 35 |
| 8 | Signal for pulse generation | 23 | 9 |
| 9 | Signal for pulse generation | 25 | 11 |
| 10 | Signal for pulse generation | 26 | 51 |

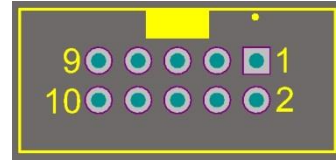


¹ Note that PoKeys Mach3 plugin supports only 4 axes

PoKeys Pulse engine v2 documentation

10-pin motor driver connector pinout

| Pin | Function |
|----------------|--------------------|
| 1 | Axis enable output |
| 3 | Direction output |
| 5 | Step output |
| 7 | Error input |
| 2, 4, 6, 8, 10 | GND |
| 9 | Not connected |



Dedicated axis switch inputs

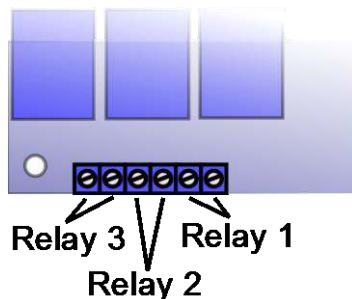
All inputs have built-in pull-up resistor - switches must be connected between **GND (on the PoKeysCNCaddon)** and the corresponding input. Select 'Dedicated pin' in the axis settings.

| | |
|--------|--|
| -AX8 | |
| RefAX8 | |
| +AX8 | |
| -AX7 | |
| RefAX7 | |
| +AX7 | |
| -AX6 | |
| RefAX6 | |
| +AX6 | |
| -AX5 | |
| RefAX5 | |
| +AX5 | |
| -AX4 | |
| RefAX4 | |
| +AX4 | |
| -AX3 | |
| RefAX3 | |
| +AX3 | |
| -AX2 | |
| RefAX2 | |
| +AX2 | |
| -AX1 | |
| RefAX1 | |
| +AX1 | |

| Pin (from top) | Function |
|----------------|---------------------|
| -AX8 | Limit- for axis 8 |
| RefAX8 | Ref/home for axis 8 |
| +AX8 | Limit+ for axis 8 |
| -AX7 | Limit- for axis 7 |
| RefAX7 | Ref/home for axis 7 |
| +AX7 | Limit+ for axis 7 |
| -AX6 | Limit- for axis 6 |
| RefAX6 | Ref/home for axis 6 |
| +AX6 | Limit+ for axis 6 |
| -AX5 | Limit- for axis 5 |
| RefAX5 | Ref/home for axis 5 |
| +AX5 | Limit+ for axis 5 |

| Pin (continued) | Function |
|-----------------|---------------------|
| -AX4 | Limit- for axis 4 |
| RefAX4 | Ref/home for axis 4 |
| +AX4 | Limit+ for axis 4 |
| -AX3 | Limit- for axis 3 |
| RefAX3 | Ref/home for axis 3 |
| +AX3 | Limit+ for axis 3 |
| -AX2 | Limit- for axis 2 |
| RefAX2 | Ref/home for axis 2 |
| +AX2 | Limit+ for axis 2 |
| -AX1 | Limit- for axis 1 |
| RefAX1 | Ref/home for axis 1 |
| +AX1 | Limit+ for axis 1 |

Relay outputs



PoKeysCNCaddon board features 3 relay outputs with normally-open contacts.

Rating:

- max. 7A/240VAC, max. 10A/125VAC or max. 10A/28VDC.

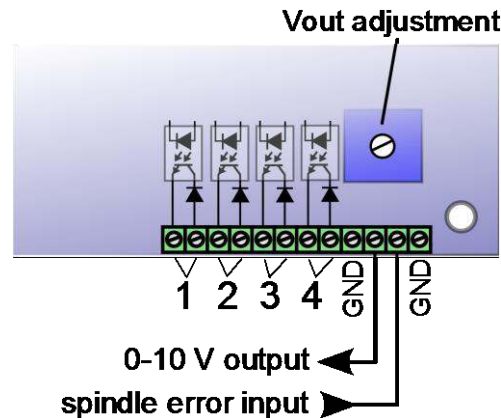
PoKeys Pulse engine v2 documentation

Open-collector outputs

PoKeysCNCaddon board features 4 open-collector outputs with LEDs for signaling the output state.

Rating:

- Maximum applied voltage: 80 V
- Maximum DC current: up to 50 mA



0-10 V voltage output

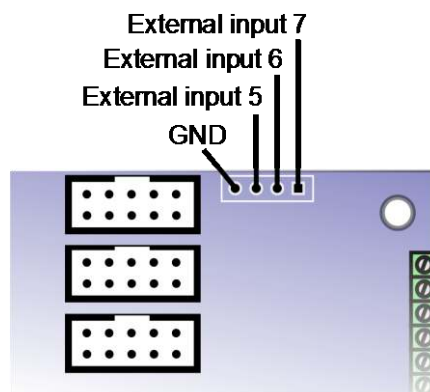
PWM signal is used to create the 0-10 V voltage output. PWM signal with 0% duty cycle produces 0 V on output, while 100% duty cycle produces V_{max} on output. V_{max} can be adjusted using the potentiometer 'Vout'.

In order to convert PWM signal to an analog output, a low-pass filter with the time constant of 1 ms is applied to the source signal. In order to avoid ripples in the analog output, use PWM frequency of 10 kHz or more.

Setup/calibration: either set the duty cycle to 100% or connect the PWM signal input to PoKeysCNCaddon board (pin 3) to +3.3V. Use the multimeter to measure voltage between GND and 0-10 V output. Use the Vout adjustment potentiometer to adjust the voltage to 10 V (

Additional digital inputs

There are 4 additional digital inputs: spindle error input and 3 general purpose external digital inputs, available on the top right corner of the PoKeysCNCaddon board.



Pulse engine limitations:

- Minimum/maximum position:
 - Internal motion controller: -/+ ~16.8 million ticks
 - External (buffered) mode: -/+ ~2100 million ticks

PoKeys Mach3 plugin

Installing plugin

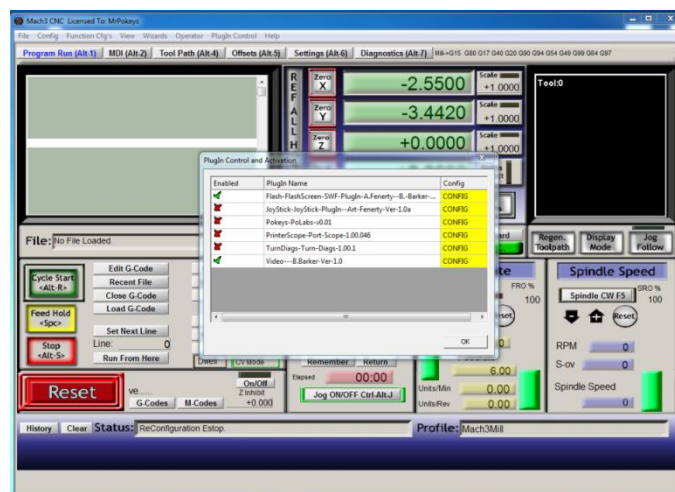
In order to install PoKeys Mach3 plugin, simply copy the Pokeys.dll to the Mach3 plugin folder (by default C:\Mach3\Plugins\). Also, install the latest PoKeys software using the provided setup file.

PoKeys Mach3 plugin existing functionality

- 3-/4-axis CNC machine support
- Support for PoKeys55, PoKeys56U, PoKeys56E and PoKeys57E devices
- Mapping of PoKeys digital inputs to Mach3 OEM LEDs and OEM buttons
- Mapping of Mach3 OEM LEDs to PoKeys digital outputs
- Mapping of PoKeys encoders to Mach3 DROs
- Support for matrix keyboard
- Support for kbd48CNC keyboard on I2C address 1
- Support for PWM outputs
- Support for alphanumeric LCD display
- Support for analog inputs (analog joystick, analog to DRO mapping, offsets and gains adjustment, automatic calibration)
- Support for IO mapping (Mach3 native input-output pins, additional 100 Mach3 IO device pins - device name PoKeys_{serial number})
- Dedicated menu for each device
- Support for pendant with the activation switch
- Usage of PoKeys Pulse engine (available on PoKeys56U and Pokeys56E devices) as external motion controller for Mach3
- Safety charge pump output on pin 53
- External motion controller homing support
- Soft-limits and limit-override support
- Probing support

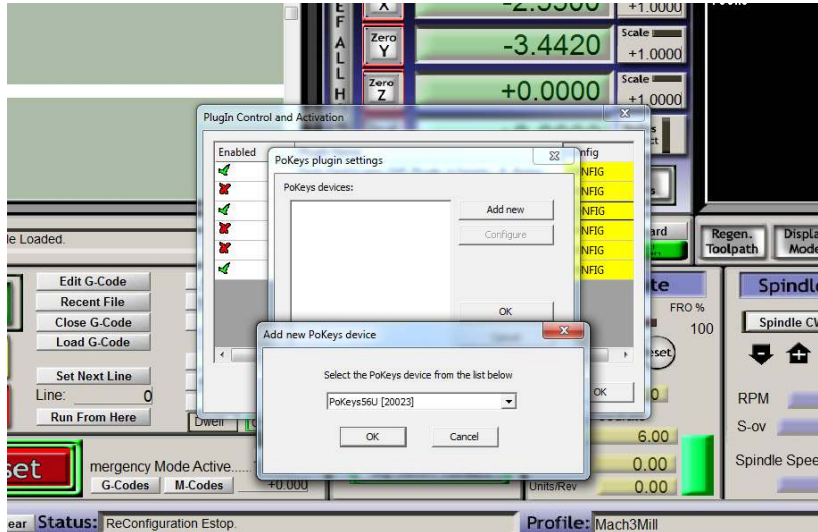
Configuring plugin for the first time

Open Mach3 and go to Config -> Config plugins.. The following dialog will appear.



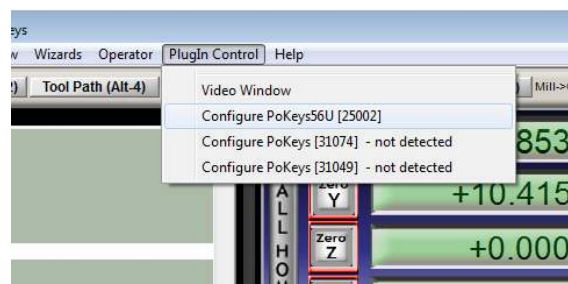
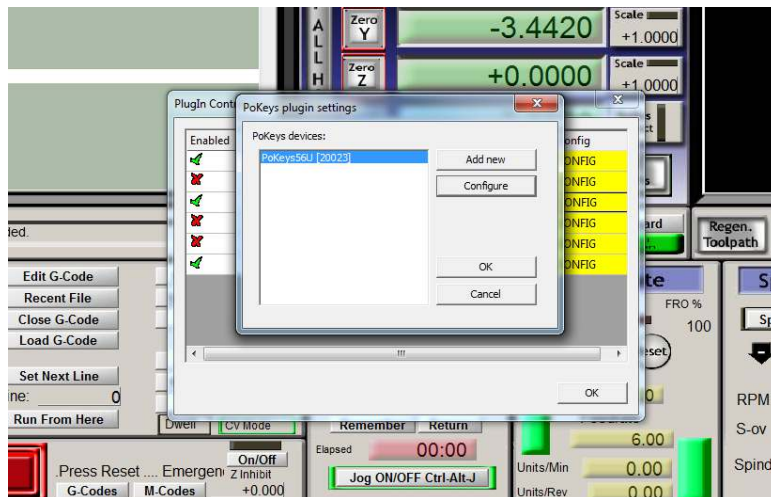
PoKeys Pulse engine v2 documentation

Enable the PoKeys-Polabs plugin and click CONFIG to start configuring the plugin. PoKeys plugin support multiple PoKeys devices (PoKeys55, PoKeys56U and PoKeys56E). To add a new device configuration, click the 'Add new' button and select the PoKeys device (as illustrated in the image below).



After new device configuration is added, **Mach3 MUST BE RESTARTED!**

After restart, the option 'Configure' is enabled. This opens the device configuration dialog where user can configure the device. The same can be achieved using a dedicated device menu entry in the Mach3 Plugin Control menu.



PoKeys Pulse engine v2 documentation

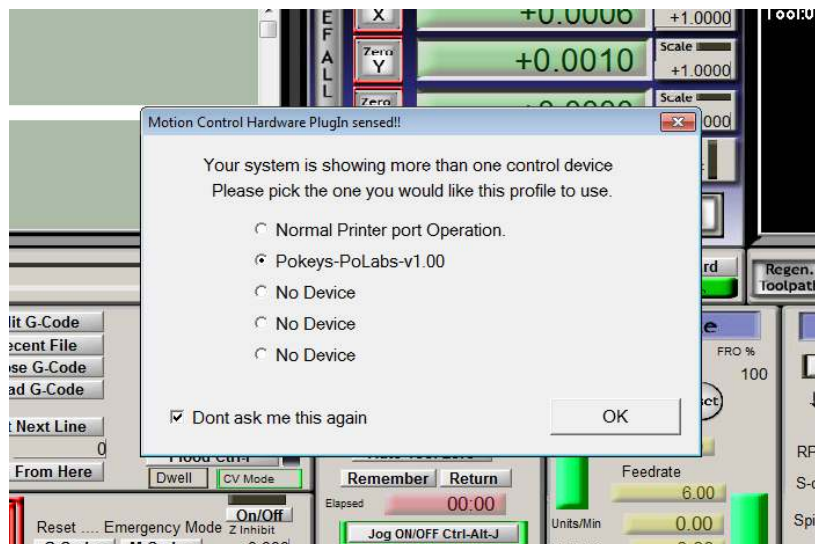
Enabling Pulse engine

In order to use Pulse engine support, go to device configuration, switch to 'Pulse engine' tab and enable one of the following options:

- Integrated 3ch: use the integrated pulse engine support in PoKeys56U and PoKeys56E. This option supports step frequencies up to 25 kHz
- External 4ch without IO: use the pulse engine with conjunction with a simple external pulse engine adapter. This option supports step frequencies up to 125 kHz.
- External 4ch with IO: use the pulse engine with PoKeysCNCaddon external boards. This option supports step frequencies up to 125 kHz.

After selecting one of the options above, click OK and restart Mach3 in order to allow Mach3 recognize an external motion controller.

On the next Mach3 startup, the following dialog will appear, notifying you that the motion control hardware plugin was detected. Select PoKeys-Polabs and click OK.



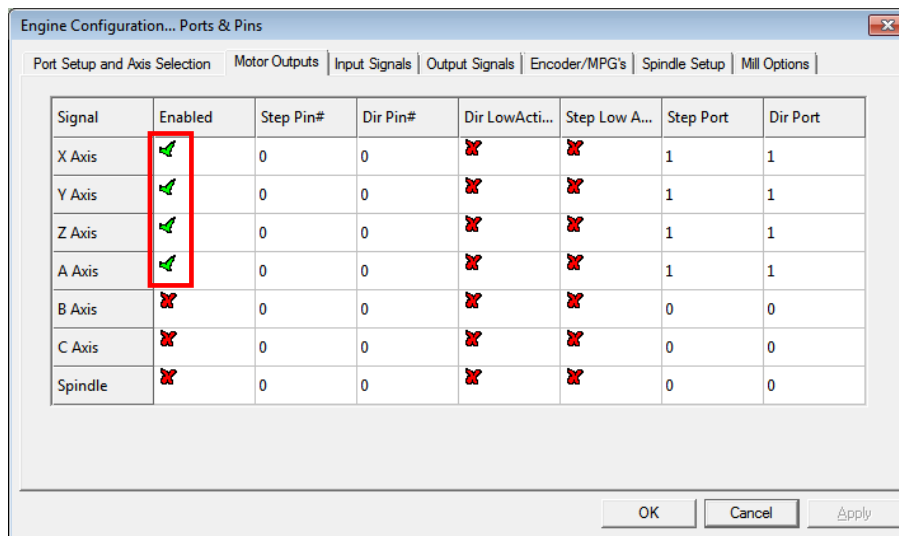
To enable Pulse engine, the emergency switch input must be connected between pin 52 and ground. The switch must be NC (normally closed) type.

At this step, configure the axes as normally through Config -> Motor tuning. See below for details.

PoKeys Pulse engine v2 documentation

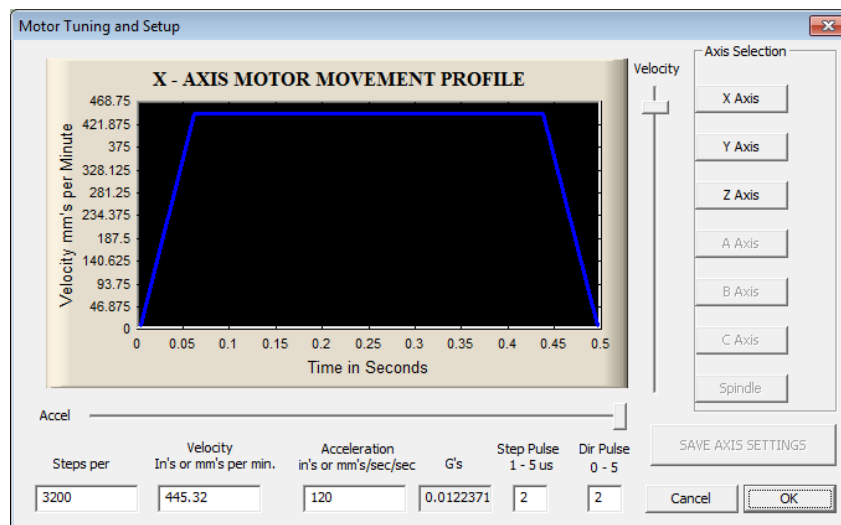
Motors/axis setup

Open Config > Ports & Pins. The following dialog will appear.



Please check that the X, Y and Z axis are enabled (enable A Axis if external pulse generator is used). Other settings are **ignored**.

After enabling the axes, open the Motor tuning dialog (Config > Motor tuning).



Follow the Mach3 motor tuning procedure to setup the appropriate values for 'Steps per', 'Velocity' and 'Acceleration' for each axis. The 'Step pulse' and 'Dir pulse' options are **IGNORED**.

To setup Home/Soft Limits, go to the menu Config > Homing/Limits. In this dialog, software limits and homing speeds can be setup. Use the 'Reversed' and 'Home neg' options to setup the axes directions. Please note that 'Slow Zone' is not supported.

PoKeys Pulse engine v2 documentation

Motor Home/SoftLimits

Entries are in setup units.

| Axis | Reversed | Soft Max | Soft Min | Slow Zone | Home Off. | Home N... | Auto Zero | Speed % |
|------|----------|----------|----------|-----------|-----------|-----------|-----------|---------|
| X | | 120.00 | -100.00 | 1.00 | 0.0000 | | | 50 |
| Y | | 100.00 | -100.00 | 1.00 | 0.0000 | | | 20 |
| Z | | 0.00 | -70.00 | 1.00 | 0.0000 | | | 20 |
| A | | 100.00 | -100.00 | 1.00 | 0.0000 | | | 20 |
| B | | 100.00 | -100.00 | 1.00 | 0.0000 | | | 20 |
| C | | 100.00 | -100.00 | 1.00 | 0.0000 | | | 20 |

G28 home location coordinates

| | | | |
|---|--------------------------------|---|--------------------------------|
| X | <input type="text" value="0"/> | A | <input type="text" value="0"/> |
| Y | <input type="text" value="0"/> | B | <input type="text" value="0"/> |
| Z | <input type="text" value="0"/> | C | <input type="text" value="0"/> |

OK

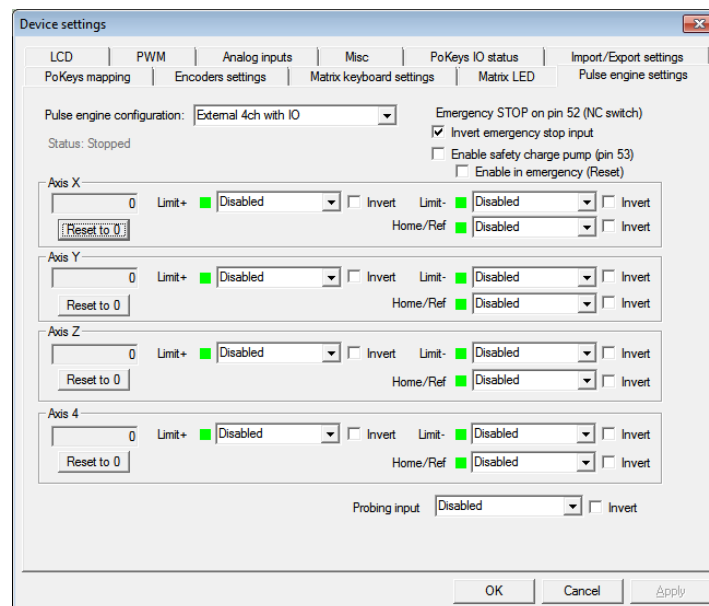
Axis switches configuration

In order to configure the axis switches, open Device configuration (either via Config Plugins or via a dedicated device configuration menu in Plugin Control main menu in Mach3) and switch to Pulse engine settings tab. The following dialog appears.

There is a separate drop-down menu for each available switch. If external pulse engine with IO functionality is selected, external dedicated option can be selected in the menu for each switch or a standard PoKeys digital input pin (the latest is the only option to use when using integrated pulse engine or external pulse engine without IO functionality).

Home/ref switch has some additional options:

- **Shared with Limit-**: Limit- switch functions both as Limit- and as home position switch. During homing, Limit- functionality is temporarily disabled
- **Shared with Limit+**: same as above, but with Limit+ switch



All switches can be inverted - the green/red blocks on the left of the switch selection options display the current switch status, with green indicating a free (non-tripped) switch and red indicating tripped switch. Use the 'Invert' option to switch between the states if necessary.

If limit switches are enabled, PoKeys Pulse engine will enter emergency mode if any limit switch gets triggered.

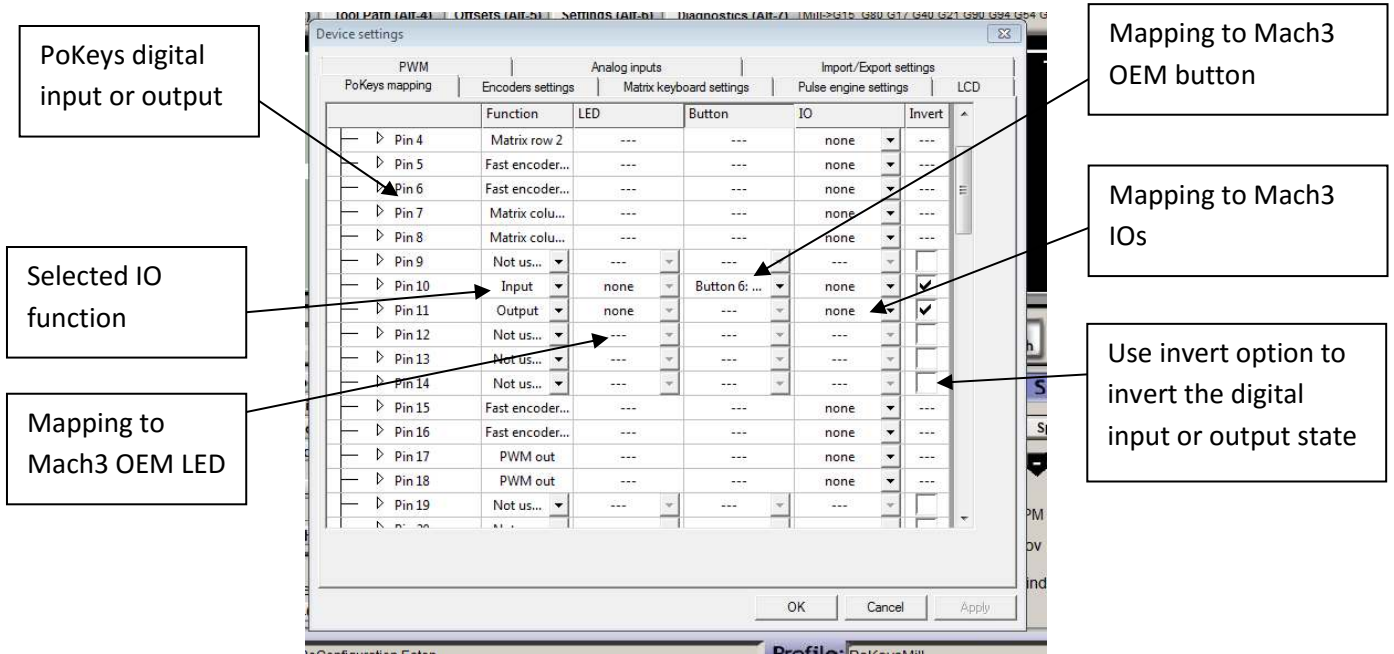
The probing input option is available at the bottom of the dialog and offers mapping the probing input to either external digital inputs or PoKeys digital input pins.

PoKeys Pulse engine v2 documentation

Setting up digital inputs and outputs mapping

To access the digital inputs and output mapping, open the menu PlugIn control > Configure PoKeys {your serial number}.

The following dialog will appear



First column displays a list of all inputs or outputs, available on your PoKeys device. Use the tree structure to navigate between different peripherals and their IO pins.

The second column displays the pin function. If the pin is assigned a special function, a description of this function will be displayed. If multiple special functions are assigned, a red 'Conflict' warning will be displayed.

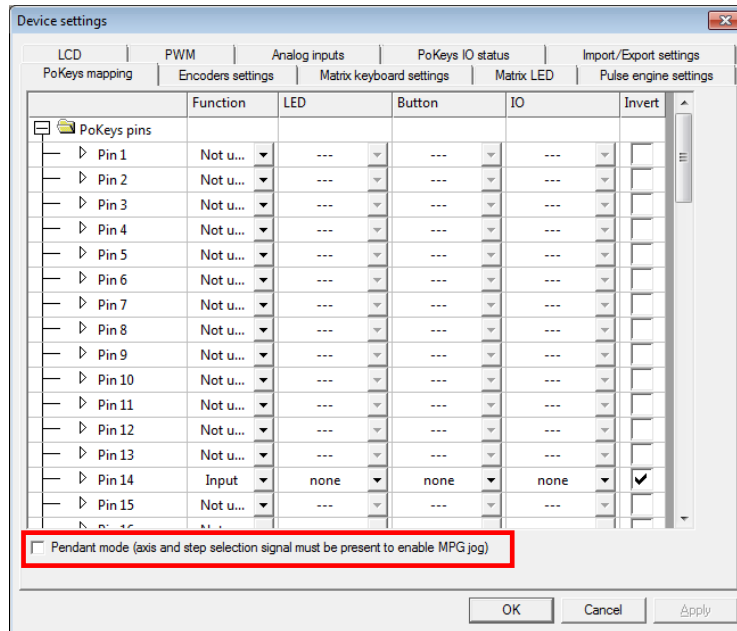
Third column (available for digital inputs and outputs) enables selection of mapping to Mach3 OEM LEDs. If the pin function is set to 'Input', this mapping will enable setting of Mach3 OEM LED state based on PoKeys IO pin state. If the pin function is set to 'Output', Mach3 OEM LED state will be reflected to PoKeys IO pin state.

Fourth column (available only for digital inputs) enables selection of IO mapping to Mach3 OEM buttons. When PoKeys IO pin is triggered, the selected Mach3 OEM button will be triggered also.

Fifth column (available for digital inputs and outputs) enables selection of mapping to/from Mach3 IOs (outputs, such as spindle relay, vacuum, ... used internally by Mach to control different external devices and inputs, such as limit, home switches, ... used internally by Mach to detect the status of the machine) and Mach3 IODevice inputs and outputs (accessible via VBScript).

Pendant mode

Plugin supports the usage of pendant with activation switch. If such pendant is connected to PoKeys, 'Pendant mode' should be enabled (checkbox at the bottom of the 'PoKeys mapping' dialog). In this mode, jog action will be deactivated when the activation switch is released and will be automatically activated when there is a signal detected for both the axis and step selection.



PoKeys Pulse engine v2 documentation

PoPendant configuration

Use the following table to configure PoPendant with Mach3. Activate 'Pendant mode' in Mapping page in order to activate the MPG jogging activation/deactivation using the 'Control switch' on the side of the PoPendant.

The configuration can also be downloaded (see PoPendant homepage) and imported into Mach3 (go to Import/Export tab in plugin configuration and select 'PoKeys pin mapping' and 'Encoder settings and mapping', then click on 'Import' and select the PoPendant configuration file).

Note: the following table only gives an example on how to connect the PoPendant to PoKeys device. To ease the setup process, the configuration file for this example is provided on PoPendant homepage. Wiring can be rearranged by the user, but the plugin configuration must be adjusted accordingly.

If PoKeys Pulse engine is used, 'Let PoKeys handle MPG jogging' must be checked in encoder configuration page.

| Wire | PoPendant "wire colour" | Function | PoKeys pin number | Mach3 Mapping |
|------|-------------------------|-------------|-------------------|---------------|
| 1 | red | MPG +5V | 5V | / |
| 2 | black | MPG GND | GND | / |
| 3 | green | MPG A | 1 | MPG1 B |
| 4 | white | MPG B | 2 | MPG1 A |
| 3* | purple | N.C. | N.C. | / |
| 4* | purple/black | N.C. | N.C. | / |
| 5 | green/black | Lamp + | +3.3V | / |
| 6 | white/black | Lamp - | 14 | DO LED 57 |
| 7 | yellow | X axis | 19 | Button 185 |
| 8 | yellow/black | Y axis | 20 | Button 186 |
| 9 | brown | Z axis | 21 | Button 187 |
| 10 | brown/black | A axis | 22 | Button 188 |
| 9* | pink* | B axis | 24 | Button 189 |
| 10* | pink/black* | C axis | 27 | Button 190 |
| 11 | gray | x1 | 3 | Button 191 |
| 12 | gray/black | x10 | 4 | Button 192 |
| 13 | orange | x100 | 7 | Button 193 |
| 14 | orange/black | Ctrl Switch | GND | / |
| 15 | Light blue | Estop | 52 | IO Estop** |
| 16 | blue/black | Estop GND | GND | / |
| 17 | red/black | N.C. | N.C. | / |
| | shield | shield | GND | / |

* Not available on all units

** Don't configure Estop mapping if pulse engine is enabled

N.C.= not connected

DO = digital output

DI = digital input

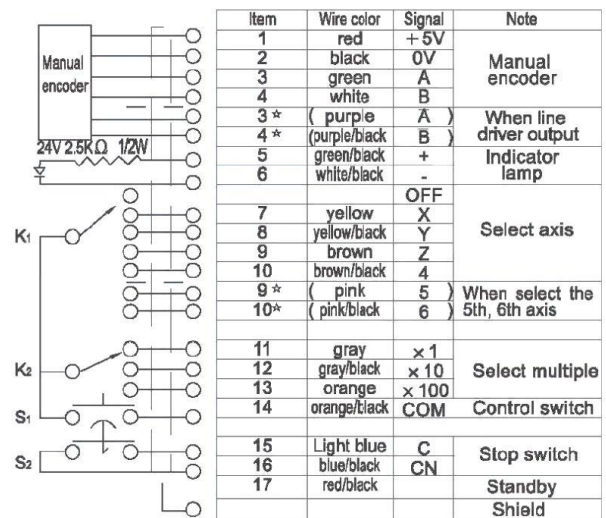
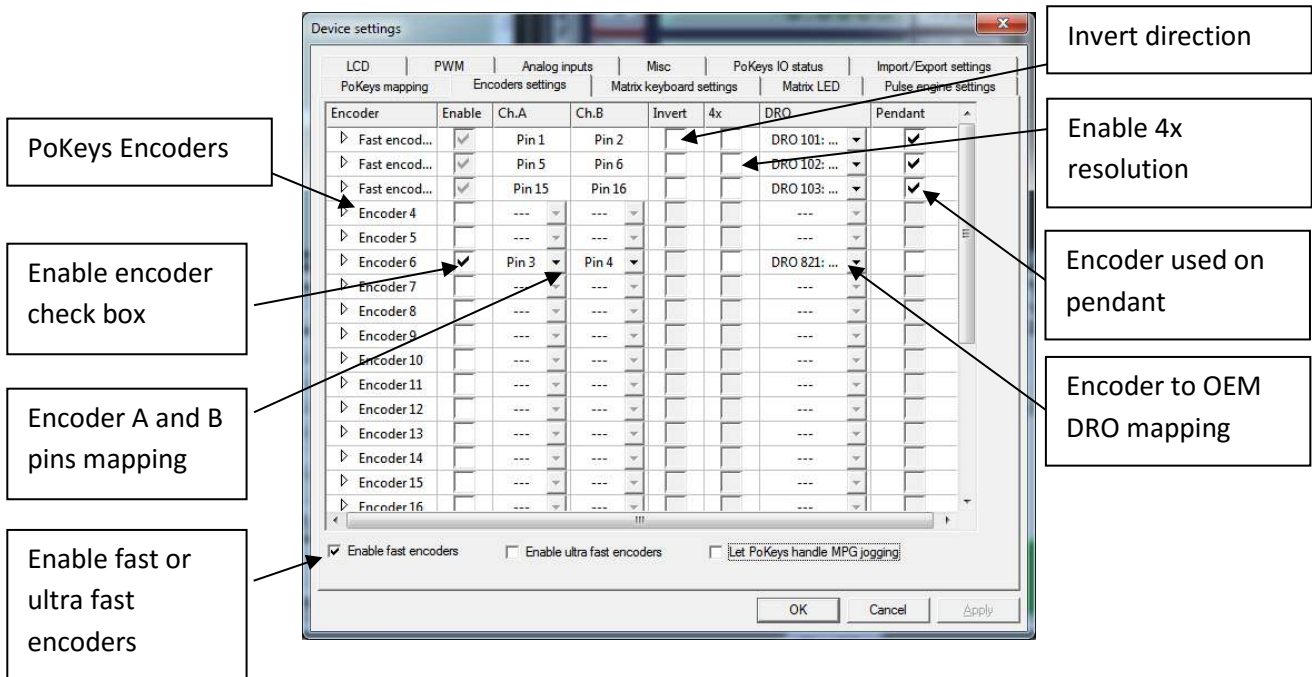


Figure 3: PoPendant internal wiring

Encoder (MPG) settings



The encoder page lists all supported encoders with their current settings. Fast encoders (replacing encoders 1-3) can be enabled by selecting the 'Enable fast encoders' option in the bottom part of the dialog. Ultra fast encoders (available on PoKeys56 devices) appear as encoder 26 and can also be enabled using the check box at the bottom of the window.

For other ('normal') encoders channel A and B signals must be setup. Select the appropriate PoKeys pin in each list. The selected pin will be automatically set as digital input.

To invert the encoder direction (instead of switching A and B signal connections physically) use the 'Invert' option. The check box in the sixth column enables 4x greater encoder resolution. The second to last column enables selection of encoder to Mach3 OEM DRO mapping.

The option in the last column 'Pendant' tells PoKeys plugin which encoder is used as MPG on the pendant. In case the 'Pendant mode' is enabled and there is an invalid signal from connected pendant, changes of encoders marked with 'Pendant' will have no effect on Mach3 or motion.

MPG (manual pulse generator) setup

PoKeys plugin ties itself directly into Mach3 core and does not represent a device a an LPT port-based extension. **Therefore Mach3's Ports and Pins configuration should not be used to setup the MPGs. If you configure MPG in Mach3's Ports and Pins dialog, these MPGs won't work with PoKeys.**

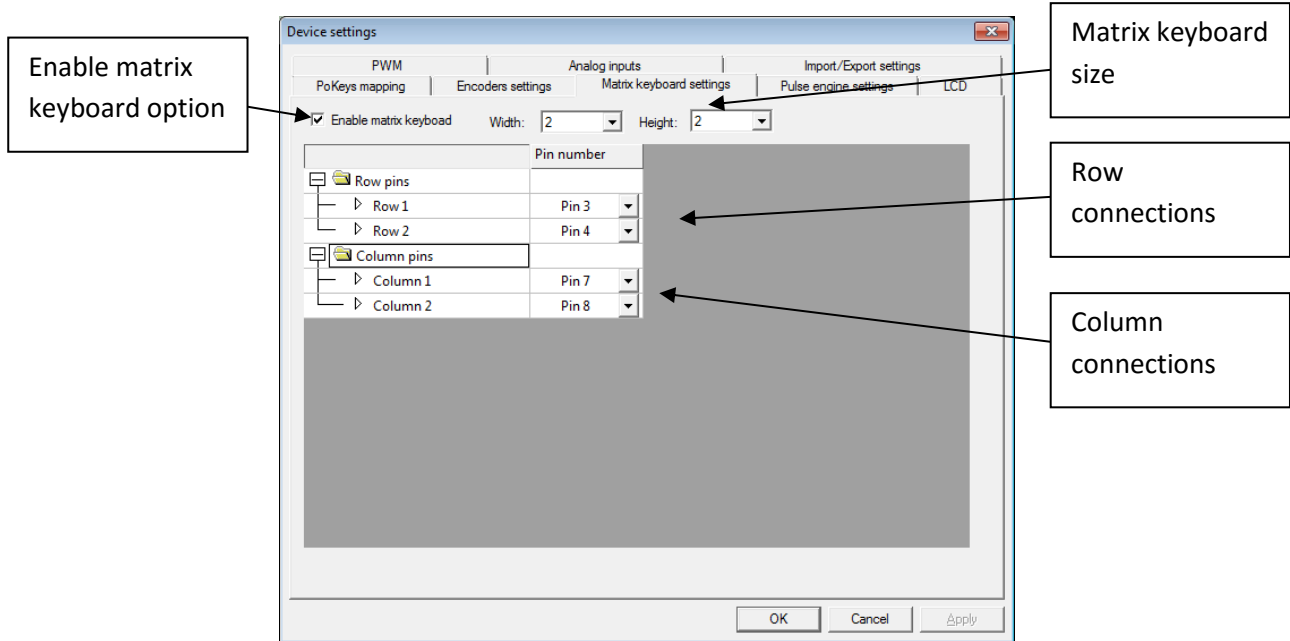
In order to setup MPG, follow the instructions above for an encoder, but select 'DRO 101 (MPG1)' (for MPG1), 'DRO 102' (for MPG2) or 'DRO 103' (for MPG3) in DRO field for that encoder. Also note, that the corresponding MPG must be only enabled in Mach3's Ports and pins under MPG tab.

If PoKeys Pulse engine is used, 'Let PoKeys handle MPG jogging' must be checked.

Matrix keyboard setup

The matrix keyboard setup gives the options to activate matrix keyboard, select its width and height and assign PoKeys pins to matrix keyboard row and column connections.

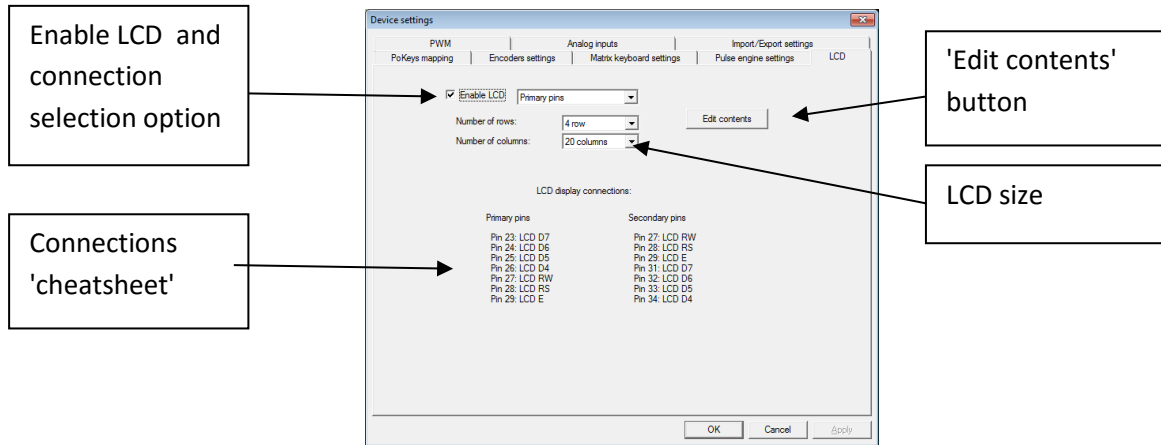
The selected pins are automatically setup as digital inputs and outputs.



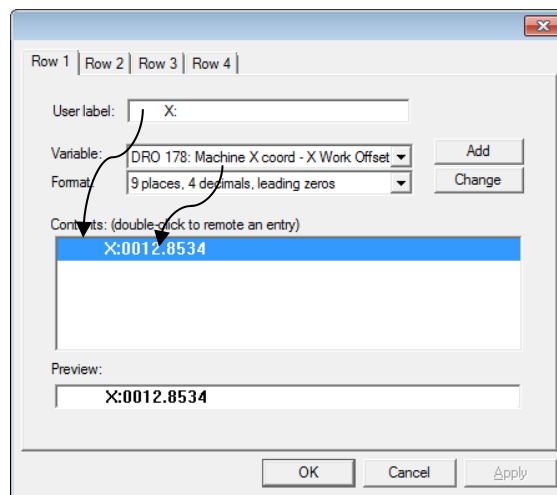
To setup mapping of matrix keyboard keys to OEM LEDs and buttons, go back to 'PoKeys mapping' tab and select appropriate functions for the matrix keyboard entries in the list of available IOs.

LCD setup

The LCD configuration dialog can be used to enable LCD, select connection option (primary or secondary pins, as defined in the PoKeys manual), select LCD size and edit contents of the LCD.



To edit the LCD contents, setup the LCD first, then click on 'Edit contents' button. The following dialog will appear



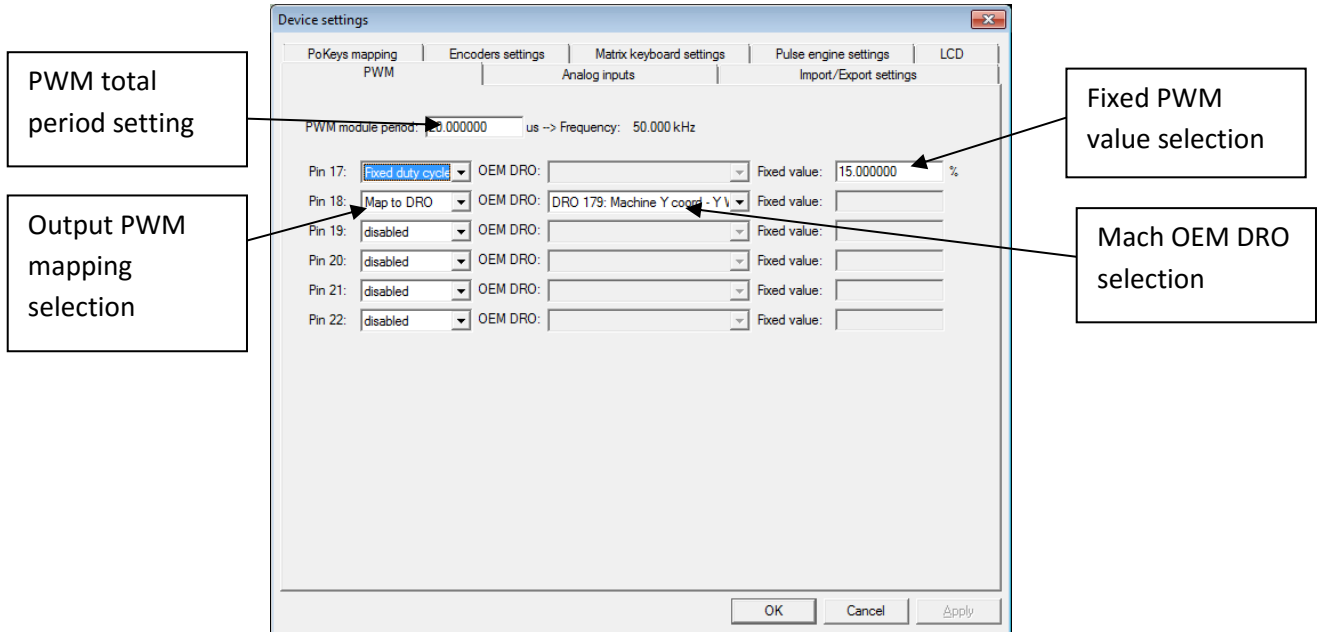
The dialog holds as many tabs as there are configured LCD lines in the previous step. The 'Row 1' dialog is used to setup only the line 1 of the LCD display ('Row 2', ... are used to setup the other lines of the display).

Each row can hold multiple entries – either label only, either holding a numeric display of one of the available variables. To add a new entry, enter the 'User label' (optional), select a variable you would like to display and its display format. Then click 'Add' button. The contents list will be updated with the new entry. To remove the entry, double-click on it. Although entries are displayed in the list in the vertical manner, they are combined on the LCD horizontally as is displayed in the 'Preview' field at the bottom.

PoKeys Pulse engine v2 documentation

PWM (Pulse-width modulated) outputs

PoKeys devices support up to 6 pulse-width modulated digital outputs. All outputs share the same PWM total period (specified in microseconds) and have separately configurable duty cycles. Duty cycles can be specified either in 0-100% or as raw PWM duty cycle period in microseconds.



Each PWM output can be deactivated, mapped to Mach3 OEM DRO (PWM period in microseconds or in %) or assigned a fixed value (PWM period in microseconds or in %).

Analog inputs

Available analog inputs on the PoKeys device (pins 43-47 on PoKeys55 and pins 41-47 on PoKeys56) can be either mapped to Mach3 OEM DRO register or used as an analog joystick axis, used for jogging.

Analog inputs are displayed as 12-bit value (10-bit analog values on PoKeys55 devices are up-scaled to 12-bit) and can be configured with user specific offset and gain value using the following formula:

$$u_{corrected} = \frac{u_{AD} - u_{offset}}{4096} * u_{gain}$$

where $u_{corrected}$ is the corrected value of analog to digital readout u_{AD} using the offset u_{offset} and gain u_{gain} . The offset and gain values can be adjusted for each analog input separately. Mapping to DRO or analog joystick is done using the corrected value $u_{corrected}$.

| Analog input | Current value | Offset | Gain | Corrected value | Analog joystick | DRO |
|------------------|----------------|--------|-------|-----------------|-----------------|------|
| Analog input 41: | 1979 (1.594 V) | 1983 | 2.000 | -0.002 | Not used | none |
| Analog input 42: | 1996 (1.608 V) | 1996 | 2.000 | 0.000 | Axis Y | none |
| Analog input 43: | 0 (0.000 V) | 0 | 0.000 | 0.000 | Not used | none |
| Analog input 44: | 1961 (1.580 V) | 0 | 0.000 | 0.000 | Not used | none |
| Analog input 45: | 0 (0.000 V) | 0 | 0.000 | 0.000 | Not used | none |
| Analog input 46: | 2358 (1.900 V) | 0 | 0.000 | 0.000 | Not used | none |
| Analog input 47: | 0 (0.000 V) | 0 | 0.000 | 0.000 | Not used | none |

Analog joystick functionality enables convenient jogging option. Based on the analog voltage, present on the selected pin, the selected axis can be jogged progressively. To enable analog joystick, assign the axes in the 'Analog joystick' column and click 'Calibrate' button at the bottom of the dialog. A simple wizard will walk you through the process and enable you to calibrate (automatically set the gain and offset values) based on your input. After the successful calibration, enable analog joystick functionality by checking the box 'Enable analog joystick'.

To disable unwanted jogging in zero position, adjust the parameter 'Deadband' based on the noise of your analog input (enter value in analog value ticks – 0 to 2048). If the $|u_{AD} - u_{offset}| < u_{deadband}$ the axis will not be jogged.

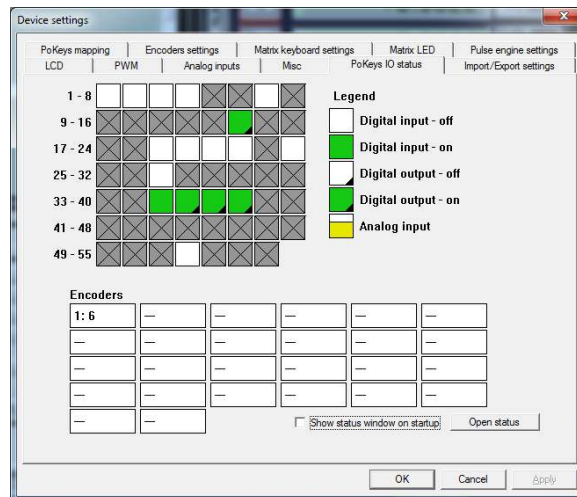
If 'Use OEM LED 1911 to enable the joystick' option is checked, analog joystick can be enabled and disabled using the OEM LED 1911 signal.

PoKeys Pulse engine v2 documentation

PoKeys IO status

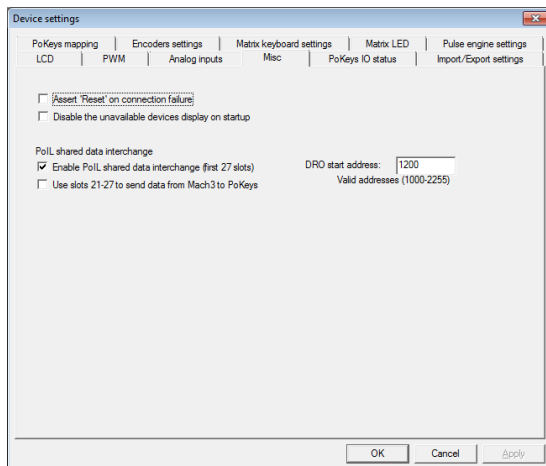
This tab gives the user an overview of the PoKeys inputs and outputs. PoKeys pins are represented as a grid of colored squares, each resembling a single PoKeys pin and encoder values are listed at the bottom of the dialog.

By clicking the 'Open status', a floating dialog is displayed, giving the user an overview of PoKeys inputs and outputs, encoder values and PoKeys Pulse engine states even when configuration dialog is closed.



Other (miscellaneous) settings

Misc tab contains additional miscellaneous settings.



Assert 'Reset' on connection failure: if checked, Mach3 will be but into 'Reset' mode when the connection with the PoKeys device is dropped.

Disable the unavailable devices display on startup: if checked, PoKeys plugin won't display the 'Unavailable devices' window on Mach3 startup if the current device is not available

PoKeys Pulse engine v2 documentation

PoIL shared data interchange

This option enables interchange between PoIL shared slots (see PoBlocks manual) and Mach3 DRO registers. Once enabled, first 27 shared data slots are copied from PoKeys PoIL core to Mach3 DROs, starting by the Mach3 DRO number, specified in the field on the right (values between 1000 and 2255 are valid).

If 'Use slots 21-27 to send data from Mach3 to PoKeys' option is enabled, slots 21 to 27 are read from specified Mach3 DRO registers and sent to PoKeys PoIL core.

Custom operations can be performed on data from various PoKeys peripherals and result forwarded to Mach3 (e.g. spindle speed calculation, product counting, PID control with reference set by Mach3, ...).

Reading and writing of IO from VB script

PoKeys Mach3 plugin exposes each PoKeys device (named PoKeys_{serial}, where serial is the serial number of the PoKeys device) as 100 virtual IO pins that can be accessed from Mach3 VB script with the following functions:

GetIODeviceName(DevID As Short) Return String

DevID - Device ID's start at zero and go up.

Return - Returns the name of the Device as a String. If the device ID is out of range the return will be "NoDevice"

GetIODeviceInput(DevID As Short , IONumber As Short) Return Double

DevID - Device ID's start at zero and go up.

IONumber - The number of the IO Starting at zero (Pin number -1)

Return - Returns the value of an input OR the value that an output is set to . If the device is not found a return of 999 will be sent back.

SetIODeviceOutput(DevID As Short , IONumber As Short, Value As Double)

Return Short

DevID - Device ID's start at zero and go up.

IONumber - The number of the IO Starting at zero (Pin number -1)

Value - Any value to set the output to. for digital outputs 0 and 1 are used as on and off

PoKeys Pulse engine v2 documentation

Return - Return of 0 if there are no faults, 1 is returned if the pin is not found, 2 is returned if the pin is an output pin.

Example script (finds the PoKeys device with the serial number 25000, then toggles the IO 1 on and off at a rate of 1 Hz):

```
Sub Main()
DevName = "PoKeys_25000"
Outputnumber = 1

DevID = -1

Do
DevID = DevID+1
SearchName = GetIODevName(DevID)'Search for the Device
If(SearchName = "NoDevice") Then
  MsgBox ("Error Finding Device")
  Exit Sub
End If
Loop While (DevName <> SearchName)

For d=0 To 60'Loop 60 times to toggle the output on and off for one min
  r = SetIODevOutput(DevID,Outputnumber,1)'Activate the output
  If(r<>0) Then
    MsgBox("Output#" & Outputnumber & " " & GetIODevIOName(DevID,Outputnumber) & " is Not
an
output" )
    Exit Sub
  End If
  Sleep(500) 'Wait .5 sec
  SetIODevOutput(DevID,Outputnumber,0)'Turn the output off
  Sleep(500)'Wait .5 sec

Next d

End Sub

Main
```

Additional OEM buttons

| OEM button | Function |
|------------|-------------------------|
| 1900 | Plugin Jog Toggle |
| 1901 | Plugin Jog + |
| 1902 | Plugin Jog - |
| 1903 | Plugin Rapid Jog Toggle |
| 1904 | Plugin Goto 0's |
| 1910 | Plugin Spindle CW |
| 1911 | Plugin Spindle Stop |
| 1912 | Plugin Spindle CCW |

Additional OEM LEDs

| OEM LED | Function |
|---------|---------------------------------------|
| 1900 | Plugin Jog X axis LED |
| 1901 | Plugin Jog Y axis LED |
| 1902 | Plugin Jog Z axis LED |
| 1903 | Plugin Jog A axis LED |
| 1904 | Plugin Jog B axis LED |
| 1905 | Plugin Jog C axis LED |
| 1906 | Plugin Jog Select 0.001 increment LED |
| 1907 | Plugin Jog Select 0.01 increment LED |
| 1908 | Plugin Jog Select 0.1 increment LED |
| 1909 | Plugin Jog Select 1 increment LED |

Pulse engine v2 operating principles

PoKeys Pulse engine v2 (upgrade of the original PoKeys Pulse engine) is available on PoKeys56U and PoKeys56E devices and enables a direct control of a positioning systems that accepts step/direction signals (stepper motors, servo systems, etc.).

PoKeys Pulse engine divides the operations into 1 millisecond time slots, during which the pulse frequency is held constant, and supports the generation of up to 25 pulses per 1 millisecond time slot using integrated pulse generator or up to 125 pulses per 1 millisecond time slot using external pulse generator circuit (which equates to 25/125 kHz maximum pulse frequency supported).

At each time slot beginning, the selected limit and home switches are read and evaluated. If emergency switch or any activated limit switch (enabled in the configuration) is tripped, the pulse engine is put into Error mode and no more pulses are generated (with hard-stop mechanism). Limit switches can be disabled using the 'Limit override' function. In addition, PoKeys pulse engine also supports 'Soft-limit' function, which limits the machine motion using the virtual limit switches.

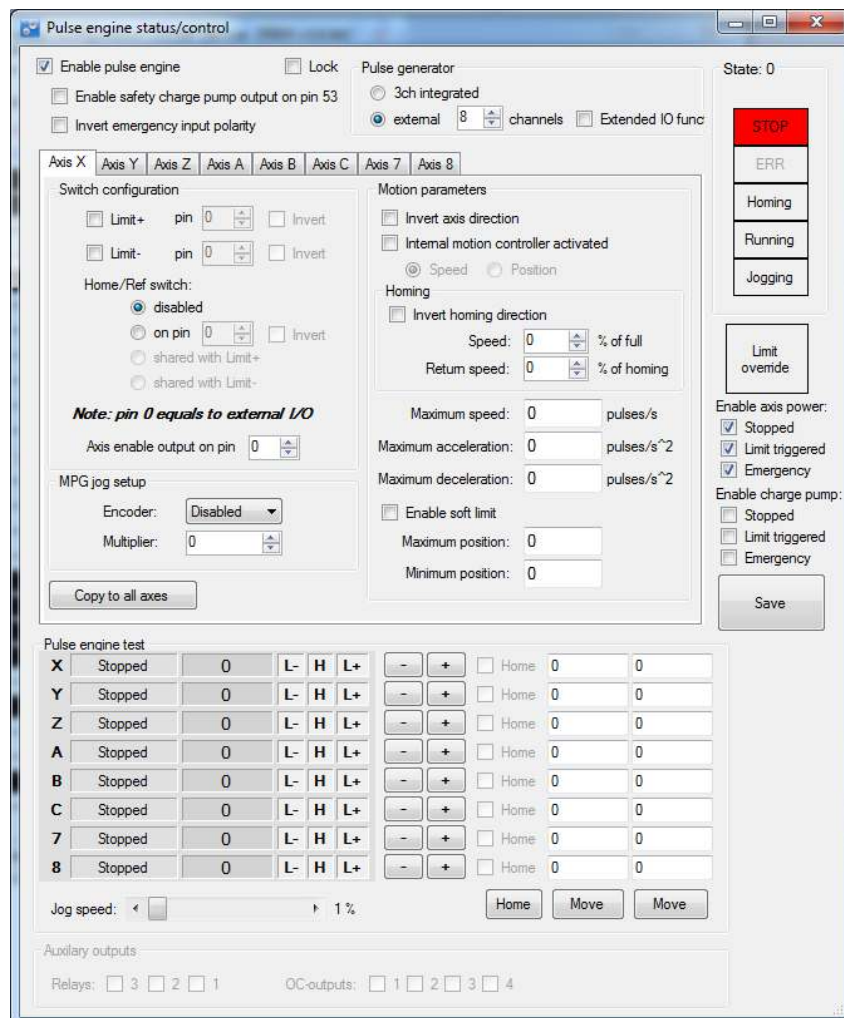


Figure 4: Pulse engine configuration window in PoKeys configuration software

PoKeys Pulse engine operates in different modes with additional modes selectable per each axis.

Modes of operation

- **Stopped:** the pulse engine does not generate any pulses.
- **Error:** the pulse engine encountered an error (e.g. limit switch was activated).
- **Homing:** homing mode is activated. In this mode, one or more axes can be homed. The selected axis (or axes) moves in negative direction at predefined fraction of the maximum speed until the home switch is tripped. Then, the direction is changed to positive and speed decreased to half the previous speed. When the switch is tripped, the internal position counter is reset and the axis is commanded to stop. This operation does not include moving back to position 0. The state of homing procedure is reflected in axes states.
- **Probing:** during probing, selected axes are actuated by PoKeys device until a probe signal has changed to a predefined state. The position of the axes is saved and the motion is stopped.
- **(MPG) Jogging:** if axis has an MPG assigned, the MPG jog is done by PoKeys device itself using the MPG multiplier value.
- **Running:** normal operation mode. In this mode, each axis can be put into either the 'buffer' mode (the internal controller is disabled and the slots are fed directly from a slot buffer, which must be constantly filled by the external application) or into the 'internal controller mode':
 - internal position control: moves the axis to the desired position, following the limitations set by the axis parameters,
 - internal speed control: moves the axis at the desired speed, following the limitations set by the axis parameters.

Internal controller modes and buffer mode utilize separate internal buffers for operation. Hence, changing between internal or external (buffered) mode does not require clearing the motion buffers. Moreover, internal controller can be used on selected axes in parallel to the external (buffered) mode on other axes (new to Pulse engine v2).

In buffer (slave) mode, the generated motion is transferred and temporarily stored in the timeslot buffer - a 128-slots deep buffer that holds pulse frequencies for each axis, giving a 128 millisecond buffered motion period. Each slot entry in the buffer holds 16 bytes (2 byte per axis) and each axis entry uses 15-bits for pulse frequency and MSB bit for the direction signal (if MSB bit is set, the direction output is activated). Although buffer holds 16 bytes per time slot, only [number of activated axes] bytes are transferred for each slot using default 'Fill motion buffer' command.

Fill buffer command is used to transfer the data to the slot buffer. Application that uses the fill buffer command should send as much time slot data as possible. PoKeys Pulse engine will then return the number of accepted time slots. This omits the need of additional query on the buffer free space in PoKeys Pulse engine buffer. Application should only then increase the 'read pointer' based on the number of accepted slots. Additionally, fill buffer command returns a number of parameters of the pulse engine (position, engine state, state of limit and home switches and states of each axis).

In Mach3 plugin, PoKeys Pulse engine operates in buffer (slave) mode during job execution and executes the motion, generated by Mach3 motion planner. During jogging, MPG jogging, homing, probing operations, the selected axis is switched to internal motion controller, enabling real-time

PoKeys Pulse engine v2 documentation

responses and high accuracy of positioning. MPG jogging uses encoder (MPG) values directly to feed the internal motion controller with the up-to-date information on MPG position. This results in fast responses of the machine to the MPG input.

Safety charge-pump output

When activated, 5 kHz square safety charge-pump signal is present on pin 53 if the Pulse engine is in normal operating mode. The safety charge-pump in other operating mode can be enabled by the user by selecting the 'Enable charge-pump' check boxes.

In Mach3 plugin, the user can select whether charge pump output is active during emergency.

Motor driver enable outputs

Motor driver enable outputs are available only with conjunction with PoKeysCNCaddon. User can select modes in which the motor drivers are enabled by selecting the 'Enable axis power' check boxes.

In Mach3 plugin, the motor driver enable outputs settings are joined with safety charge-pump settings.

Axis parameters

Internal mode uses the following axis parameters of motion:

- Maximum speed: maximum frequency of pulses (in pulses/s)
- Acceleration: maximum acceleration (in pulses/s²)
- Deceleration: maximum deceleration (in pulses/s²)
- Limit and home switches configuration
- Direction change configuration: direction can be changed separately for each of the axes
- Homing direction configuration: direction of homing can be changed separately for each of the axes

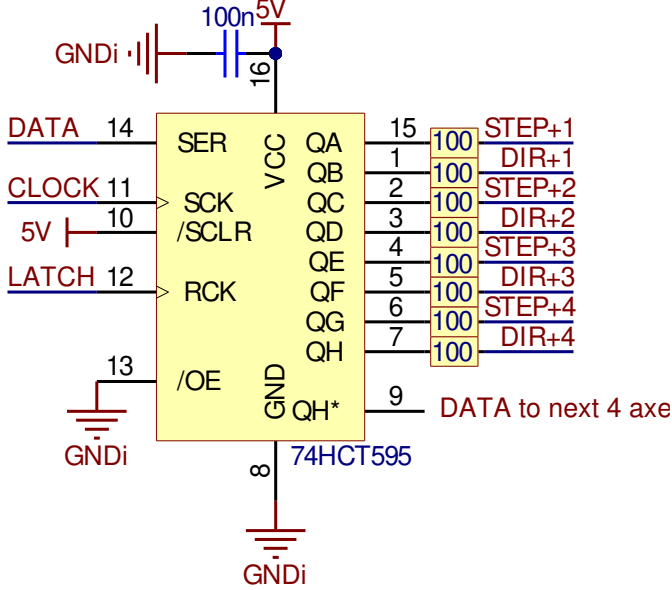
Custom external pulse generator without IO functionality

External pulse generator is a simple circuit for deserializing step and direction data, coming from PoKeys device. The circuit uses 74HCT595 IC that is connected to PoKeys board as shown in the table below.

Two 74HCT595 can be cascaded in order to support 8 axes, but single one can be used for up to 4 axes. When cascading, CLOCK and LATCH signals are shared between both ICs, while DATA out (pin 9) of the first IC is used as DATA signal of the second IC.

| Pin | Description | PoKeys56U | PoKeys56E/57E |
|-------|-----------------------------|-----------|---------------|
| | | pin | pin |
| 5V | 5 V power supply | 5 V | 5 V |
| GND | PoKeys ground | GND | GND |
| DATA | Signal for pulse generation | 23 | 9 |
| CLOCK | Signal for pulse generation | 25 | 11 |
| LATCH | Signal for pulse generation | 26 | 51 |

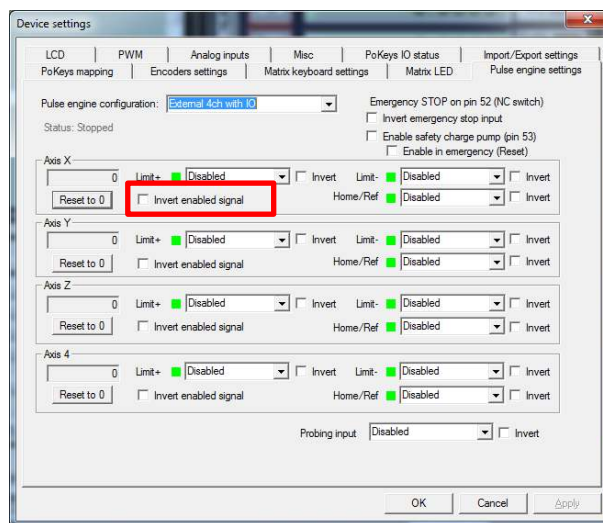
PoKeys Pulse engine v2 documentation



Frequently asked questions

Whenever Mach “reset” is blinking the stepper motor power is engaged, and you cannot turn the motor shaft with your fingers. When “reset” is released, the motors loose power.

There is an option 'Invert enabled signal' in the 'Pulse engine' tab of the PoKeys Mach3 plugin. There are two types of stepper drivers - ones expect active low signal for enabling the outputs, the others expect active high signal. Since PoKeys is not a LPT port extension, the Mach3's Ports & Pins is not functional and all configuration is done via PoKeys plugin configuration dialogs.



I really do not know how to set up the spindle control. Normally I would use for example the S60 (for spindle speed of 60 to produce an analog output to control the spindle). I do not know how to tell the pokeys CNC addon board how to pick up this S command.

This is achieved using the PWM output of the PoKeys board, connected to the pin 3 of the PoKeysCNCaddon board connection. Go to PoKeys Mach3 plugin configuration, tab 'PWM', select 'Map to DRO in %' and select DRO202. Then set the appropriate multiplier that the DRO value is multiplied with before sending it to the output (the output goes from 0 to 100 %, so in case you have values between 0 and 500 in this DRO, set the multiplier to 0.2). If you want to lower the output range, lower the multiplier value (digitally scale the output voltage instead of using the pot).

Similarly, spindle relay outputs can be configured in the 'PoKeys mapping' tab for one of the pins (for example, configuring one pin as Digital output and mapping it to LED 11 (Spindle ON LED)).

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